

Innovations in Vehicle Simulation Software for Ease of Use

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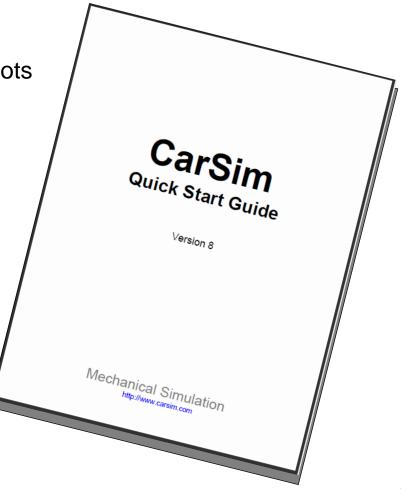
Background

- Applications for vehicle dynamics simulation tools in the automotive industry are constantly expanding
- To meet the needs of new users the software must grow in features, sophistication and complexity
- The challenge to software designers is to keep the software easy to use despite increasing complexity
 - Keeping the interface intuitive (obvious)
 - Structuring the interface for ease of use (efficient)
 - Making it easy to set up vehicles and tests
 - Facilitating evaluation of results
 - "Help" resources
- CarSim 8 has many features illustrating these techniques

Quick Start Guide

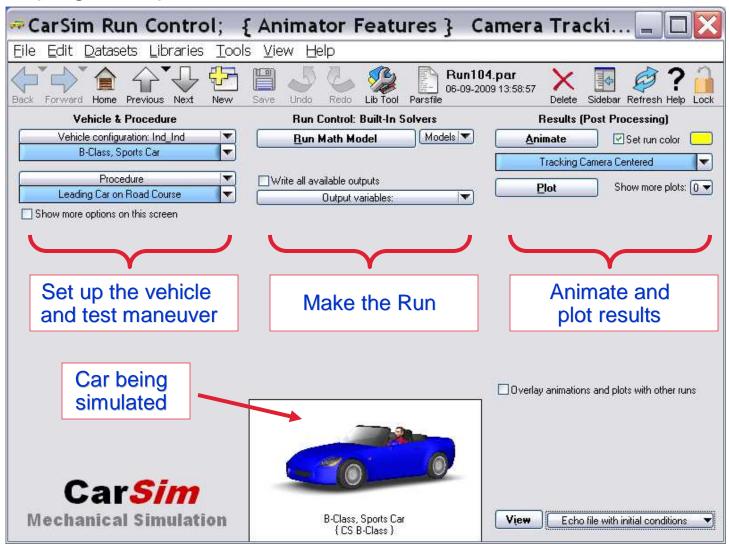
Learn to use software in 2-hour exercise

- Run control
- Animating simulation results
- Plotting results and creating new plots
- Creating databases
- New test procedures
- Changing vehicle properties
- Desktop shortcuts
- Managing multiple databases



