



Automobiles and  
Light Commercial Vehicles



# Optimization and Robust Design with modeFRONTIER

Application in automotive Industry

FIAT GROUP AUTOMOBILES – CHASSIS & VEHICLE DYNAMICS



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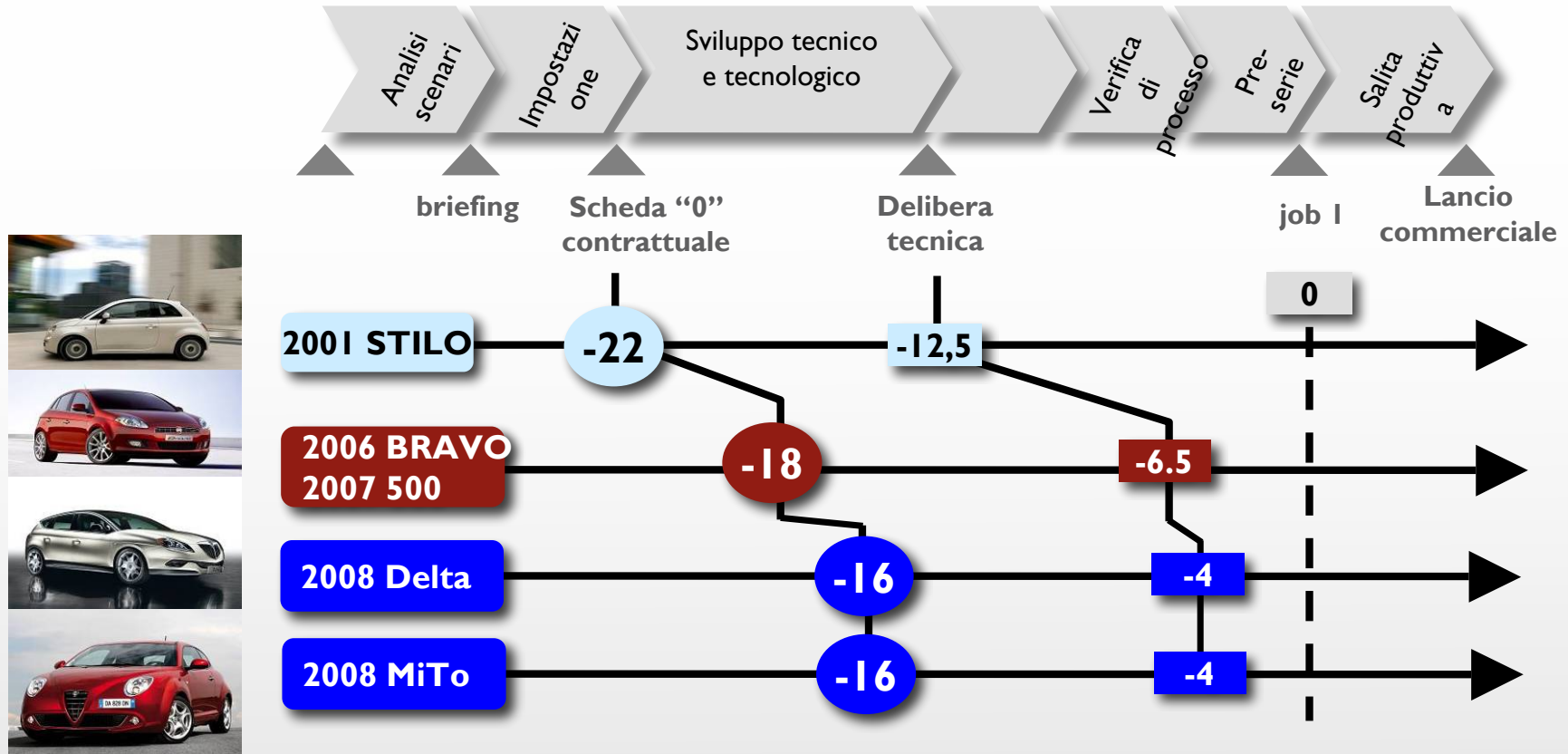
- ✓ **Introduction : Scenario & Targets**
- ✓ **Examples of DOE, ROBUST DESIGN and OPTIMIZATION in Chassis & Vehicle Dynamics**
- ✓ **Summary & Conclusion**

# Scenario

# Automotive industry competition



## Fiat Group Automobiles is a reference for product development time



**+ Quality**  
**+ Innovation**

Key success factor :  
**Virtual Analysis**

**- Costs**  
**- Time to market**

## Virtual Analysis in chassis & vehicle dynamics



- ✓ **Vehicle** : Handling & ride comfort performances must be take in account at the same time and reach the Vehicle Technical Specification coming from targetsetting of Customer Car Profile
- ✓ **Subsystems** : Performances contribution at Subsystems level must be also take in account (PTmounts & Suspension System)



- ✓ To improve **QUALITY** and reduce **TIME** a better approach could be used from the beginning in virtual analysis of vehicle dynamics :

### **DOE – OPTIMIZATION – ROBUST DESIGN**

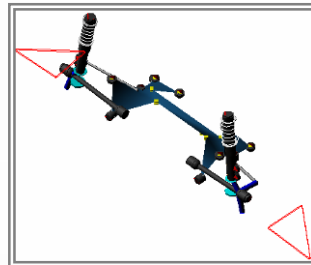
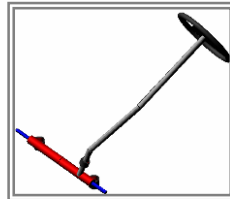
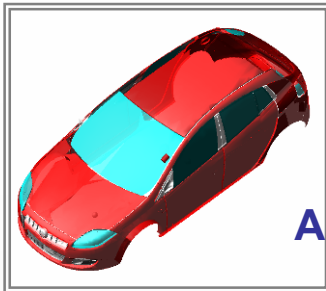
- ✓ Very high potential of that approach for handling & ride comfort analisys based on integration of :

