

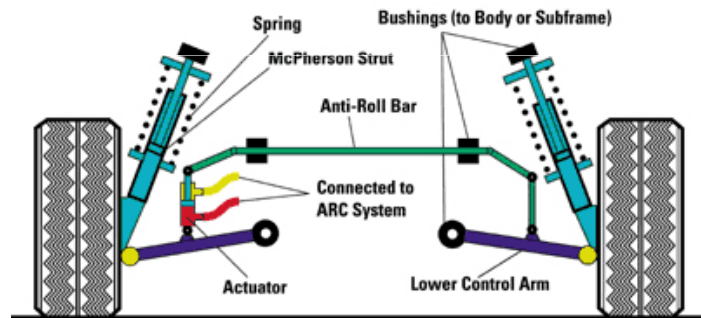
Electric Active Roll Control (EARC)

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VEHICLE DYNAMICS
EXPO 2010

22, 23, 24 JUNE 2010 MESSE STUTTGART | STUTTGART | GERMANY

About Us

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YEAR2010 
The Young European Arena of Research

Silver Medal Award



**AUTOMOTIVE PRODUCT
ENGINEERING MSc**



- Students at Cranfield University School of Engineering
- Pursuing MSc in Automotive Product Engineering
- This presentation represents our ongoing thesis research in the area of Active Roll Control
- Expected accomplishment in September 2010

Background

The Problem:

- Body roll is caused by lateral acceleration
- Too much roll causes passenger discomfort
- Also result in roll steer effects
- Adversely influences the driver's control responses

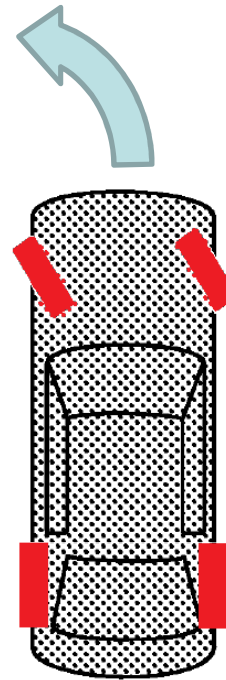
The Solution:

- Reduce the roll angle (θ) using Active Roll Control (ARC)

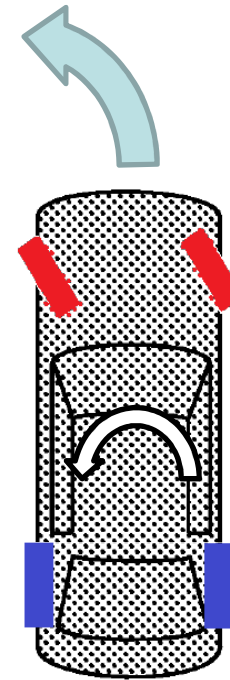


Source: First Mustang Club Of Germany

Types of ARC Control



Single Channel

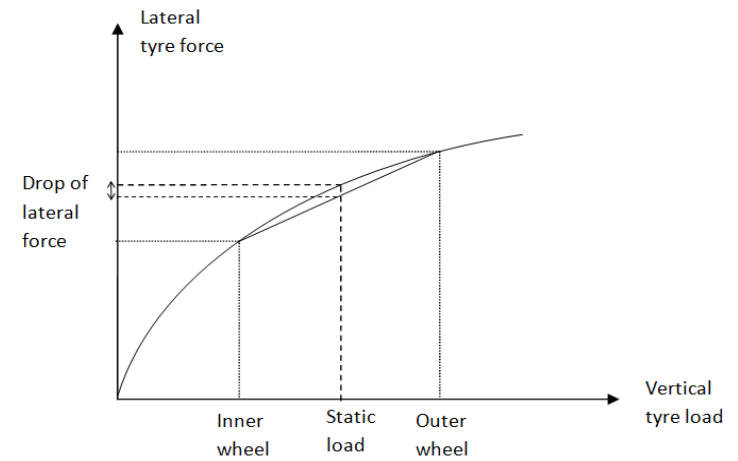


Dual Channel

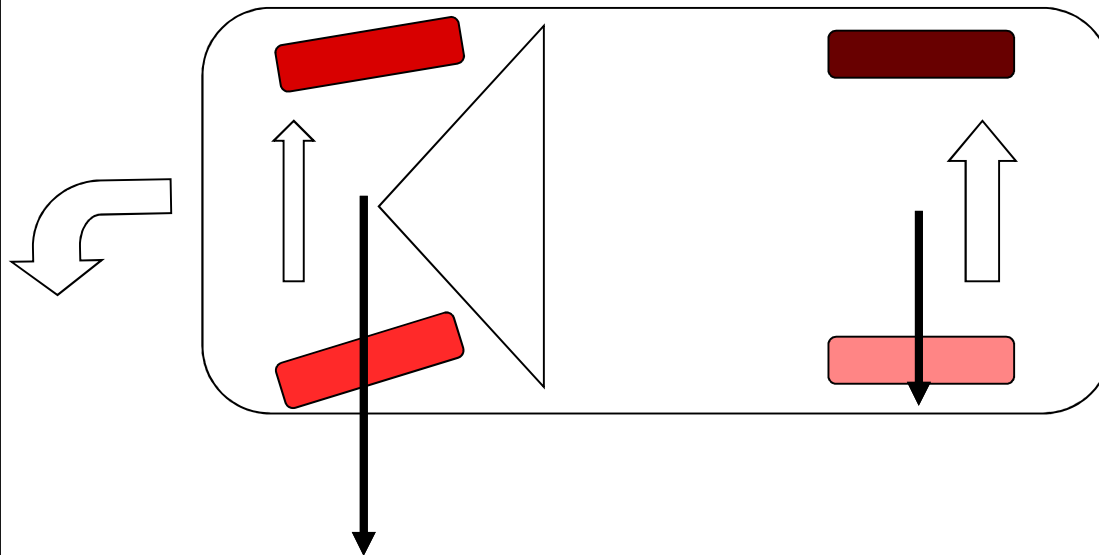
ARC Configuration	Roll Control	Yaw Control
Front + Rear (single channel)	✓	✗
Front + Rear (dual channel)	✓	✓