Program Structure

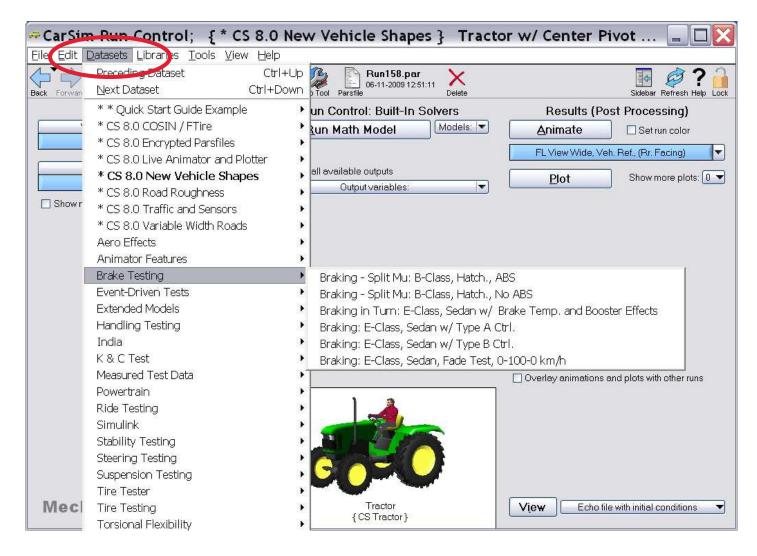
Keeping it simple and consistent



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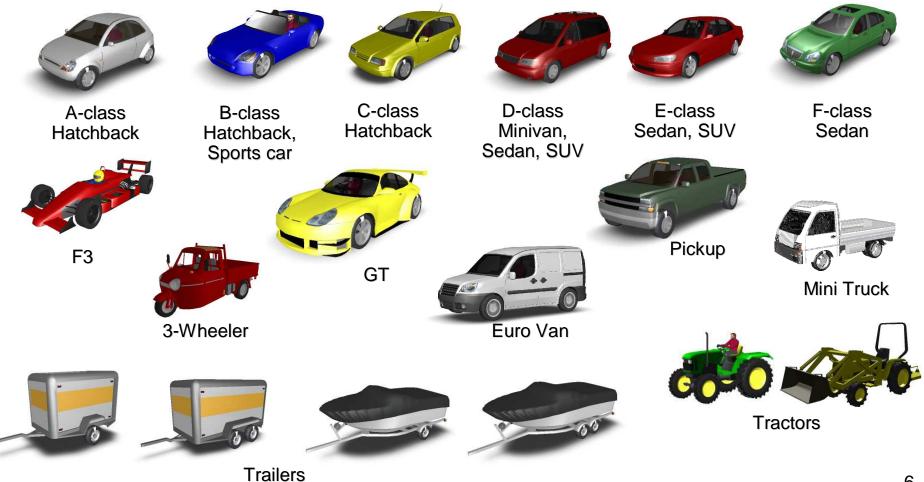
CarSim Example Tests

Over 100 examples give users a starting point for setting up their first simulation



The CarSim Vehicle Family

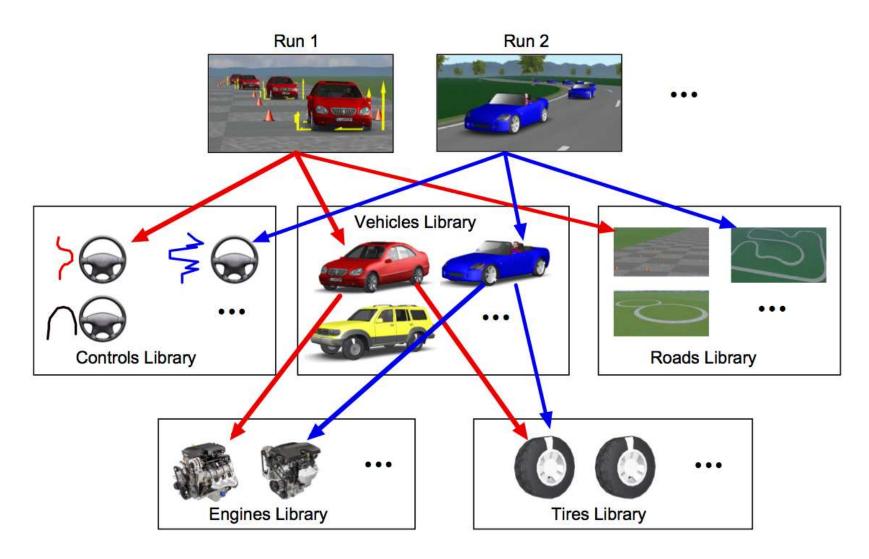
Start simulating immediately – choose from data sets for 26 generic vehicles



CarSim Database Structure

- Simulation datasets are "assembled"
- 160+ libraries (screens)

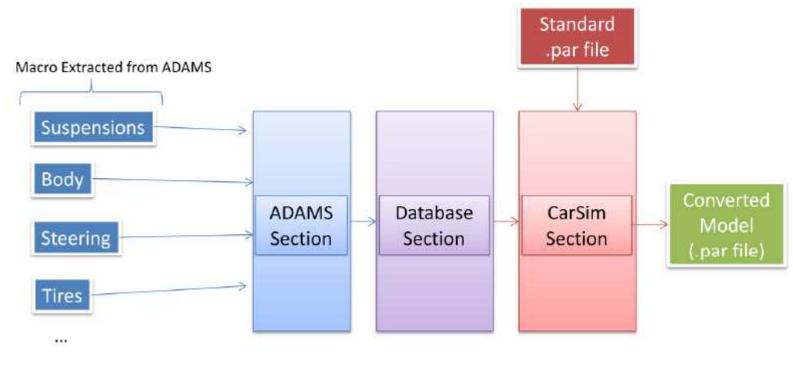
Mechanical Simulation



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Connectivity with Vehicle Dynamics Community

- Example:
 - Translating data from other programs
 - ADAMS/Car to CarSim converter, developed and validated by AMET S.r.l.