### ***MULTIBODY SIMULATION + OPTIMIZATION TOOLS***

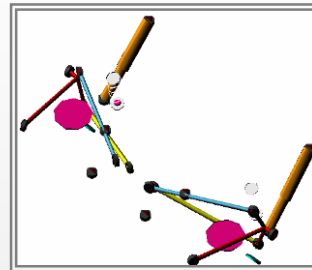
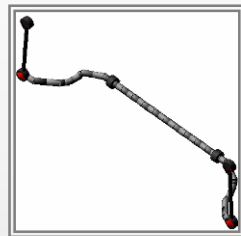
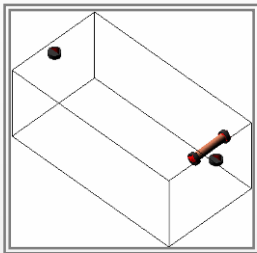
# Multibody : FIAT Customization of MSC.ADAMS/Car



## Multi-body Models



Assembling vehicle subsystems



## Subsystems

- Front Suspension
- Rear Suspension
- Steering system
- Brakes system
- Conceptual Driveline
- Anti-roll bar
- Engine
- Tires
- Body

## Assemblies/ Testrig

- Full-vehicle Handling
- Full-vehicle Comfort
- Suspension K&C
- Suspension NVH
- Suspension fatigue
- Engine
- ...

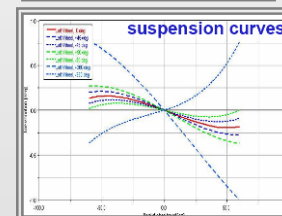
## Analysis:

- K&C SUSPENSION
- HANDLING (+driver controls)
- RIDE COMFORT
- FATIGUE TEST
- DRIVEABILITY

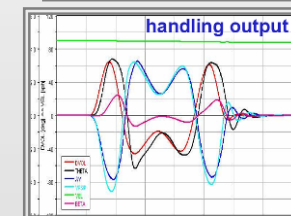
## Post-processing:

- Automatic plotting of graphs
- Calculation of single maneuver synthesis parameters
- Calculation of Handling/Comfort/Steering/Braking Subjective Quality Indexes

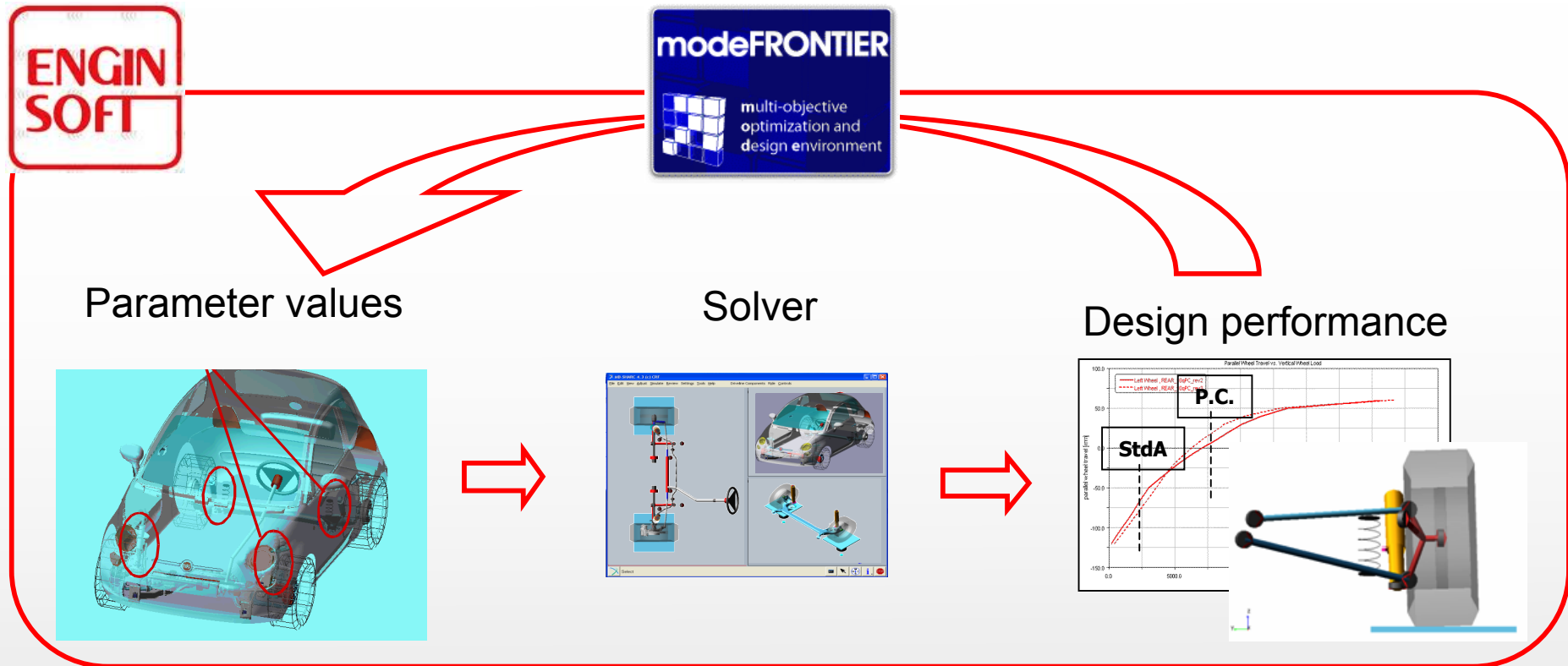
Suspension analysis



Handling maneuvers



# Multiobjective Optimization tool : ModeFrontier



- **Process Integration:** integrates any CAE software
- **Design Automation:** automates design process
- **Design Optimization:** algorithms drive design to optimum

# Multiobjective optimization & robust design : Adams/Car linked with modeFrontier



## modeFRONTIER

**Input variables**

**Model modifications**

**Results simulation**

**Output and comparison objectives and constraints**

Name	Variable Type	Constant	Expression	Dis
15 Use0_P13_X	Variable	0.000E0		0.00
16 Geo_P13_Z	Variable	0.000E0		0.00
17 Geo_P14_Z	Variable	0.000E0		0.00
18 Geo_P14_X	Variable	0.000E0		0.00
19 Geo_P14_Y	Variable	0.000E0		0.00
20 Kmolla	Variable	0.000E0		1.000E0
21 Bumpstop	Variable	0.000E0		1.000E0

