

Mechatronic Test Concepts for Vehicle Dynamics Controllers



Thomas Gockeln

dSPACE GmbH · Technologiepark 25 · 33100 Paderborn

Stuttgart · 17.06.09

- World's leading provider of solutions for developing ECU software and mechatronic controls
- dSPACE worldwide
 - Headquarters in Paderborn, Germany
 - Subsidiaries in the USA, France, the UK, and Japan; Representative Office in China
 - Distributors in 9 other countries
- 55% of sales are in exports
- Over 800 employees worldwide



Location Paderborn – Headquarters

- Development
- Administration
- Engineering
- Sales

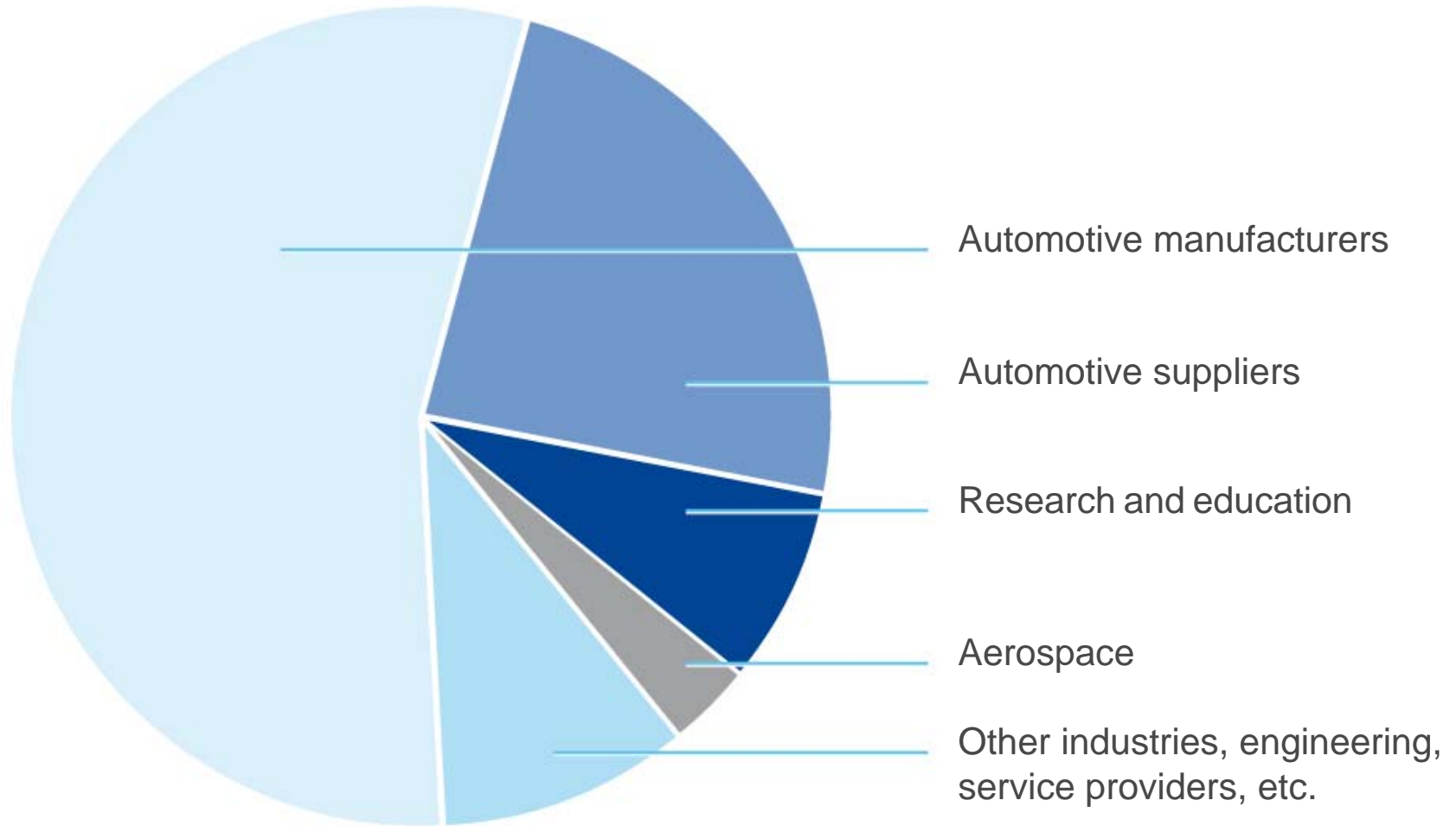
Location Pfaffenhofen/Munich

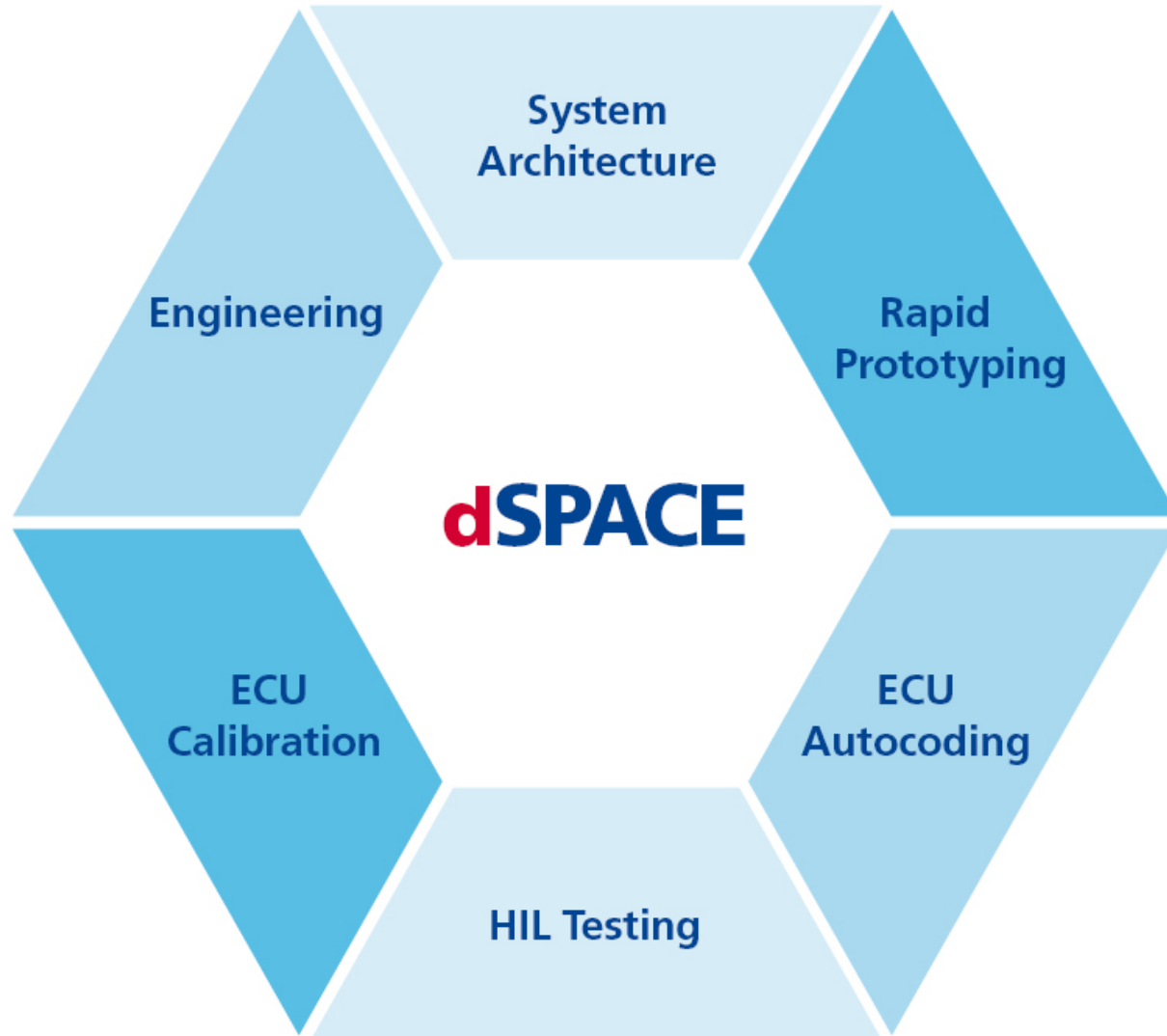
- Engineering
- Sales

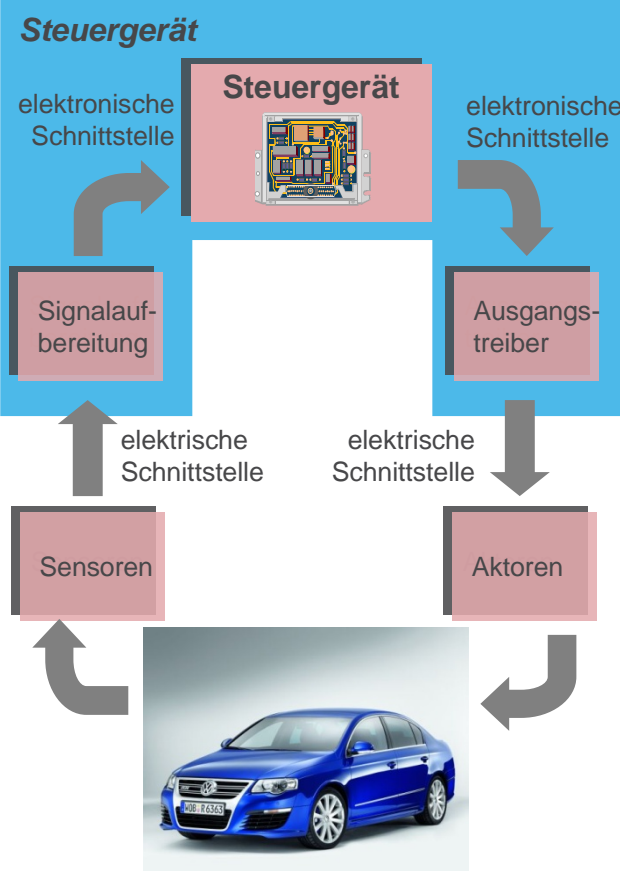
Location Holzgerlingen/Stuttgart

- Engineering
- Sales