Available from AMET S.r.l, <u>www.amet.it</u> Booth 5100

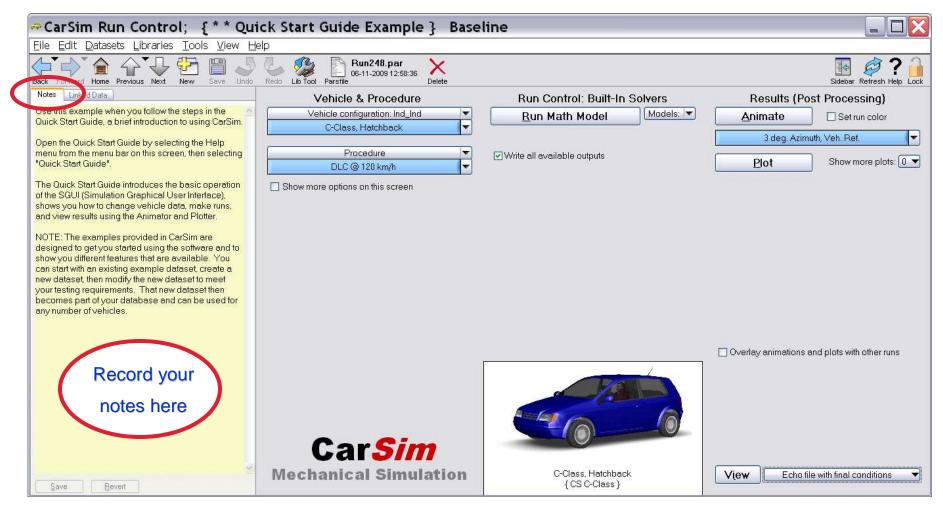
Tracking Data Sets

- Choose from multiple data base folders on start up of the program
- Display the data files used with this run

🛹 CarSim Run Control; { Aero Effects } Crosswind, Low Mu w/ ESC *								
Eile Edit Datasets Libraries Tools View Help								
Back Forward Home Previous Next New Save Undo Re	do Lib Tool Parsfile Bun107.par 06-10-2009 13:12:06 Delete		Sidebar Refresh Help Lock					
Notes Linked Data	Vehicle & Procedure	Run Control with Simulink	Results (Post Processing)					
CarSim Run Control: Crosswind, Low Mu w/ ESC Models: Simulink: ESC Control //O Channels: Import: ESC Import //O Channels: Export: ESC Export Animator: Camera Setup: Rear View High, Road Ref. Animator: Reference Frame: Camera Rear Point w/ Vehicle: Loaded Condition: D-Class, Sedan w/ Aero F O Vehicle: Loaded Condition: D-Class, Sedan w/ Aero F O Vehicle: Loaded Condition: D-Class, Sedan w/ Aero F O Vehicle: Loaded Condition: D-Class, Sedan w/ Aero F O Vehicle: Loaded Condition: D-Class, Sedan w/ Aero F O Vehicle: Loaded Condition: D-Class, Sedan w/ Aero F O Vehicle: Loaded Condition: D-Class, Sedan w/ Aero F O Vehicle: Loaded Condition: D-Class, Sedan w/ Aero F O Vehicle: Loaded Condition: D-Class, Sedan w/ Aero F O Vehicle: Vehicl	Vehicle configuration: Ind_Ind	Run Now Send to Simulink Models: ESC Control Write all available outputs Output variables:	Animate Set run color Rear View High, Road Ref. (Frt. Facing) Plot Show more plots: 0					
 Vehicle: Assembly: D-Class, Sedan (Transparent, N Suspension: Independent Compliance, Springs, at Suspension: Shock Absorber: Big Car Damping Suspension: Auxiliary Roll Moment: Linear 384 N Suspension: Jounce and Rebound Stops: +60 m Suspension: Shock Absorber: Big Car Damping Suspension: Shock Absorber: Big Car Damping Suspension: Jounce and Rebound Stops: +60 m Suspension: Jounce and Rebound Stops: +60 m Suspension: Jounce and Rebound Stops: +60 m Suspension: Spring: 153 N/mm Suspension: Independent System Kinematics: D-C Suspension: Dive Angle (Caster Change): Front { Suspension: Longitudinal Position: Front Strut - L Suspension: Camber Angle: Front Strut - Camber 	Shows links the data se							
- Suspension: Lateral Position: Front Strut - Lateral - Suspension: Toe Angle: Front Strut - Toe Change			☑ Overlay animations and plots with other runs					
 Suspension: Dive Angle (Caster Change): Front ! Suspension: Longitudinal Position: Front Strut - L Suspension: Camber Angle: Front Strut - Camber Suspension: Lateral Position: Front Strut - Lateral Suspension: Toe Angle: Front Strut - Toe Change 		To Po	Crosswind, Low Mu w/o ESC {No dataset selected} {No dataset selected}					
Animator: Shape Assembly: Euro Sedan Tire Animator: Shape File Link: Euro. Sedan Tire Animator: Shape File Link: Euro. Sedan Wilegel	Car <i>Sim</i> Mechanical Simulation	D-Class, Sedan w/ Aero Forces	{No dataset selected} {No dataset selected} View Echo file with initial conditions					
Expand All Collapse Refresh New Tree		{D-Class}						