## MSC.ADAMS/Car

# Input Variables, Objectives and Constraints



## Input variables:

### Suspension Vertical Stiffness and Damping

(spring, shock absorber)

### Suspension Longitudinal Stiffness and Damping

(bushings, shock absorber)

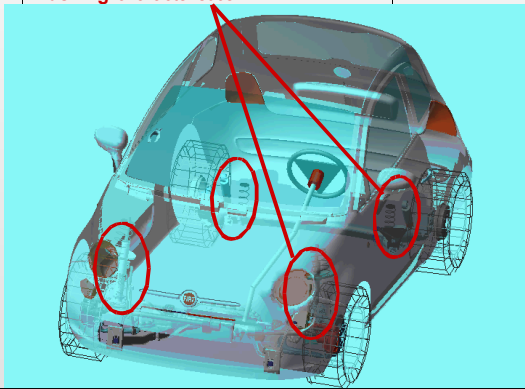
### Suspension Rolling stiffness

(spring, anti-roll-bar)

### Suspension Elasto-Kinematic

#### Input variables:

- Spring** Stiffness and preload
- Bumpstop** clearance and characteristics
- Anti-roll bar** diameter
- Damper** characteristics
- Bushing** characteristics



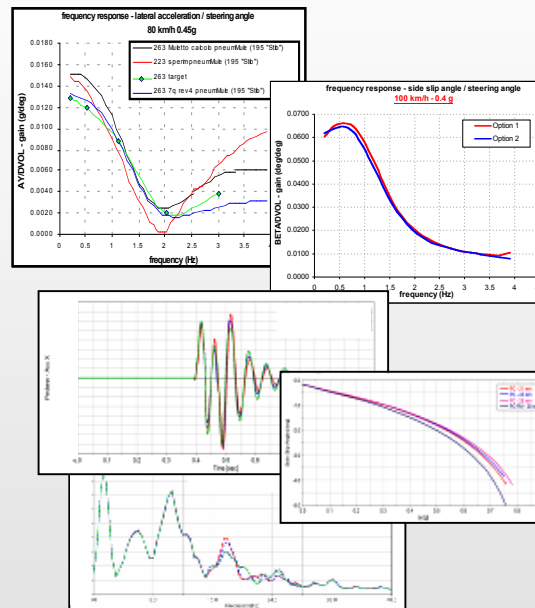
## Objectives:

### Key synthesis Handling parameters

(understeer, sideslip curve, yaw, rolling - gains, time delays)

### Key synthesis Comfort parameters

(peak accelerations, time dissipations, RMS/RMF)

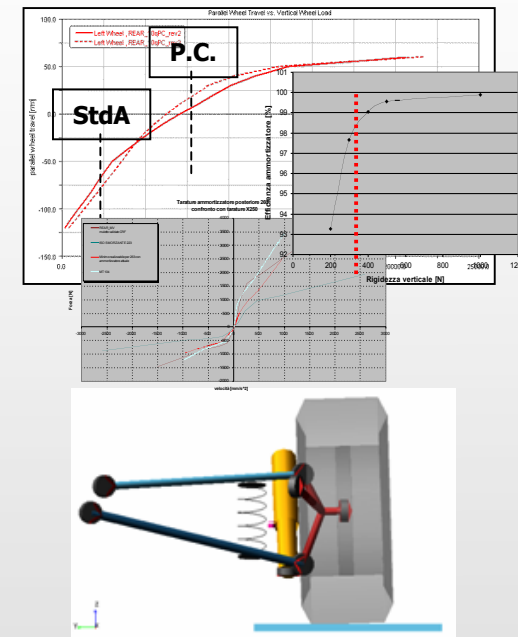


## Constraints:

Ride heights in various load conditions

Feasibility of the components for .ex. rate between axial and radial bushing stiffness, damper characteristics, bumpstop length and characteristics etc.

### Performance constraints





# DOE Study and Optimization Method



## Preliminary Study :

DoE Study (Sobol/Reduced-factorial distribution) =>  
 Selection of principal variables / constraints / objectives

## Main Study :

- ✓ DoE Study or DoE Study + Optimization of a limited number of input variables & objectives using *detailed model or response surfaces*
- ✓ Pareto FRONTIER => Selection of “optimum” solutions of vehicle target setting
- ✓ *Robustness* evaluation of Pareto optimal solution

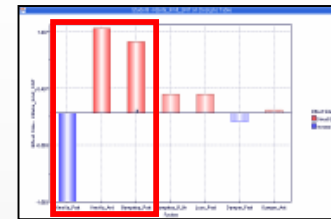
### Results of DOE study:

- Sensitivity and correlation direct/inverse of design variables vs targets & between each design variables
- Principal Heavy constraints (boundary condition)

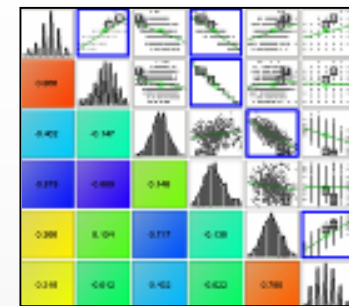
### Main Goal DOE / Optimization:

- Optimization of targets
- Trade-off scenarios
- Robustness of solutions

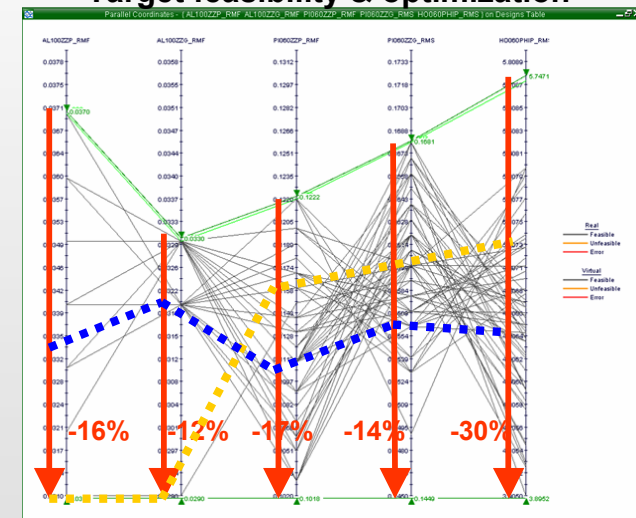
Linear and non-linear correlations



Main Influences (Inputs and Outputs)



Target feasibility & optimization





✓ Introduction

✓ **Examples of DOE, ROBUST DESIGN and OPTIMIZATION in Chassis & Vehicle Dynamics**

✓ Summary & Conclusion

## Applications – some examples



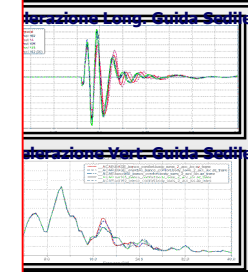
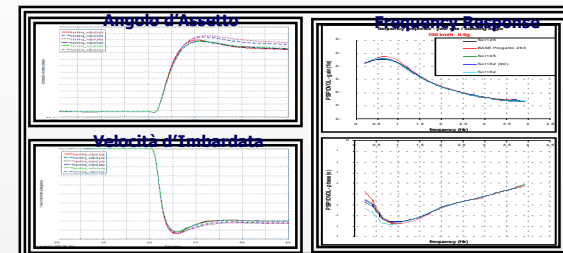
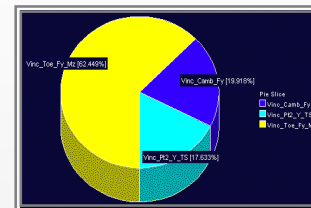
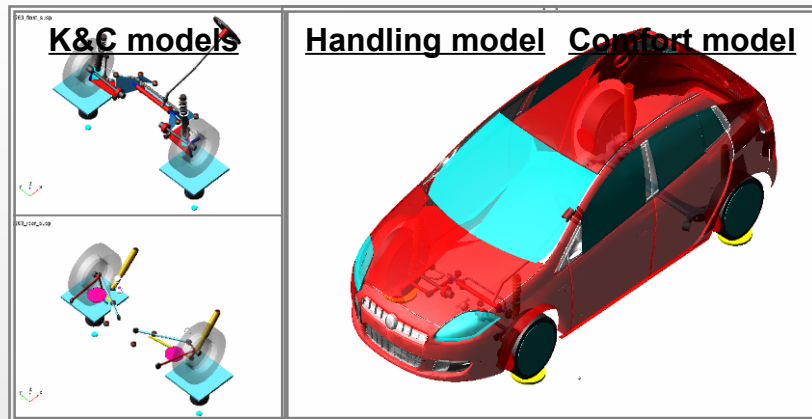
- ❖ **Handling & Ride Comfort**
  
- ❖ **K&C Suspension**
- ❖ **PT Mounts System**
  
- ❖ **Suspension NVH - Handling**
- ❖ **Active Systems (ARB)**
  
- ❖ **→ Focus on Timing & optimization results**
- ❖ **→ Method comparison**

# Handling&Comfort



## DOE & Optimization handling&comfort performances

Input Variables	Constraints	Objectives
<ul style="list-style-type: none"> <li>- Spring stiffness and preload</li> <li>- Bumpstop clearance and stiffnesses</li> <li>- Bushing stiffnesses X,Y,Z</li> <li>- Shock-absorber characteristics</li> <li>- ARB diameter</li> </ul>	<ul style="list-style-type: none"> <li>- Vehicle Heights (different load conditions)</li> <li>- components feasibility</li> </ul>	<p>Handling&amp;Comfort synthesis parameters</p> <ul style="list-style-type: none"> <li>- Roll,Pitch,yaw velocity,sideslip angles</li> <li>- time delays,pk/gain frequency</li> <li>- Peak/peak obstacle passing</li> </ul>



**Simulated manoeuvres :**  
 K&C : Elastokinematics  
 Handling : Sweep, Step Steer  
 Comfort : Obstacle passing,  
 Motorway, Pavè

**Results:**  
 Performance target  
 optimization

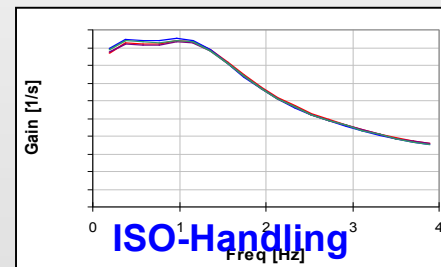
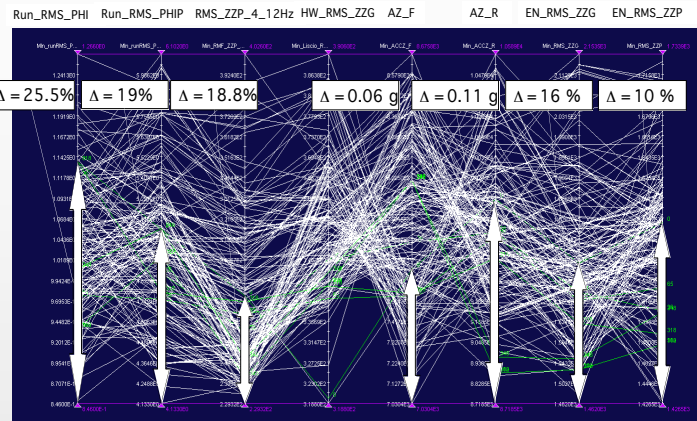
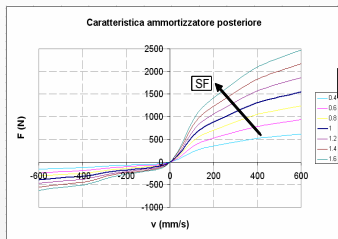
9 input variables  
 6 objectives  
 12 constraints  
 7 maneuvers  
 350 designs:  
 70 Sobol x 5 MOGA-II iterations  
 alt. 350 Sobol  
 3.5 days