Yaw Rate Control

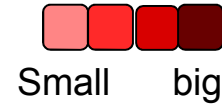
Non linearity of the lateral force capability:



More oversteering:
increasing weight transfer to the rear



Normal load:



Roll moment:

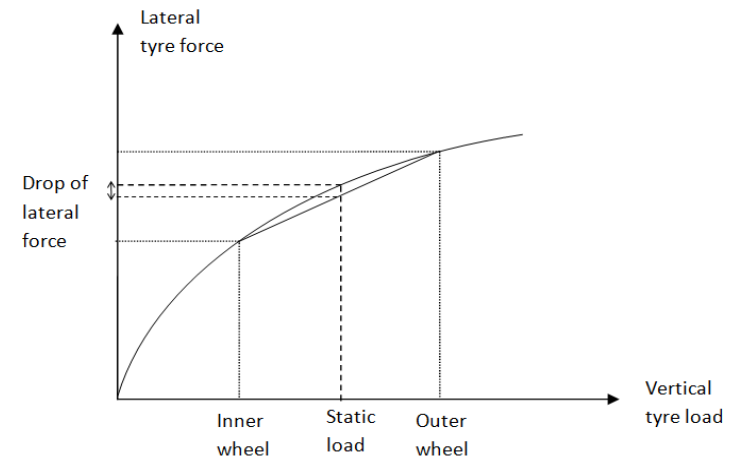


Lateral forces:

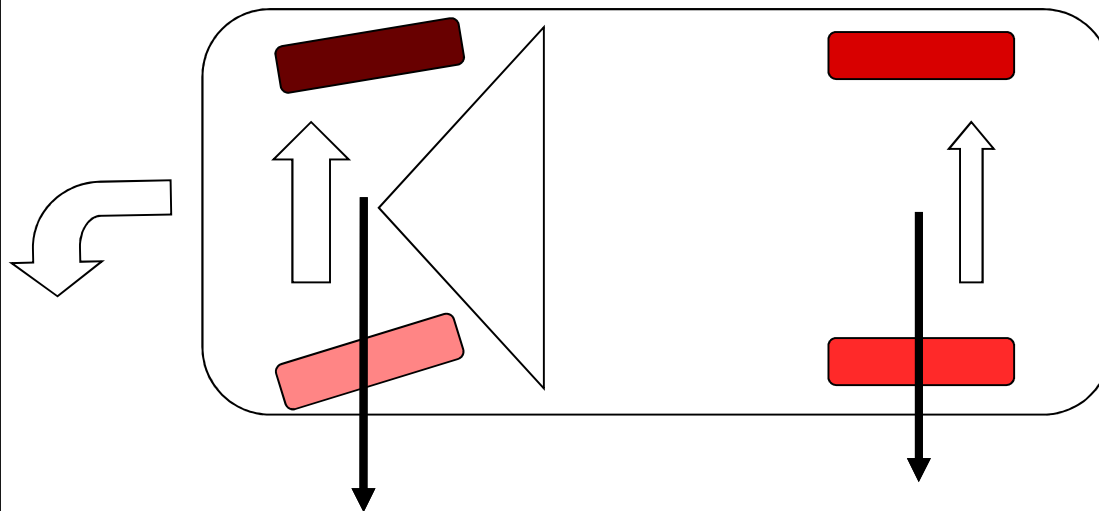


Yaw Rate Control

Non linearity of the lateral force capability:



More understeering:
increasing weight transfer to the front

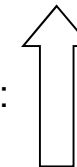


Normal load:



Small big

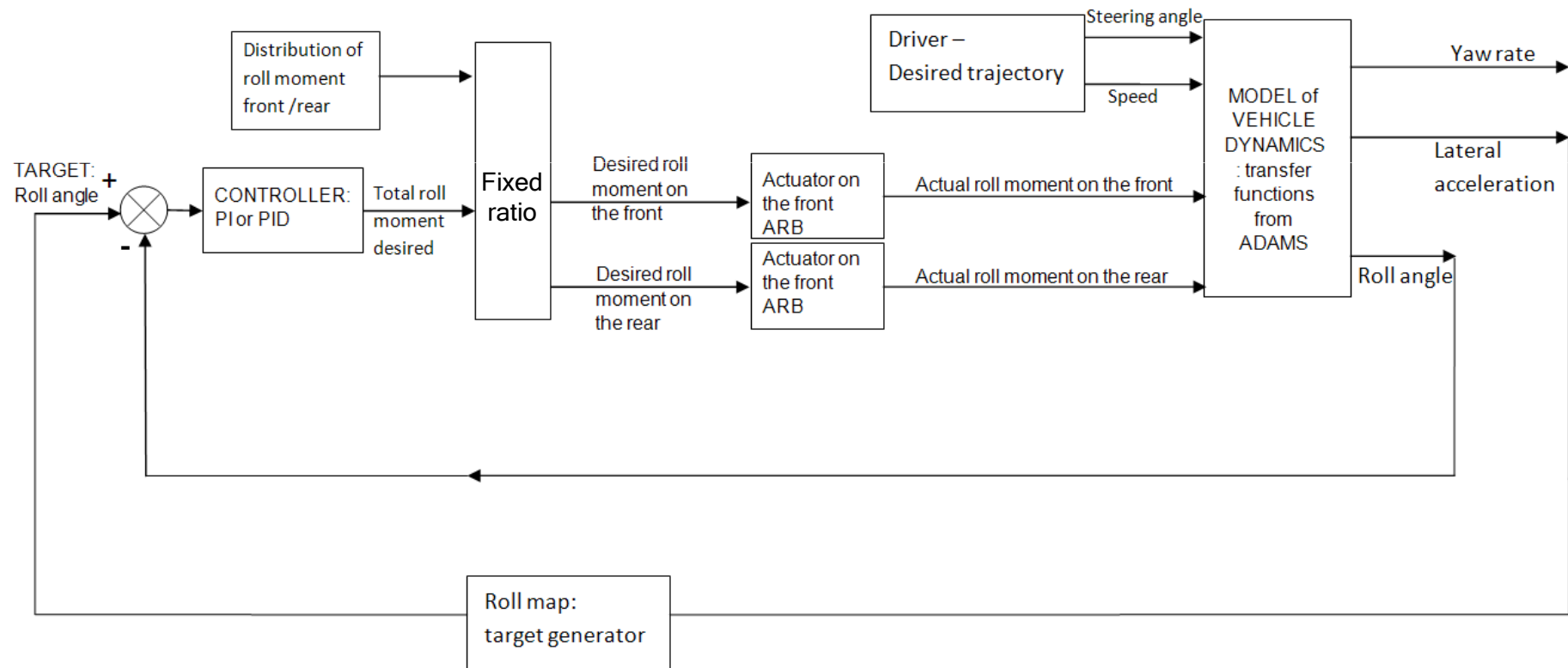
Roll moment:



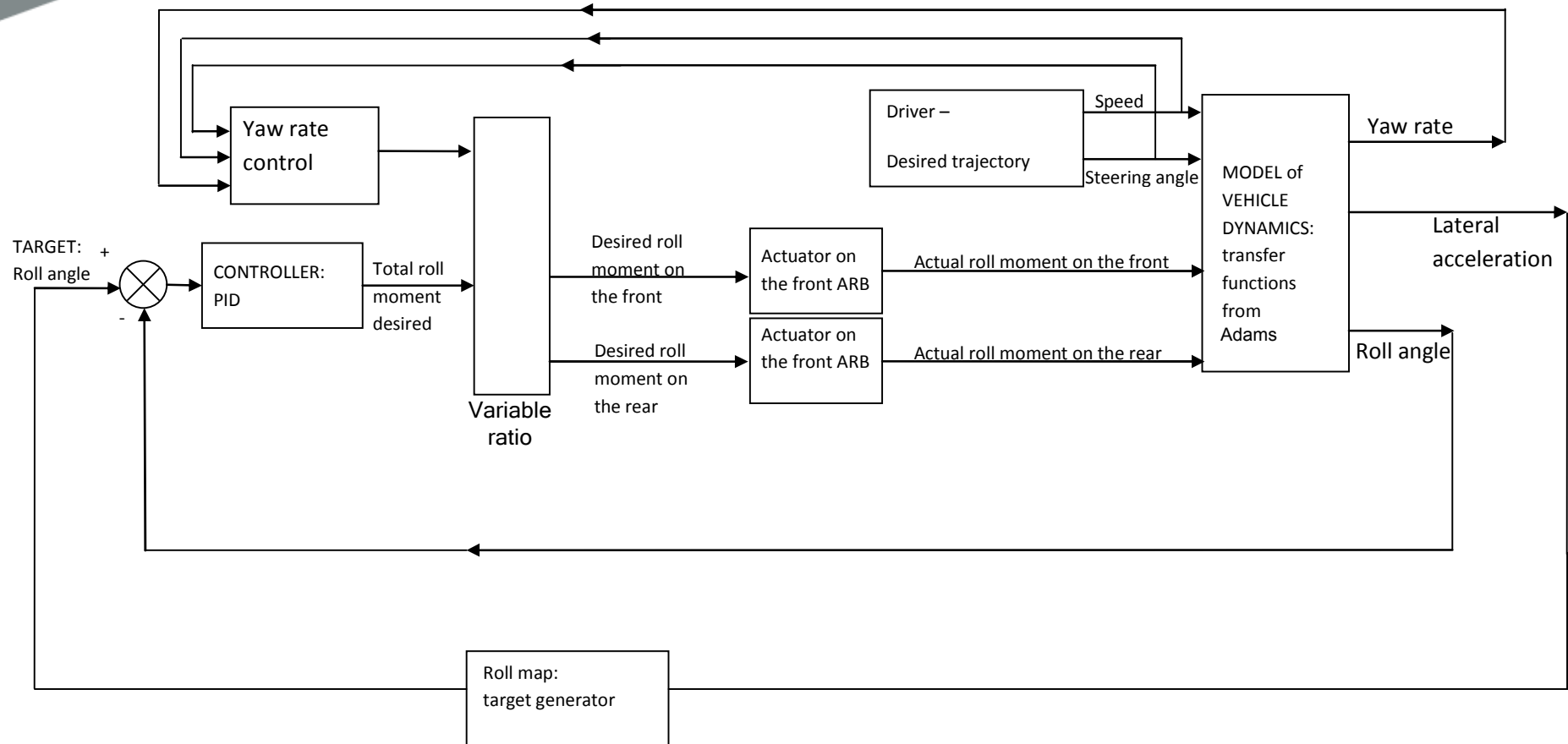
Lateral forces:



Single Channel Control System



Dual Channel Control System



Electric vs Hydraulic

	Hydraulic ARC	Electric ARC
Response	Slow	Quick
Cost	Expensive	Cheaper
Design	Complex	Simple
Maintenance	Difficult	Easier
Adaptability	Difficult	Easier

EARC also offers fuel consumption reduction of 1 – 2% compared to HARC*

*Source: ZF Sachs

Aims and Objectives of Research

1. Simulation of single channel HARC
2. Simulation of single channel EARC
3. Compare single channel HARC vs EARC

4. Simulation of dual channel HARC
5. Simulation of dual channel EARC
6. Compare dual channel HARC vs EARC

Electric Active Roll Control (EARC)

Modeling (MSC-Adams)

- Creation of detailed vehicle model and ARC mechanisms using Adams/Car and Adams/Mechatronics
- Sizing and physical location of EARC and HARC components
- Specifying suspension parameters:
 - Tire model
 - Suspension kinematics
 - Spring rates