Document the Run

Make it easy to document history and purpose of runs



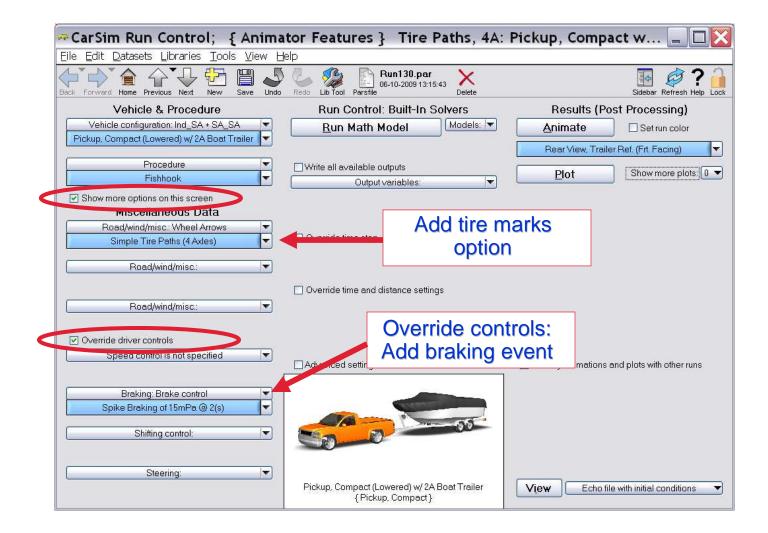
Protecting Data

- Encryption prevents vehicle data from being visible
- Complete data sets or sub-sets can be encrypted
- Encrypted components can be replaced with substitute data sets

	files } Encr 📮 🗆 🔀					
Eile Edit Datasets Libraries Tools View Help						
Back Forward Home Previous Next New Save Undo Redo Lib Tool Parsfile	4.par 09 13:57:42 X Iso 20 Constant Sidebar Refresh Help Lock					
Vehicle & Procedure Run Control: Built-In Solvers Results (Post Processing)						
Vehicle configuration: Ind_Ind Run Math Model Models	Animate Set run color					
GT, Rear Engine Encrypted	210 deg. Azimuth (Close), Veh. Ref.					
	Plot Show more plots: 0 -					
Show more options on this screen						
	Overlay animations and plots with other runs					
Car <i>Sim</i>						
Mechanical Simulation	View All data sent to solver or animator 🔻					