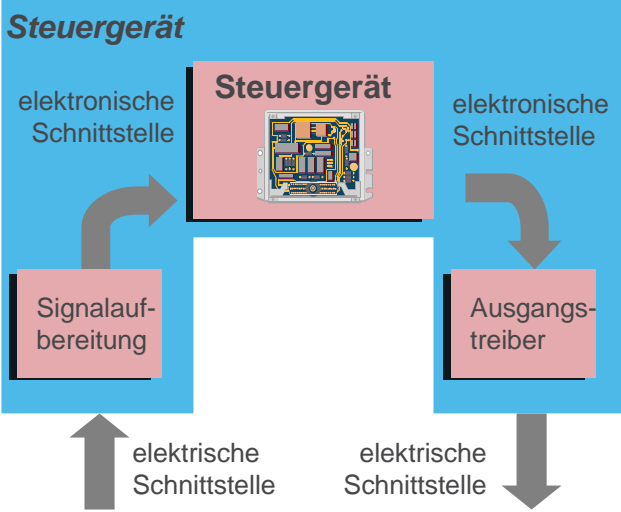








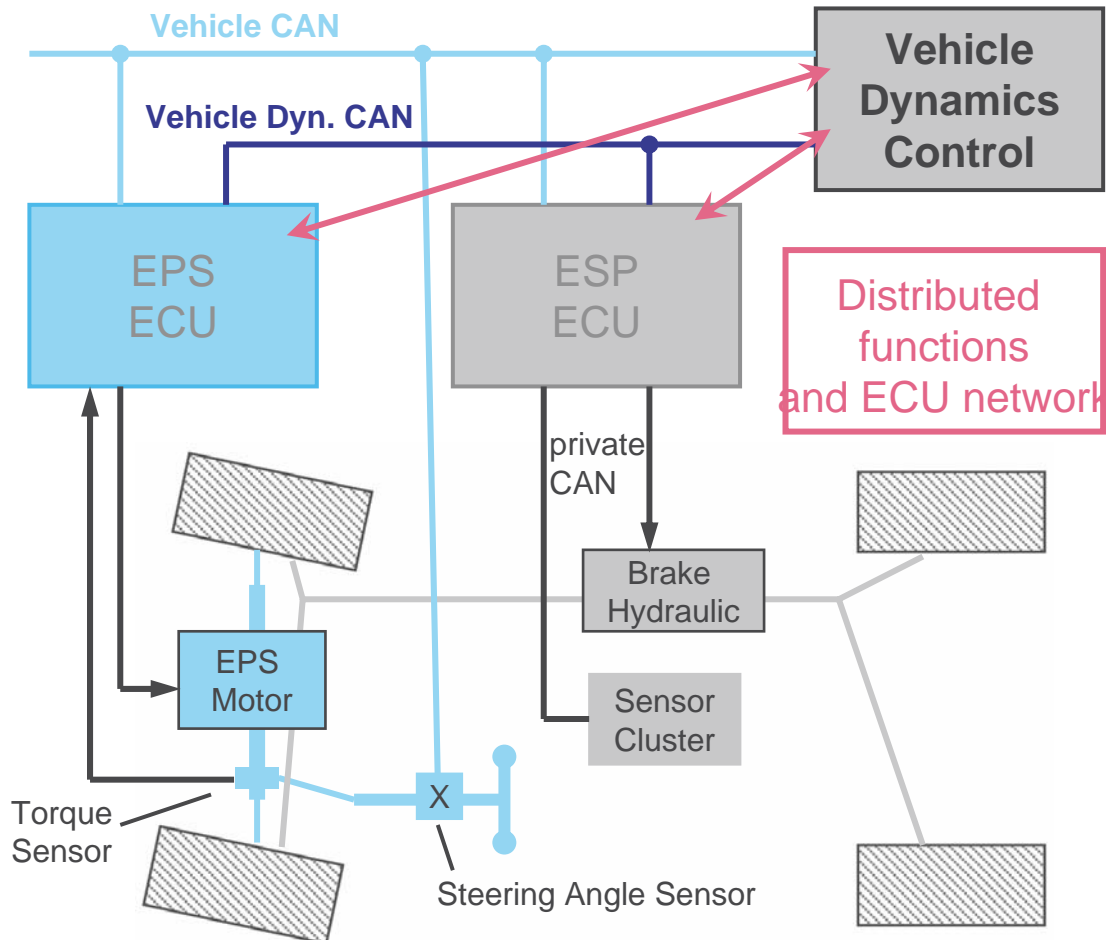
Reale Fahrzeugumgebung



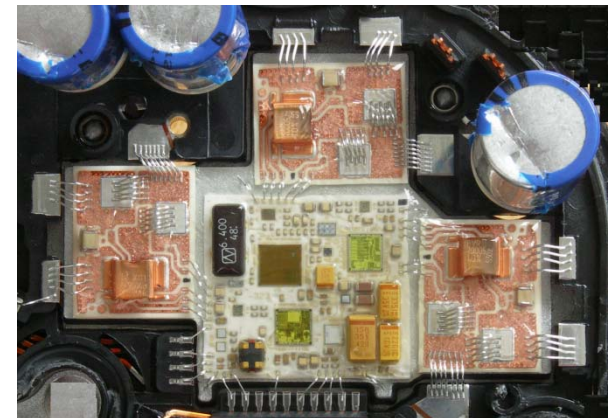
Simulierte Fahrzeugumgebung

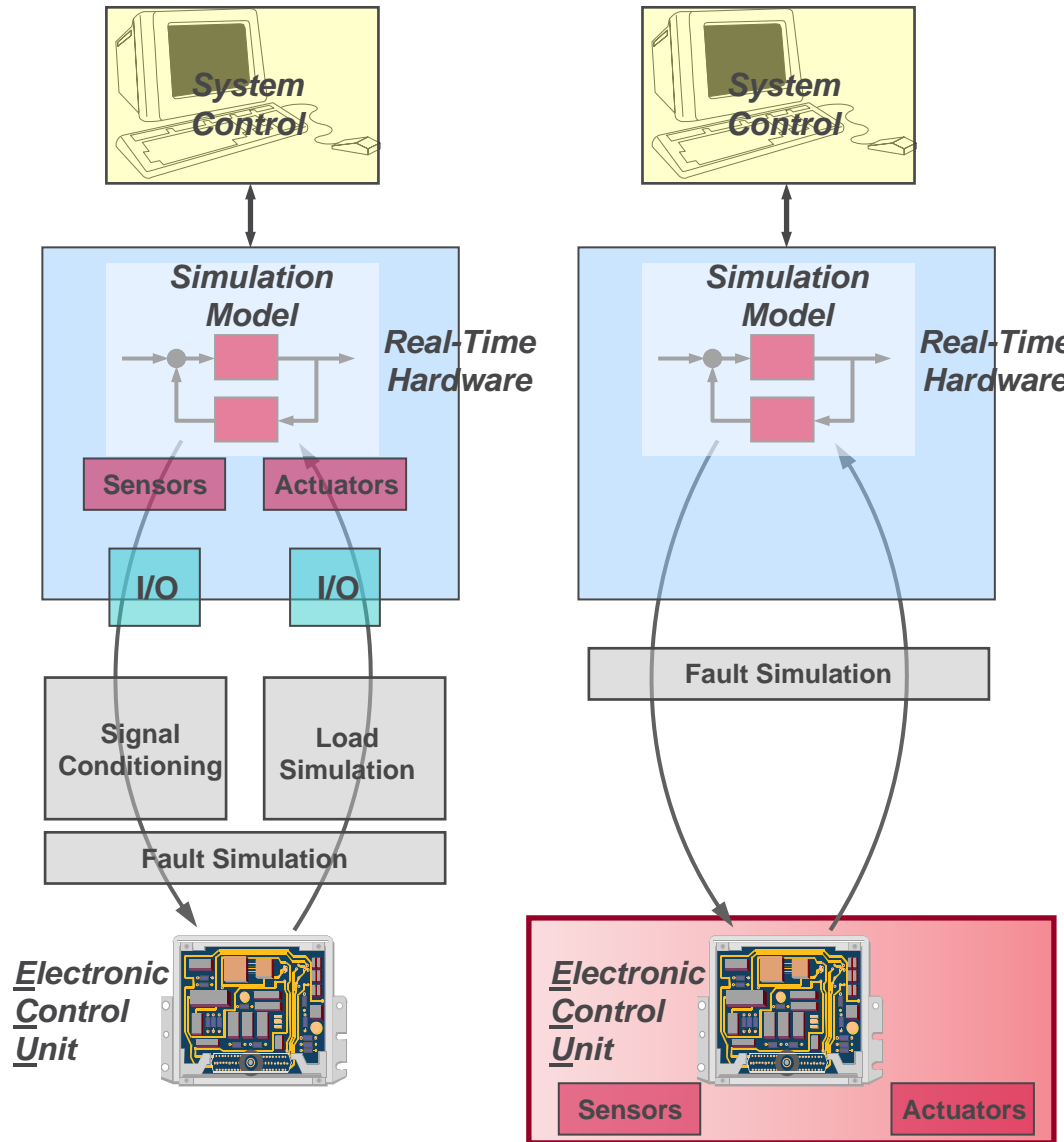


ECU network for Vehicle Dynamics (example structure):