# Ride Comfort (Handling Constraints)



## DOE & optimization comfort performances satisfying handling targets

Input Variables	Constraints	Objectives
<ul style="list-style-type: none"> <li>- Spring stiffness and preload</li> <li>- Bumpstop clearance and stiffnesses</li> <li>- Bushing stiffnesses X,Y,Z</li> <li>- Shock-absorber characteristics</li> </ul>	<ul style="list-style-type: none"> <li>- Vehicle Heights</li> <li>- components feasibility</li> <li>Handling parameters :</li> <li>- gain ay,Theta,Psip,Beta</li> <li>- time delays Psip/Ay,...</li> </ul>	<ul style="list-style-type: none"> <li>- Seats acceleration (RMF, amplitude)</li> <li>- Peak/peak obstacle passing</li> <li>- body motion (velocity&amp;acceleration)</li> </ul>



**Simulated manoeuvres :**  
 K&C : Elastokin.  
 Handling : Sweep,  
                   Step Steer  
 Comfort : Ostacle,  
                   Hole,  
                   Pavè track  
                   Motorway

**Results:**  
 Max performance allowed under constraints  
 Driver characteristics

7 input variables  
 9 objectives  
 9 constraints  
 14 maneuvers  
 300 Sobol alt.  
 80 Sobol +  
 MOGA-II 4  
 iterations => 320  
 designs

# Handling & Comfort Robust Design



## DOE & Robust design of handling & ride comfort performances

Input Variables (noise variables)	Constraints	Objectives
<ul style="list-style-type: none"> <li>- Spring stiffness and preload</li> <li>- Bumpstop clearance and stiffnesses</li> <li>- Shock-absorber characteristics</li> <li>- <b>STD DEV Parameters</b></li> </ul>	<ul style="list-style-type: none"> <li>- Vehicle Heights (different load conditions)</li> <li>- components feasibility</li> </ul>	Handling&Comfort synthesis parameters <ul style="list-style-type: none"> <li>- Roll,Pitch,yaw velocity,sideslip angles</li> <li>- time delays,pk/gain frequency</li> <li>- Peak/peak obstacle passing</li> </ul>
Input variables (optimization var.)		
<ul style="list-style-type: none"> <li>- Bushing stiffnesses X,Y,Z</li> </ul>		

### Approach :

1. DOE + optimization to find Pareto solutions. →Robust Design of Pareto Solutions including STDEV as parameter
2. DOE & optimization including STDEV for all interesting inputs from the beginning

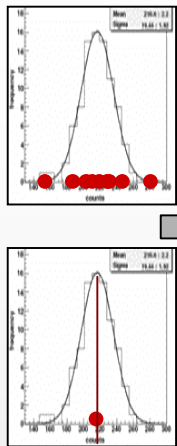
### Best compromise time - accuracy :

1. Large DOE with evaluation main parameters, correlation inputs-outputs,correlation between objectives
2. Reduction of number of input variables & objectives using direct / inverse correlation
3. New DOE + optimization to find Pareto solutions
4. Evaluation of Pareto solutions including stdev – check max/min performances

# Handling & Comfort Robust Design

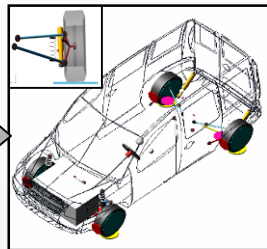


Statistic distribution input variables

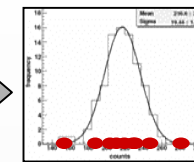
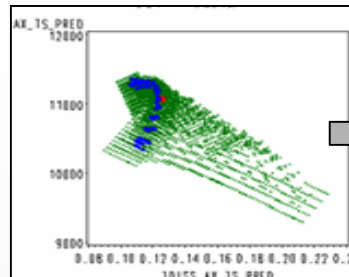


4 input variables  
6 objectives  
2 constraints  
7 maneuvers

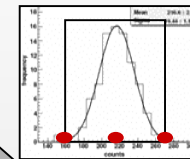
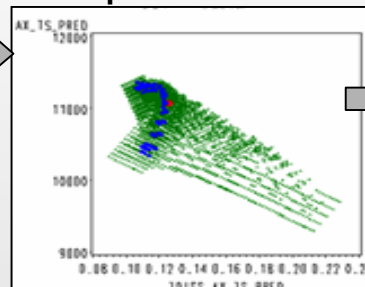
Full-vehicle analysis



Optimization of MEAN and STDEV



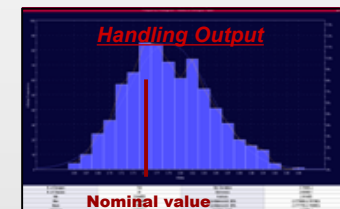
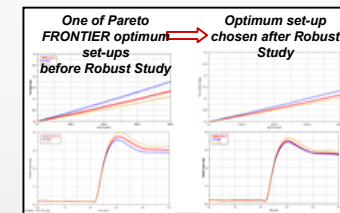
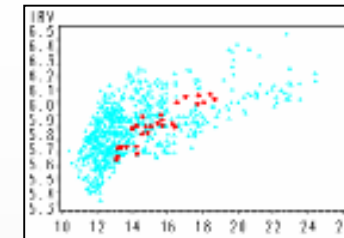
Optimization of nominal performance