Override Controls

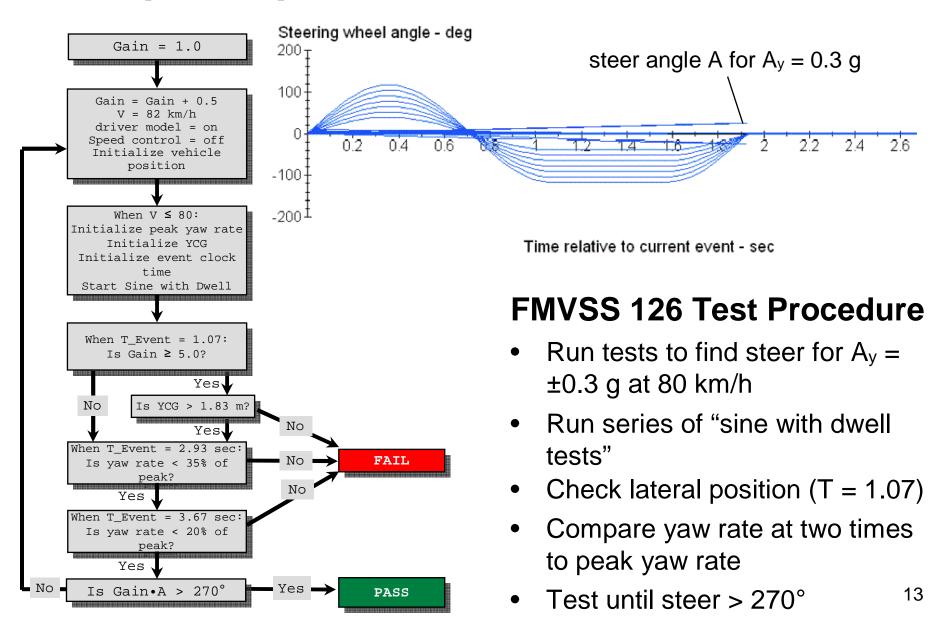
Make it easy to add options and override controls at top level