- Distributed functions, ECU network
 - Safety critical functions
→ comprehensive testing
 - Very high hardware integration level:
 - ECUs and systems come mainly from suppliers
- **simulation on power level (electrical or mechanical)**



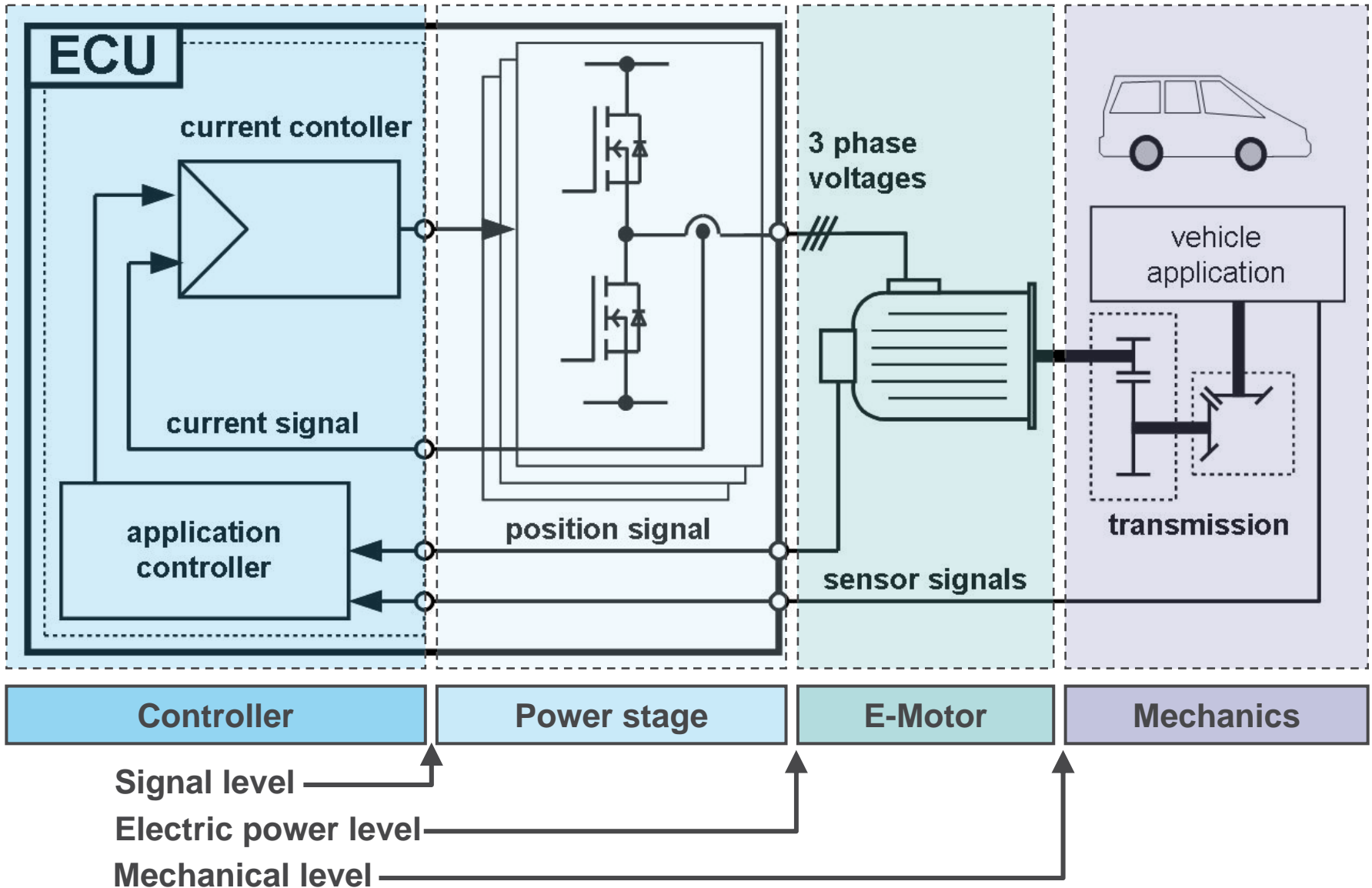


Standard Setup

Sensors and actuators are not part of the ECU

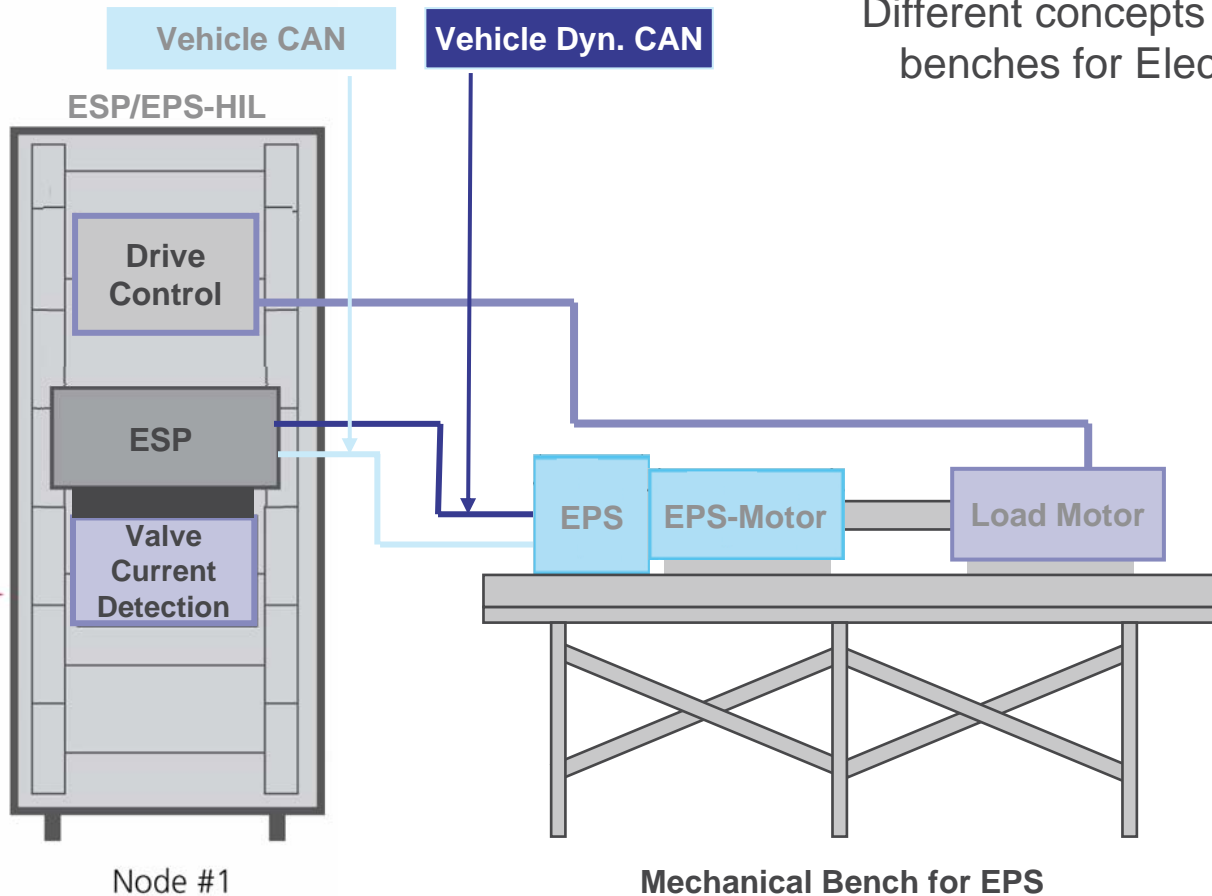