- Roll Angle
- Lateral Acceleration
- Steering Angle (dual channel)
- Yaw Rate (dual channel)
- Vehicle Speed (dual channel)

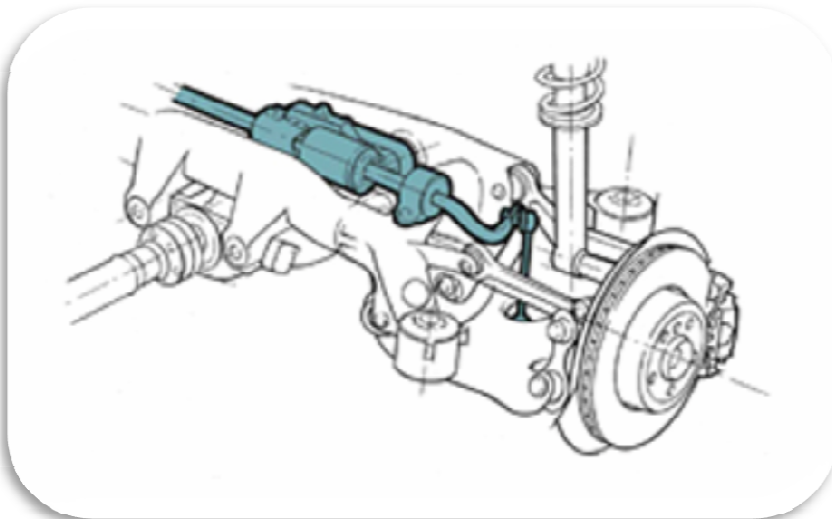
Controls (Matlab/Simulink)

- Creating control strategy for both single channel (roll angle) and dual channel (roll angle + yaw rate) using Simulink
- Tune controller parameters (PI and PID)
- Analyze the vehicle dynamics response of an EARC system and compare it to that of a HARC system