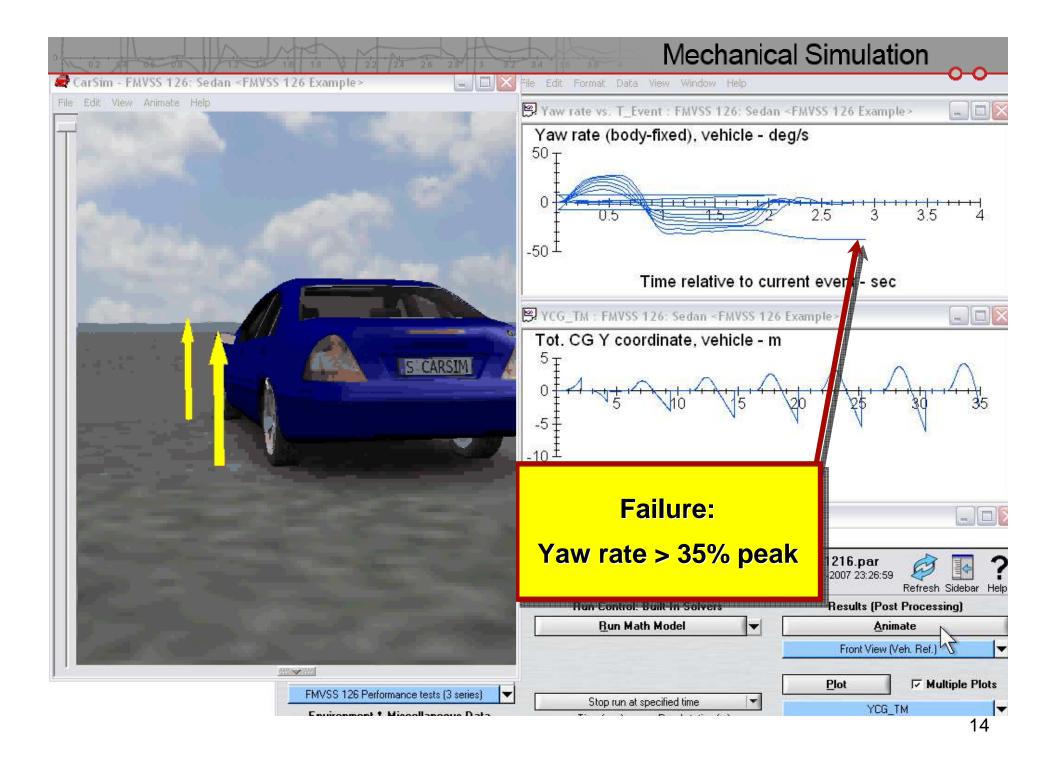


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Mechanical Simulation

Set Up Complex Test Procedures





Mechanical Simulation

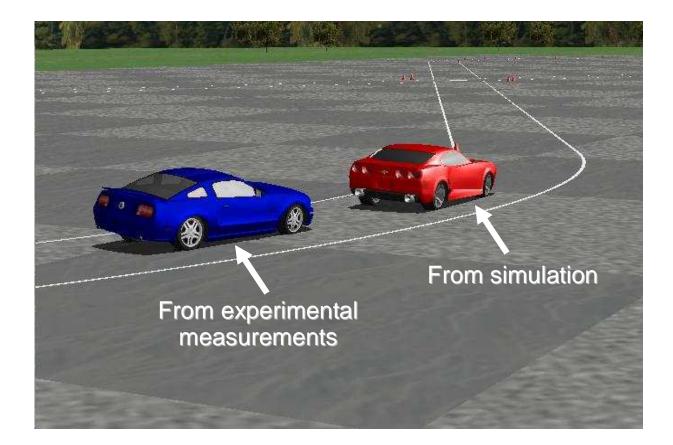
Overlay Runs

 Overlay other simulation runs or experimental test results in animations and plots

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Back Forward Home Previous Next	New Save Undo Redo Lib Tool Parsfile		Sidebar Refresh Help Lock				
Notes Linked Data	Vehicle & Procedure	Run Control with Simulink	Results (Post Processing)				
This example illustrates the improvement in vehicle stability achieved with Electronic Stabiliy Control (ESC) in high crossswinds on a low mu	Vehicle configuration: Ind_Ind D-Class, Sedan w/ Aero Forces Procedure	Run Now Send to Simulink Models: ESC Control	Animate Set run color Rear View High, Road Ref. (Frt. Facing)				
surface.		Write all available outputs	Plot Show more plots: 0 🔻				
The crosswind fans produce 100km/h wind from the right side, then the left side.	Show more options on this screen	Number of live animators for this run:					
The steering is controlled closed-loop, with the driver steering to keep the car on its path. For this run, the vehicle is equipped with ESC.		ck to overlay ther results					
The aerodynamic forces are displayed as single-headed arrows, located at the aerodynamic reference point. The center of pressure is not generally located at the			Overlay animations and plots with other runs Crosswind, Low Mu w/o ESC				
reference point, so aerodynamic moments		(Est					
complete the description of			{No dataset selected}				
aerodynamic effects. (Forces at the center of pressure are			{No dataset selected}				
replaced with forces at the reference point and			{No dataset selected}				
appropriate moments.) The moments are displayed as	Car <i>Sim</i>		{No dataset selected}				
double-headed arrows located Save Bevert	Mechanical Simulation	D-Class, Sedan w/ Aero Forces {D-Class}	View Echo file with initial conditions				

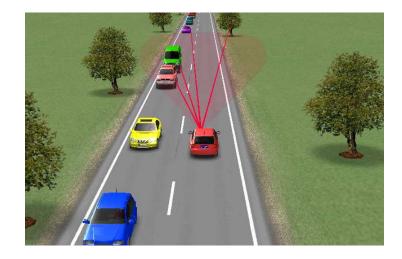
Example Animation Overlay

- Performance of the Mustang was measured on the test track
- Performance of the Camaro was simulated with CarSim