**Results:**

Robust design evaluation of handling & ride comfort performances

25 Sobol x 26 LHS + MOGA-II 5 iterations => 3300 designs



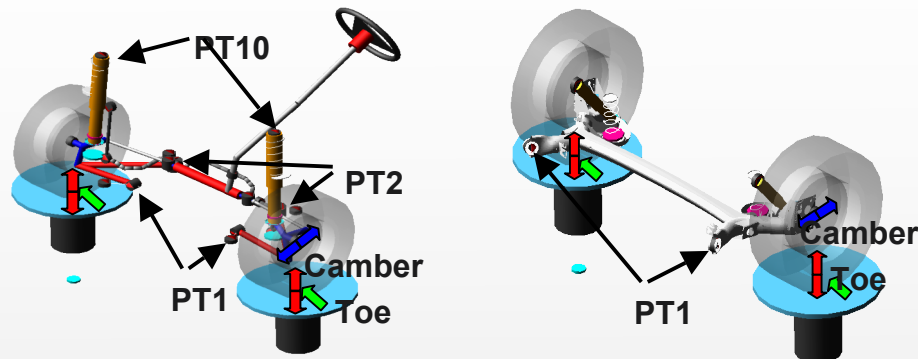
50 Sobol + MOGA-II 5 iterations => 250 designs

# K&C Suspension

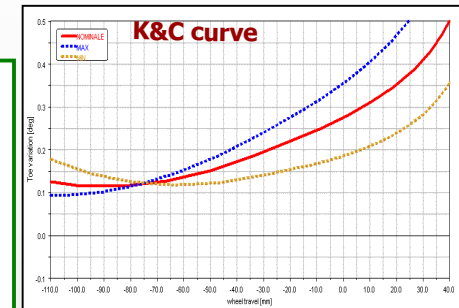
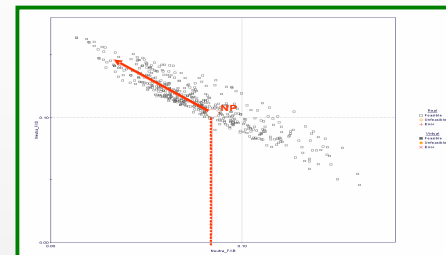


## DOE & Optimization K&C targets new suspension layout

Input Variables	Constraints	Objectives
Suspension attachments : - geometry X,Y,Z - Bushing characteristics X,Y,Z	Layout bushing feasib. Durability	Elastokinematics parameters : - toe & camber gain - Wheelbase & track var. vs Fx,Fy,Fz



Strictly correlated output parameters



### Simulated manoeuvres (ride height StdA & 2P) :

- Parallel travel
- Lateral load 2W parallel
- Braking 1W

### Results:

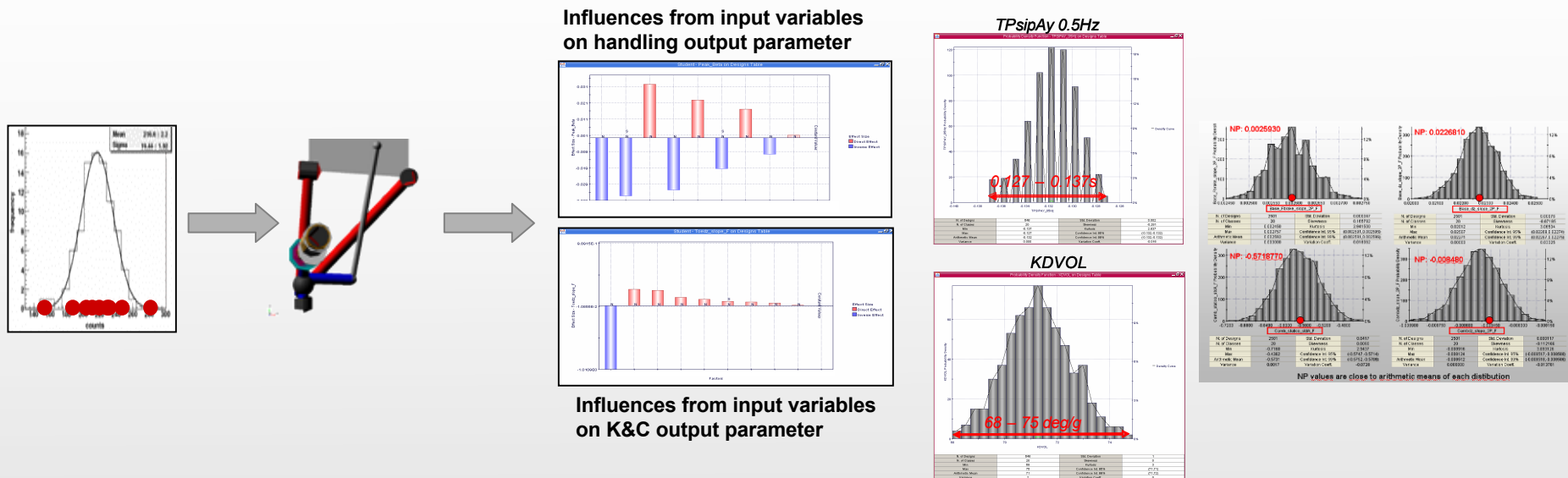
- Correlation & Sensitivity input/output variables
- Correlation design variables vs targets
- Optimization of K&C targets

- 16 input variables
- 8 objectives
- 5 constraints
- 4 analysis
- 1000 designs:
- 200 Sobol x 5 MOGA-II iterations
- 17 hours



## DOE & Robust design of suspension characteristics and tolerances analysis

Input Variables	Constraints	Objectives
- Geometric Tolerances of suspension attach.		- K&C - Handling VTS



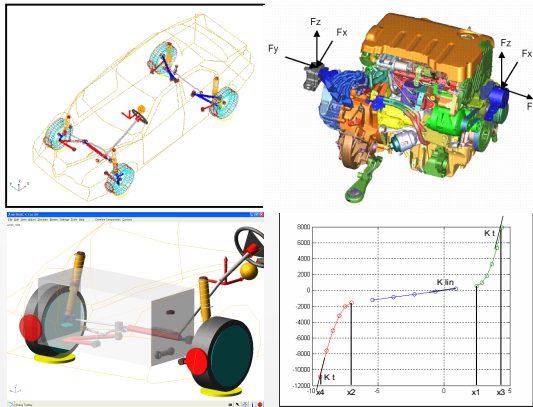
**Results:**  
Influence of geometric tolerances on K&C and handling VTS