- Front and rear roll moments

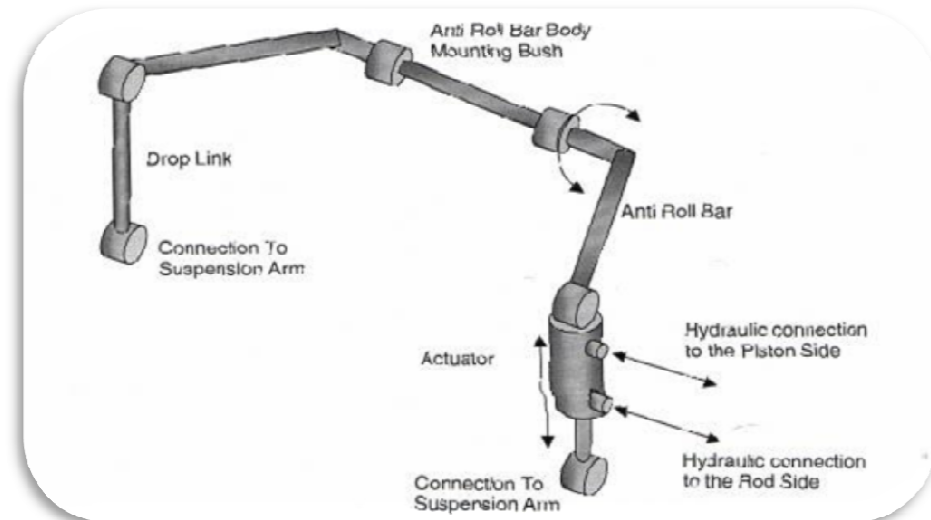
Current Hydraulic ARC Mechanisms

Rotary Actuator



Source: Bayerische Motoren Werke AG

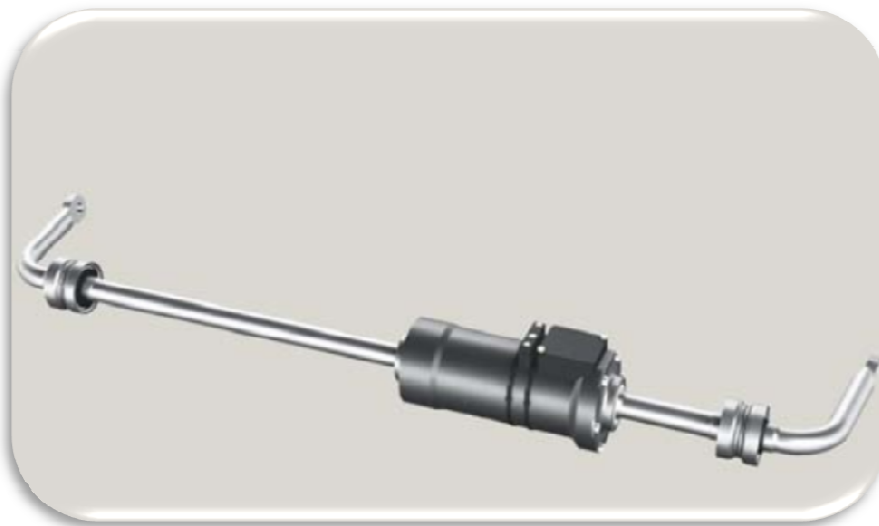
Linear Actuator



Source: TRW Automotive

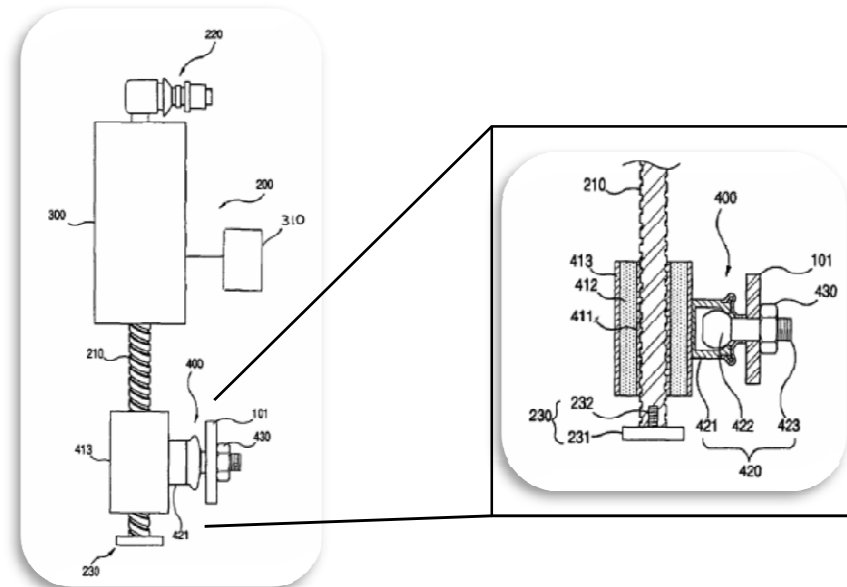
Electrical ARC Mechanisms

Rotary Actuator



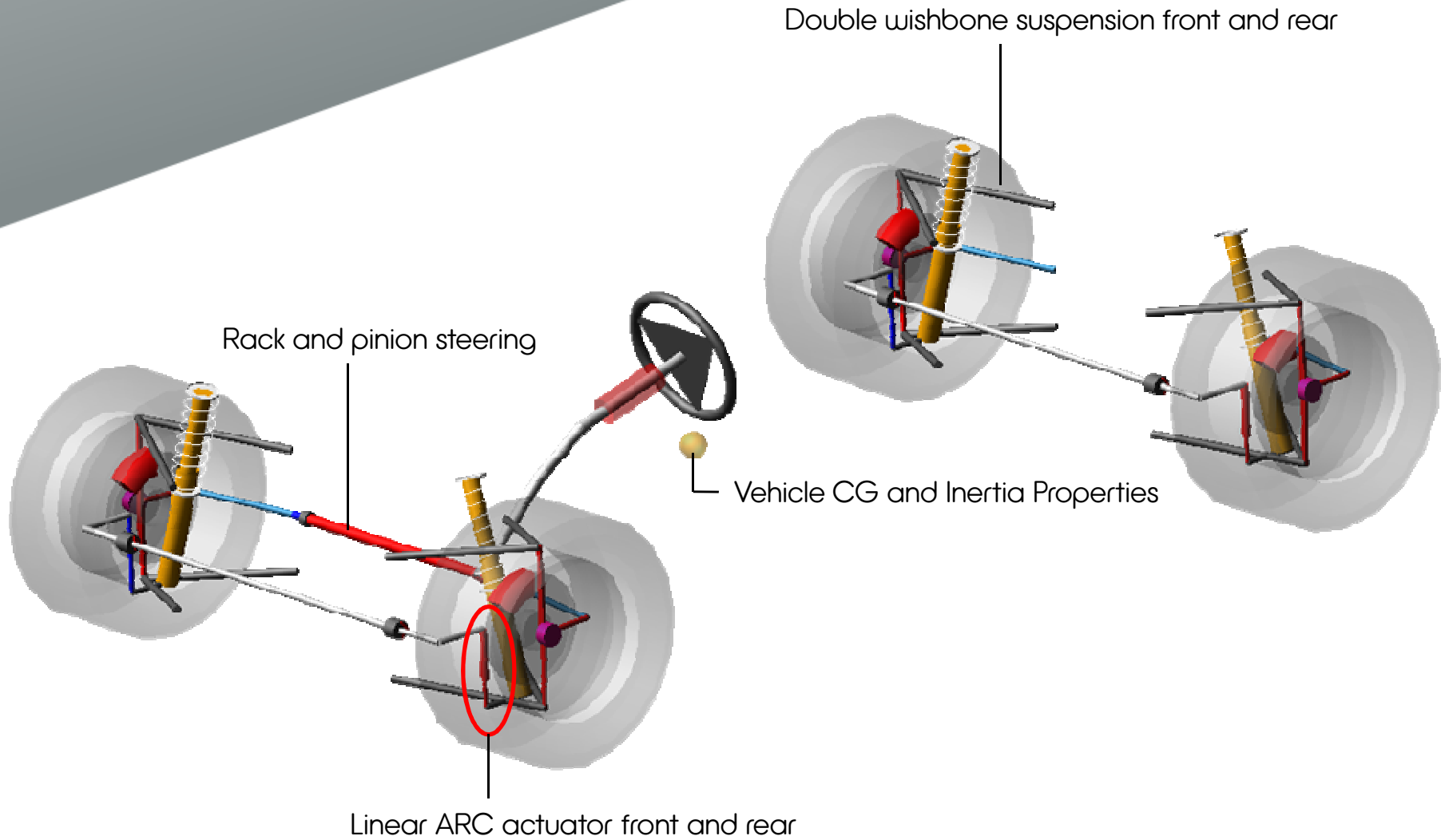
Source: ZF Sachs

Linear Actuator