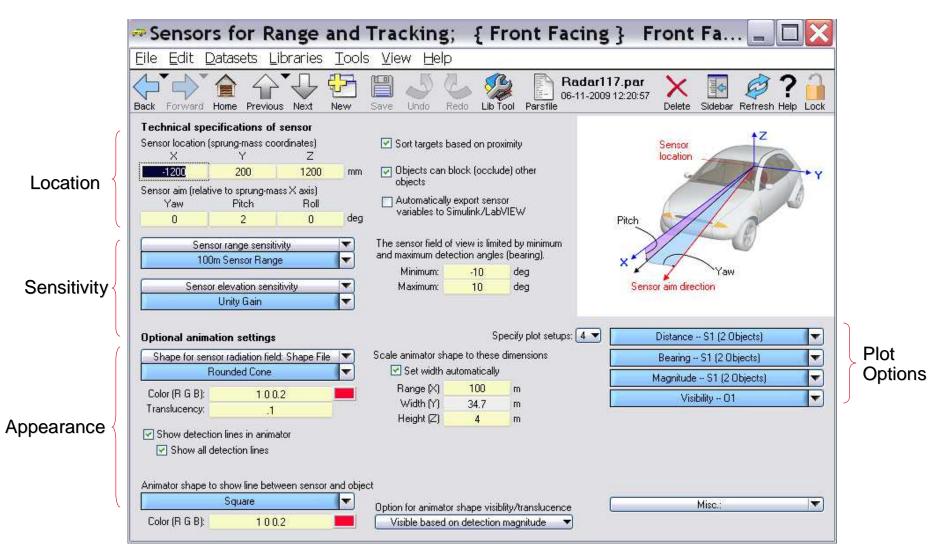


Sensors and Traffic

- Sensors and traffic are created at runtime with VS Commands
- Up to 20 sensors
 - Properties: location, orientation, field of view, sensitivity
- Up to 99 stationary or moving objects
 - Properties: current location and motion variables
 - Motion variables can be computed internally or imported from other software
- Sensors report out 10 variables for each detected object
 - Used internally: e.g., for animations
 - Can be exported to other software

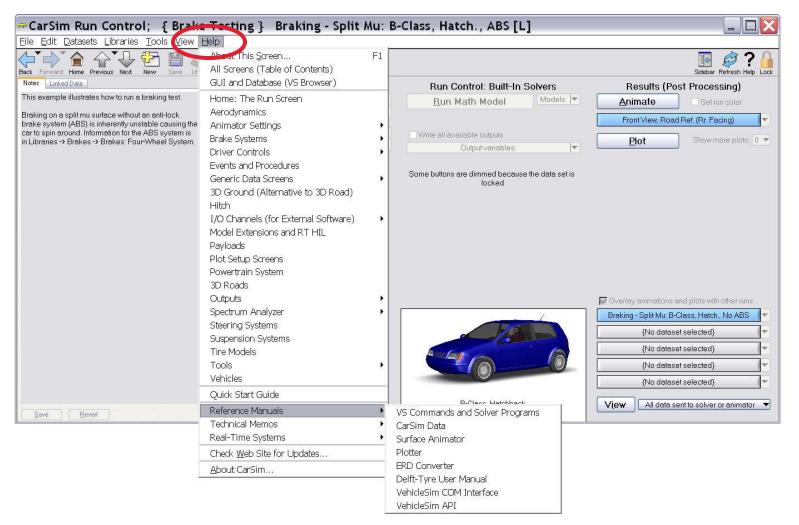


Sensor Description



Help Resources

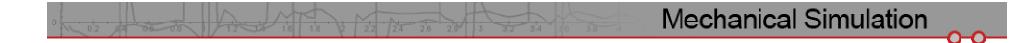
- Right click on any screen variable definition and name
- "Help" menu accesses complete documentation from the Run screen



Help Resources

- "View" options access run information and documentation of variables
- E-mail for technical help at "tech@carsim.com"

🗝 CarSim Run Control; { * CS 8.0 Traffic and Sensors } Simple Traffic Definition 📃 🗖 🔀								
Eile Edit Datasets Libraries Tools View Help								
Back Forward Home Previous Next New	Sidebar Refresh Help Lock							
Notes Linked Data	Vehicle & Procedure	Run Control: Built-In Solvers	Results (Post Processing)					
This example shows how to add traffic vehicles to	Vehicle configuration: Ind_Ind	<u>R</u> un Math Model Models V	Animate Set run color					
a simulation.	B-Class, Sports Car (Hard Top)		RR View, Veh. Ref., (Frt. Facing)					
	Procedure	Write all available outputs	Plot Show more plots: 0 V					
	Traffic Loop	Output variables:	Plot Show more plots: 0 -					
	Show more options on this screen							
			Echo file with initial conditions					
			Echo file with final conditions All data sent to solver or animator 					
			Log file of parsfiles and events					
			Simulation results (Excel)					
	1]	Overlay Simulation results (Matlab)					
			ERD header file					
			Multibody model description Imports into math model (text)					
		6	Imports into math model (Excel)					
			Outputs from math model (text)					
	Car <i>Sim</i>		Outputs from math model (Excel)					
		D Class Course Cos (Used Top)	Parameters in math model (Excel)					
Save Bevert	Mechanical Simulation	B-Class, Sports Car (Hard Top) { CS B-Class }	View Al data sent to solver or animator					



Thank You

For more information: Visit Booth 5100 www.carsim.com