# PT Mounts System

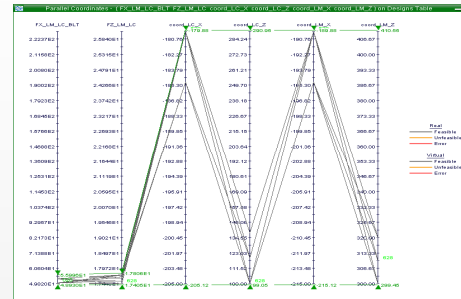


## Optimization of PTMounts System

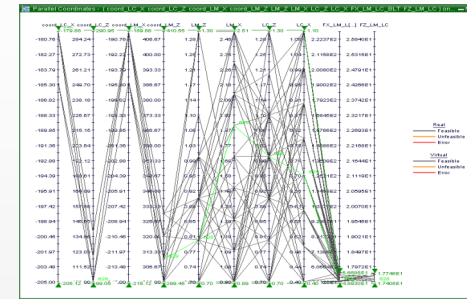
Input Variables	Constraints	Objectives
<ul style="list-style-type: none"> <li>- Geometry (Elastic center)</li> <li>- Mounts stiffnesses characteristics (X,Y,Z)</li> </ul>	<ul style="list-style-type: none"> <li>- components feasibility</li> <li>- geometry layout</li> </ul>	<ul style="list-style-type: none"> <li>- Force trasmission,working points</li> <li>- RMS/RMF seat acceleration</li> <li>- peak acceleration</li> </ul>



Targets Force trasmission& geometry



Targets Force trasmission& stiffnesses



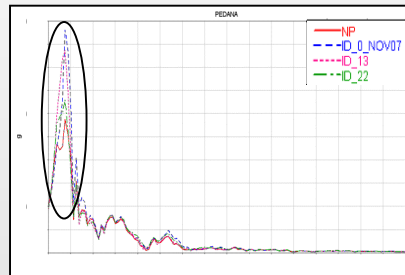
### Simulated manoeuvres:

- Static analysis (loads fatigue & misuse)
- Dynamic analyses (idle,WOT)
- Ride comfort pavè & motorway

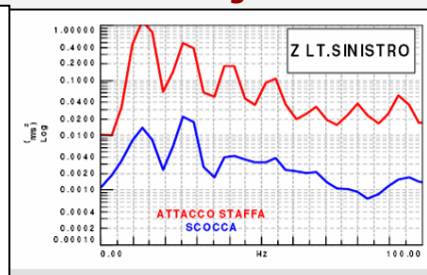
### Results:

- Optimize engine suspension characteristics in multiple mission
- Trade off in performances ride comfort , idle & acoustic

Ride comfort



Filtering AV3



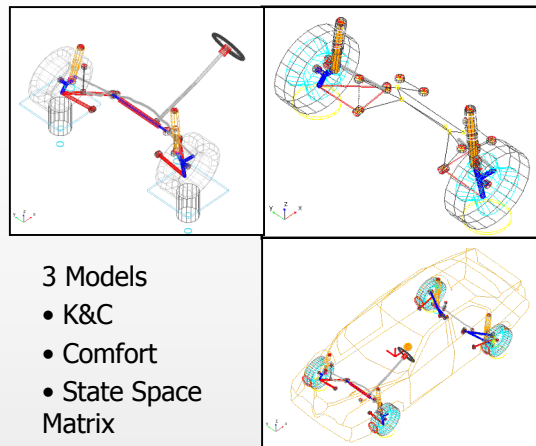
12 input variables  
 9 objectives  
 4 manoeuvres  
 500 designs:  
 100 Sobol x 5  
 MOGA-II iterations

# Suspension NVH - Handling



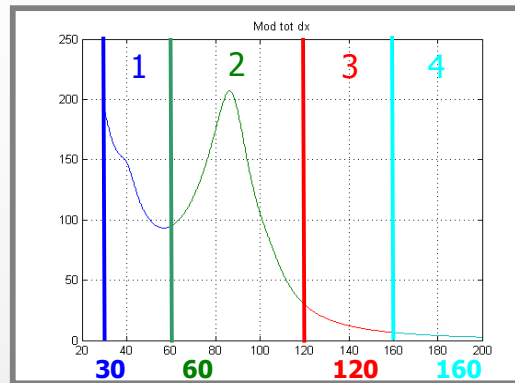
## DOE & Optimization forces transmitted from suspension

Input Variables	Constraints	Objectives
- Bushing stiffnesses X,Y,Z	Handling performance : - toe vs Fy, toe vs Mz - camber vs Fy	Ride performance : - Peak/peak obstacle passing - Med./High frequency force transmission

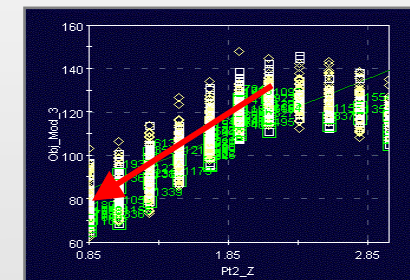


- 3 Models
- K&C
  - Comfort
  - State Space Matrix

**Results:**  
NVH-Ride Optimization determining optimum vehicle set-ups considering Handling constraints. Response surfaces used for FEM model analysis and final optimization.