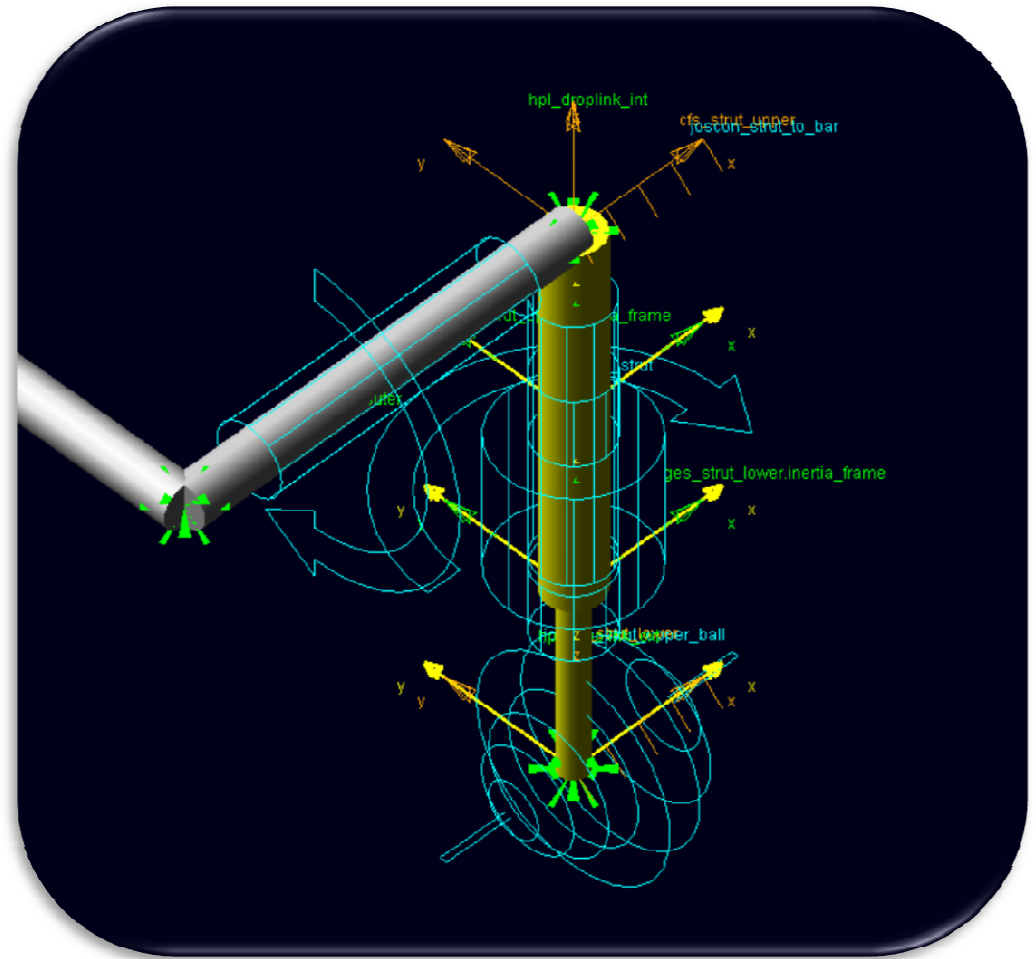
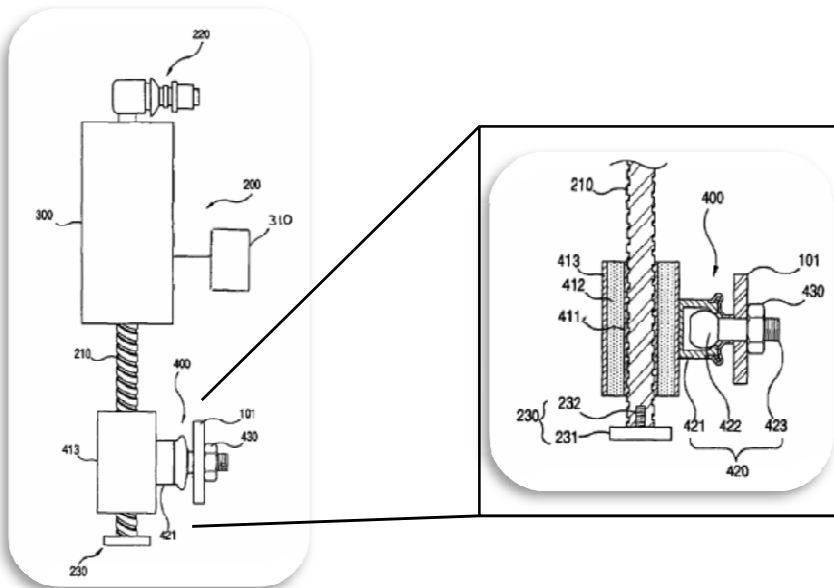


Source: Hyundai US Patent #7,427,073 B2

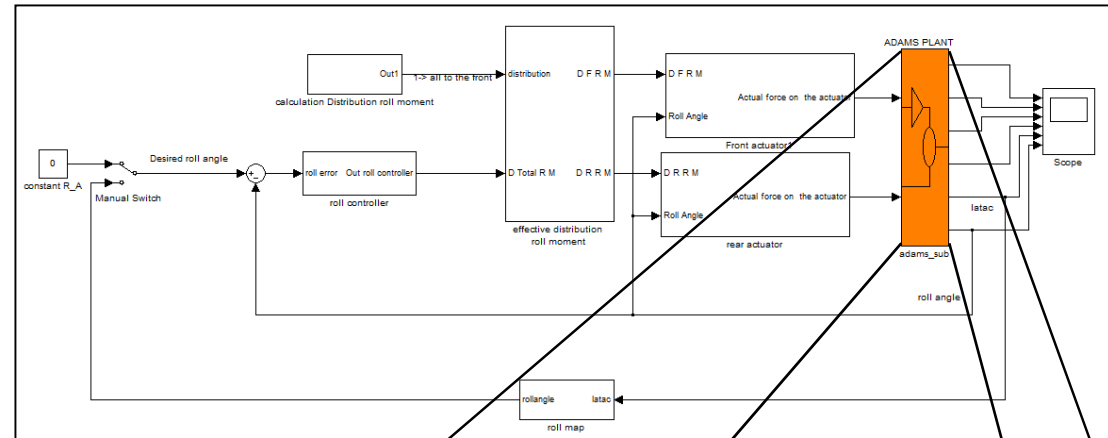
Modelling in Adams/Car



Electrical ARC Mechanism



Co-simulation between Adams and Simulink

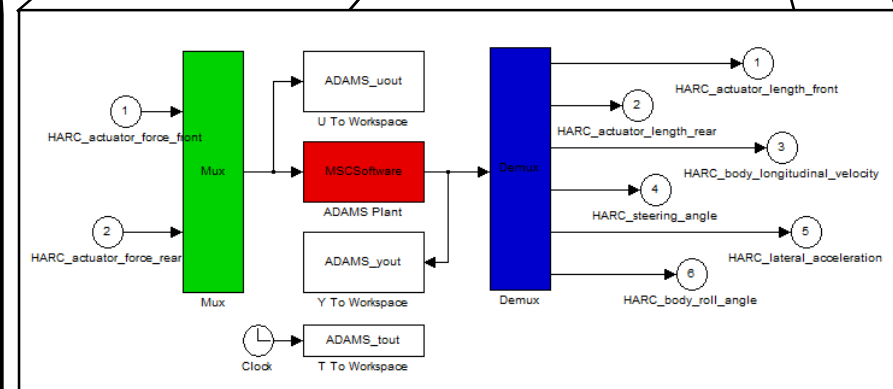


- Adams/Car outputs variables and simulation data into MATLAB/Simulink environment via an M-file and MDL-file respectively

- MDL-file contains a function block for “drag-and-drop” into Simulink control system

- Simulation is initiated using Simulink, which then carries out the co-simulation in the background with Adams/Solver

- Adams/Car and Adams/PostProcessor used for viewing simulation results



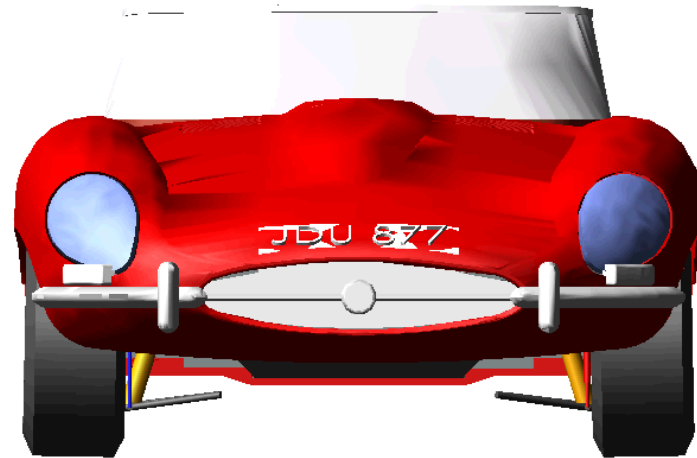
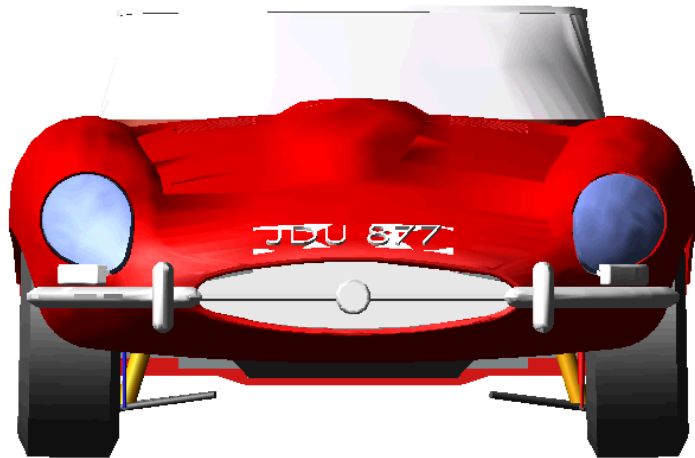
Results