8 input variables  
5 objectives  
3 constraints  
4 analysis/maneuvers  
500 designs:  
100 Sobol x 5 MOGA-II iterations  
1.5 days



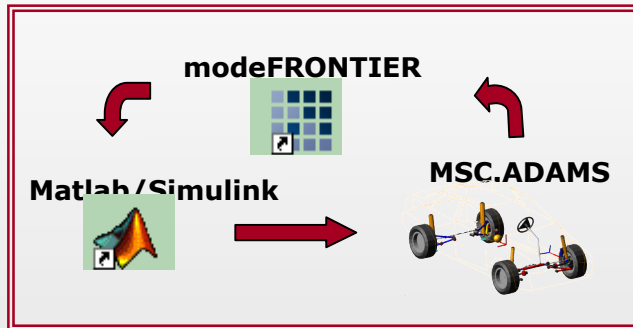
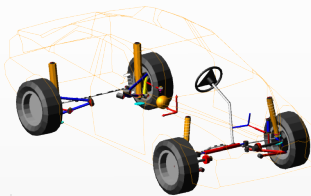
# modeFrontier - ADAMS - Matlab co-simulation



## Active Systems : DoE handling and comfort parameters

Input Variables	Constraints	Objectives
<ul style="list-style-type: none"> <li>- Spring stiffness and preload</li> <li>- Shock-absorber characteristics</li> <li>- Bushing stiffnesses X,Y,Z</li> </ul>	<ul style="list-style-type: none"> <li>- specific handling parameters</li> </ul>	<ul style="list-style-type: none"> <li>- Handling &amp; Comfort VTS</li> </ul>

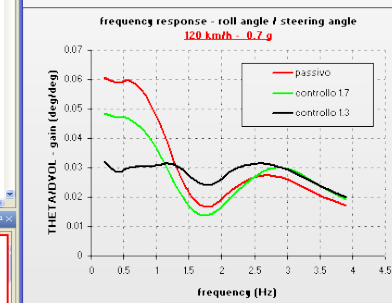
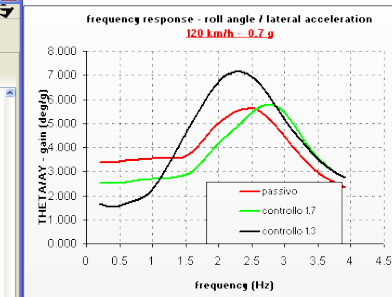
### New front active ARB



**Input Variables**

**Outputs, Objectives & Constraints**

Name	Variable T.	Value	Expression	Distribution	Scale	L
0	Kmolla_A_	Variable	0.000E0	None	0.000E0	9
1	Kmolla_	Variable	0.000E0	None	0.000E0	9
2	Camm_P_	Variable	0.000E0	None	0.000E0	9
3	Camm_Ant	Variable	0.000E0	None	0.000E0	9
4	PI1_ant	Variable	0.000E0	None	0.000E0	9
5	PI2_ant	Variable	0.000E0	None	0.000E0	9
6	Duomo_	Variable	0.000E0	None	0.000E0	9
7	PI1_nst	Variable	0.000E0	None	0.000E0	9



16 input variables  
 12 objectives  
 6 constraints  
 5 analysis  
 250 designs: 250 Sobol

### Results:

- Handling and comfort targets,
- Correlation & sensitivity input/output variables
- Study of controls in all vehicle condition

## DOE-Optimization Study results



Simulation	Time	%Perf. Improv.
Handling&Comfort	15min/design, 350designs => 3.5ggr	15%
Handling / Comfort Robust Design	8min/design, 3300 designs => 20ggr	10%
K&C Suspension	1min/design, 1000designs => 17h	25%
PT Mounts System	4min/design, 500designs => 1.3ggr	30%
Co-simulation MSC.ADAMS-Matlab Active Control System	70min/design, 250designs => 10ggr	+10% of feasible design
Suspension NVH	4min/design, 500designs => 1.5ggr	+25% of feasible design

## Methods Comparison – a test case



### *Handling and Ride-Comfort Performances*

### *Comparison between traditional & multi-objective optimization approach*

Handling/Comfort simulation - test case	TRADITIONAL APPROACH	MULTIOBJECTIVE OPTIMIZATION APPROACH
<b>Needs</b>	Knowledge and experiences about vehicle dynamics & simulation	Knowledge and experiences about vehicle dynamics & simulation . Basic knowledge of Doe, optimization techniques
<b>Method</b>	'Trial and error'	Multiobjective & statistical
<b>Human time dedicated (pre/post)</b>	8 days	3 days
<b>Calculation time</b>	1 day	5 days
<b>Total time</b>	2 weeks	< 2 weeks
<b>Human activities</b>	80% for model modification & run , 20% postprocessing	20% for model modification & run , 80% postprocessing and scenarios analysis
<b>Numbers of solutions / scenarios evaluated :</b>	X	10X – 100X
<b>Optimal performance reached</b>	70-80%	100%



- ✓ Introduction
- ✓ Examples of DOE, ROBUST DESIGN and OPTIMIZATION in Chassis & Vehicle Dynamics
- ✓ **Summary & Conclusion**

## Summary



❖ *Fiat's latest success products, were developed using intensive use of virtual analysis in only 16-18 months.*

❖ *New target for future projects : increment of virtual analysis to reduce cost & time development and to allow more robust experimental testing*

*DOE, Robust design & multiobjective optimization are success key factor*

❖ *The use of modeFRONTIER in Chassis Virtual Analysis as a DOE or/and optimization tool enables:*

- ✓ *To Reduce time and calculation loops*
- ✓ *To Gain a deeper understanding of the system and the correlation between input variables and output parameters*
- ✓ *To increase possibility to explore best solutions & scenarios*
- ✓ *To evaluate robust and stable solutions*



## Conclusion & next steps...



### *Advantages in extended application :*

- ✓ *REDUCTION OF DEVELOPMENT TIME*
- ✓ *VEHICLE TESTING & EXPERIMENTAL TUNING QUALITY ORIENTED*
- ✓ *APPROACH THE OPTIMUM SOLUTION ALREADY FROM THE BEGINNING*
- ✓ *TARGET FEASIBILITY & MAIN COSTRAINTS ARE KNOWN FROM EARLY PHASE*
- ✓ *CLEAR & OPTIMIZED TRADE OFF OF PERFORMANCES*
- ✓ *EXPLORE BEST SCENARIOS AND GIVE MORE CHOISES TO MANAGEMENT*

### *Don't forget to improve...*

- ✓ *Model complexity & detail of physical systems and components*
- ✓ *Statistical approach in model correlation : numerical model & measurements statistically correlated*

*... Words to take in mind...*

**"DOE - OPTIMIZATION - ROBUST DESIGN"**

Thanks !



*Thank you for your attention*