Without ARC

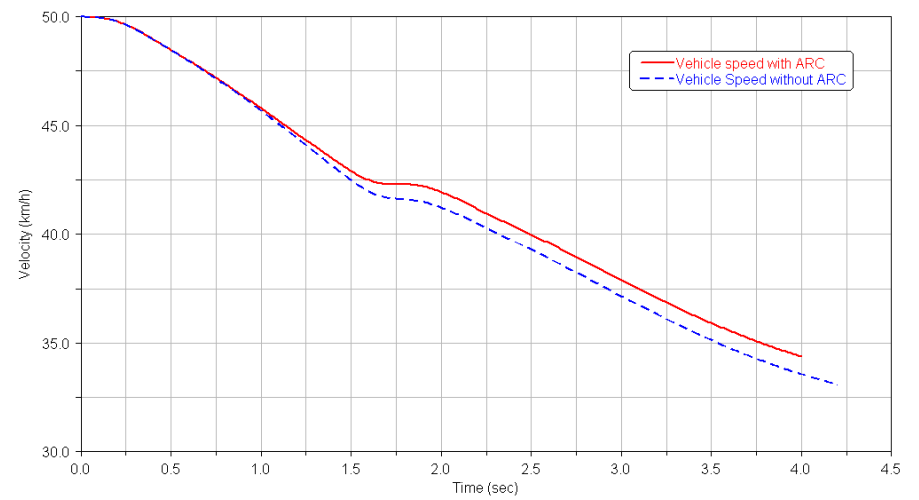
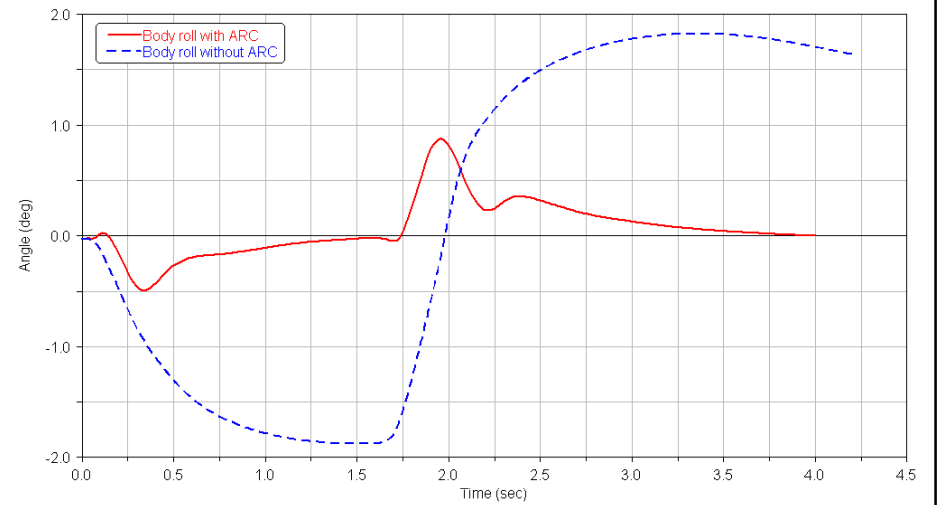
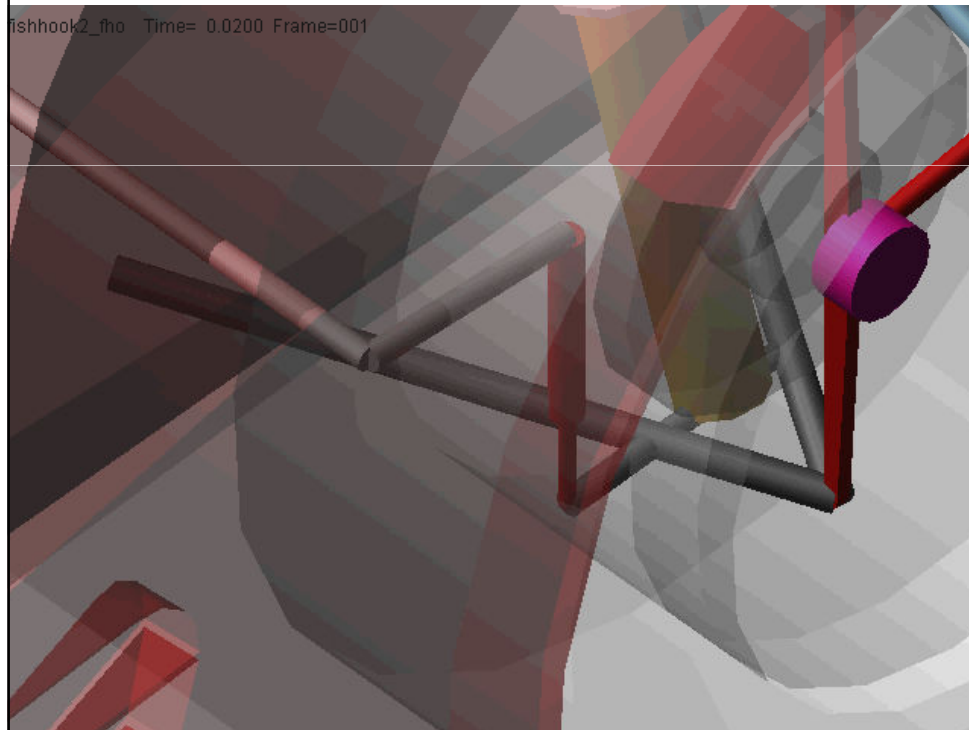
With ARC

fish_hook_pac89_tires_fho Equilibrium Frame=001

fishhookpac89tires_fho Time= 0.0100 Frame=001

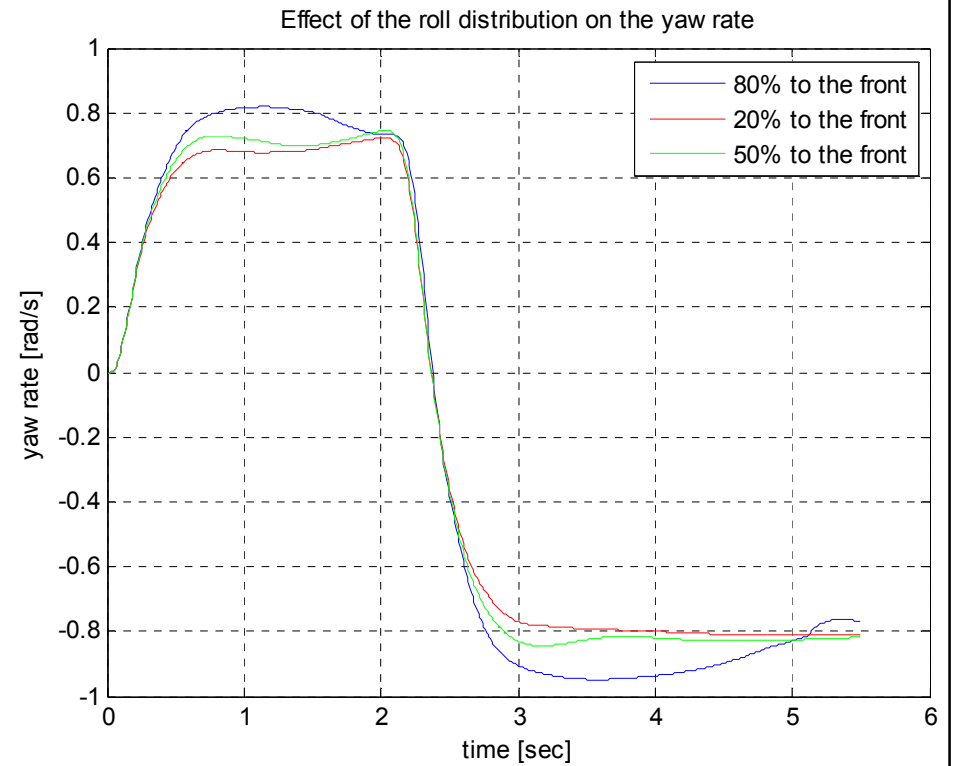


Results



Dual channel ARC: influence of the roll distribution

Multiple Runs Time= 0.0100 Frame=001



Dual channel ARC: Safety Improvement

Multiple Runs Time= 0.0100 Frame=001



Conclusion

- Active Roll Control offers potential to reduce body roll and increase stability
- Higher average vehicle speeds attainable via ARC
- Electric ARC systems offer easier implementation in full electric and hybrid vehicles
- Impact of Electric ARC systems to be investigated further
- Passive suspension can be tuned for increased comfort for vehicles with ARC systems

Thank You

Questions and Comments