Mechatronic ECU

Sensors and actuators are internal components of the ECU



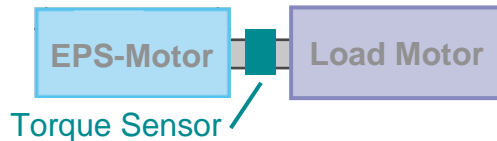
HIL Topology for Vehicle Dynamics HIL (alternative structure):

Different concepts are possible for mechanical benches for Electric Steering Systems



Different Types of Electric Steering Test Benches:

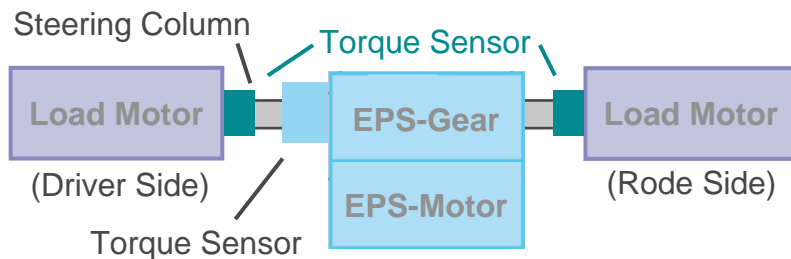
Single rotary motion load motor:



EPS Motor need to be separated from any gear

Torque Sensor need to be simulated
Additional measurement equipment possible

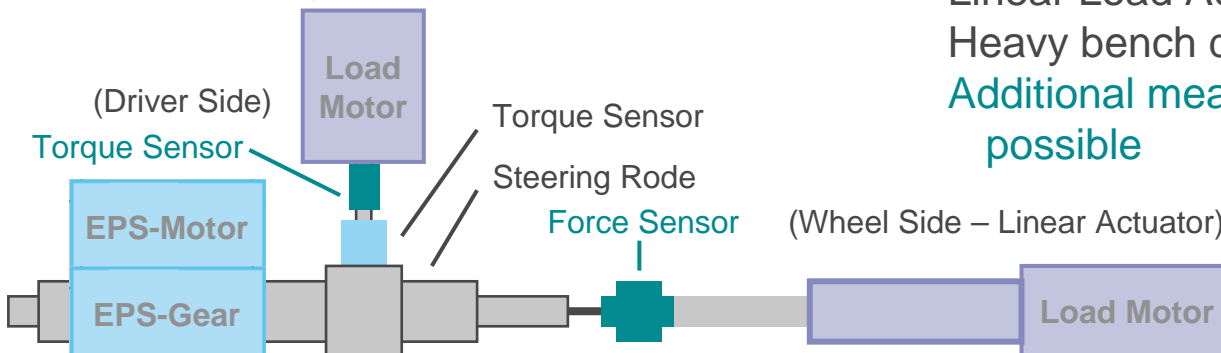
Double rotary motion load motors:



Only possible for column mounted EPS
Possible for AFS

Additional measurement equipment possible

Linear and rotary motion load motors:

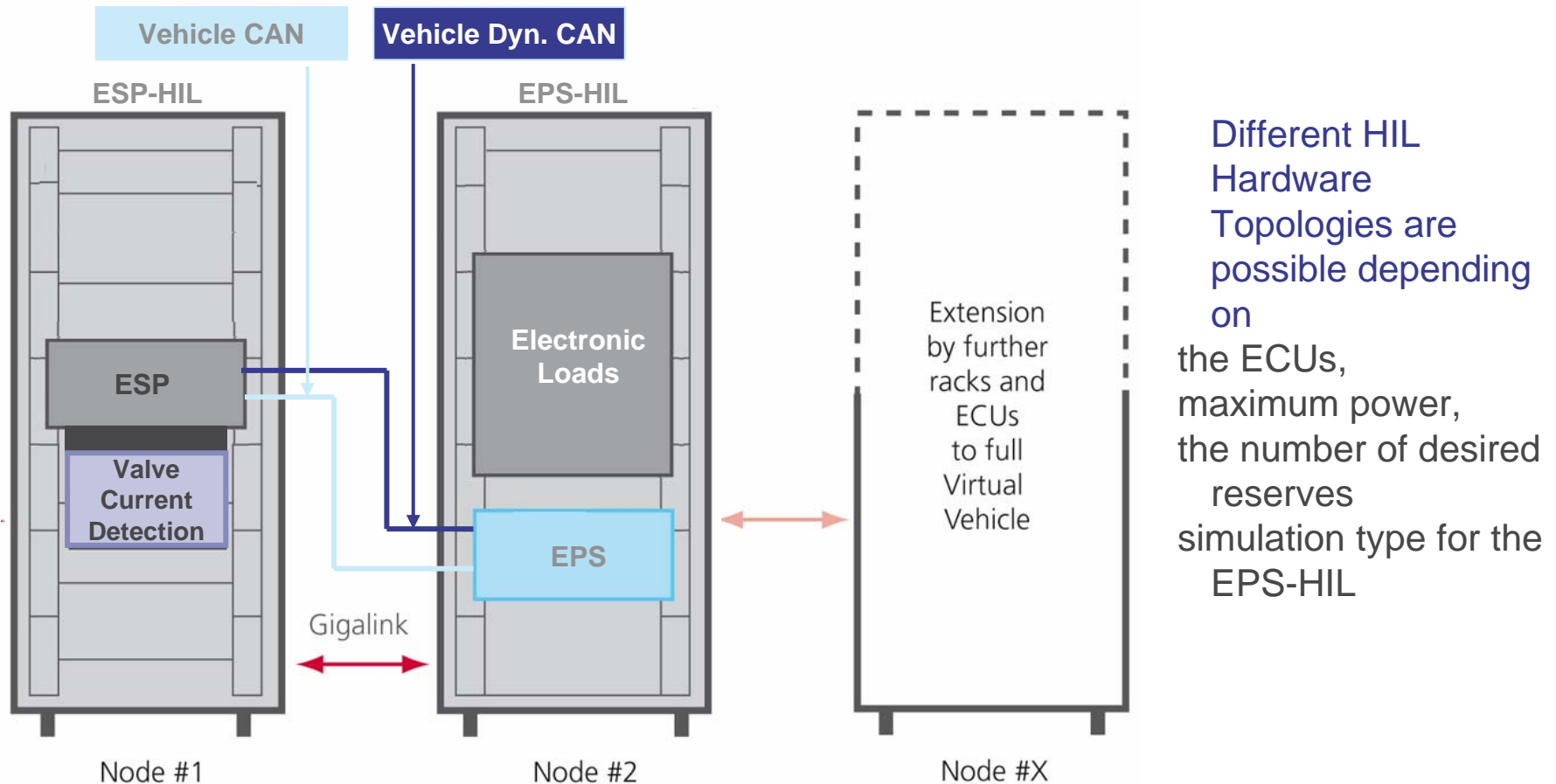


Linear Load Actuator

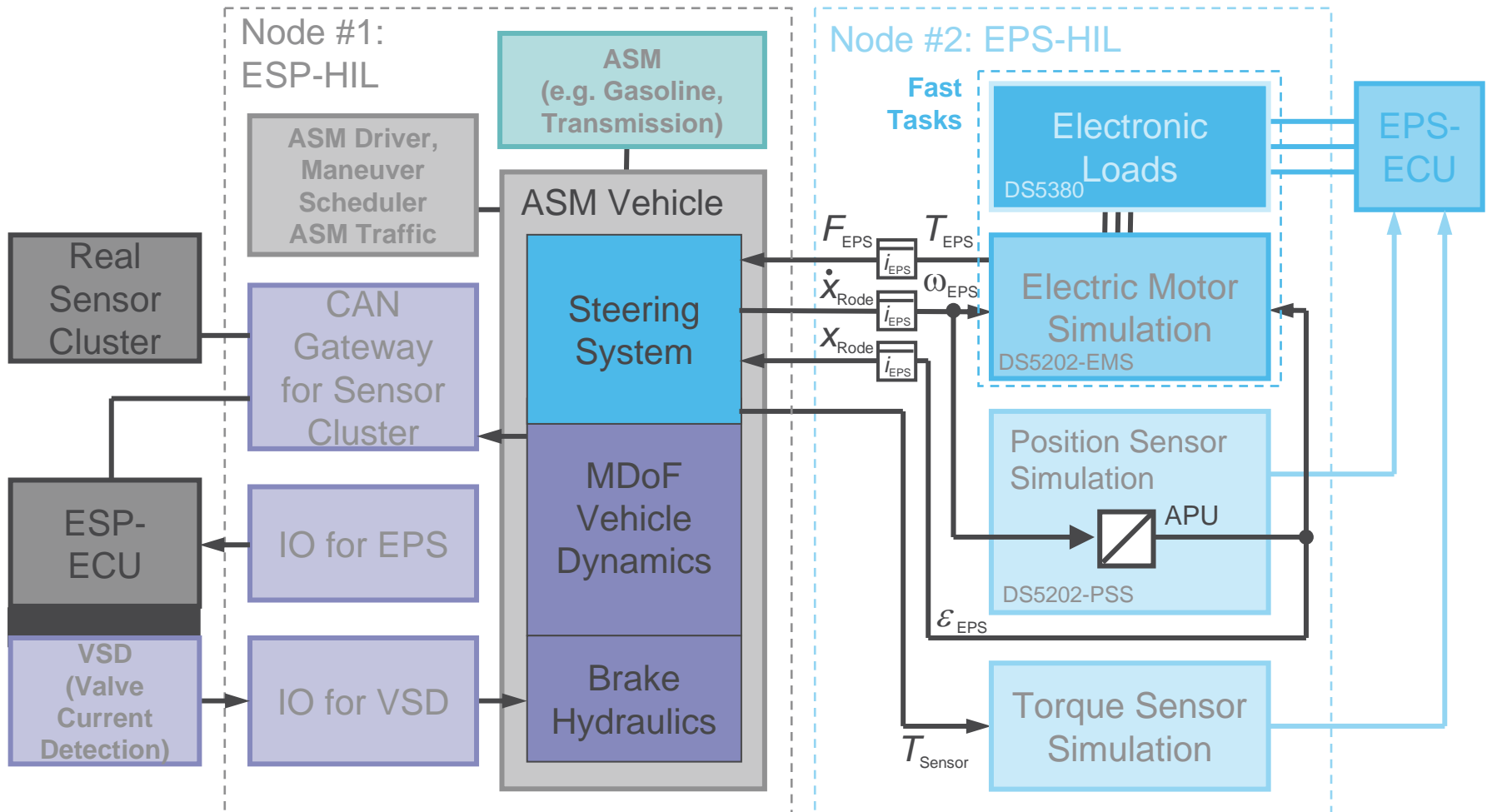
Heavy bench due to high forces (e.g. 20kN)

Additional measurement equipment possible

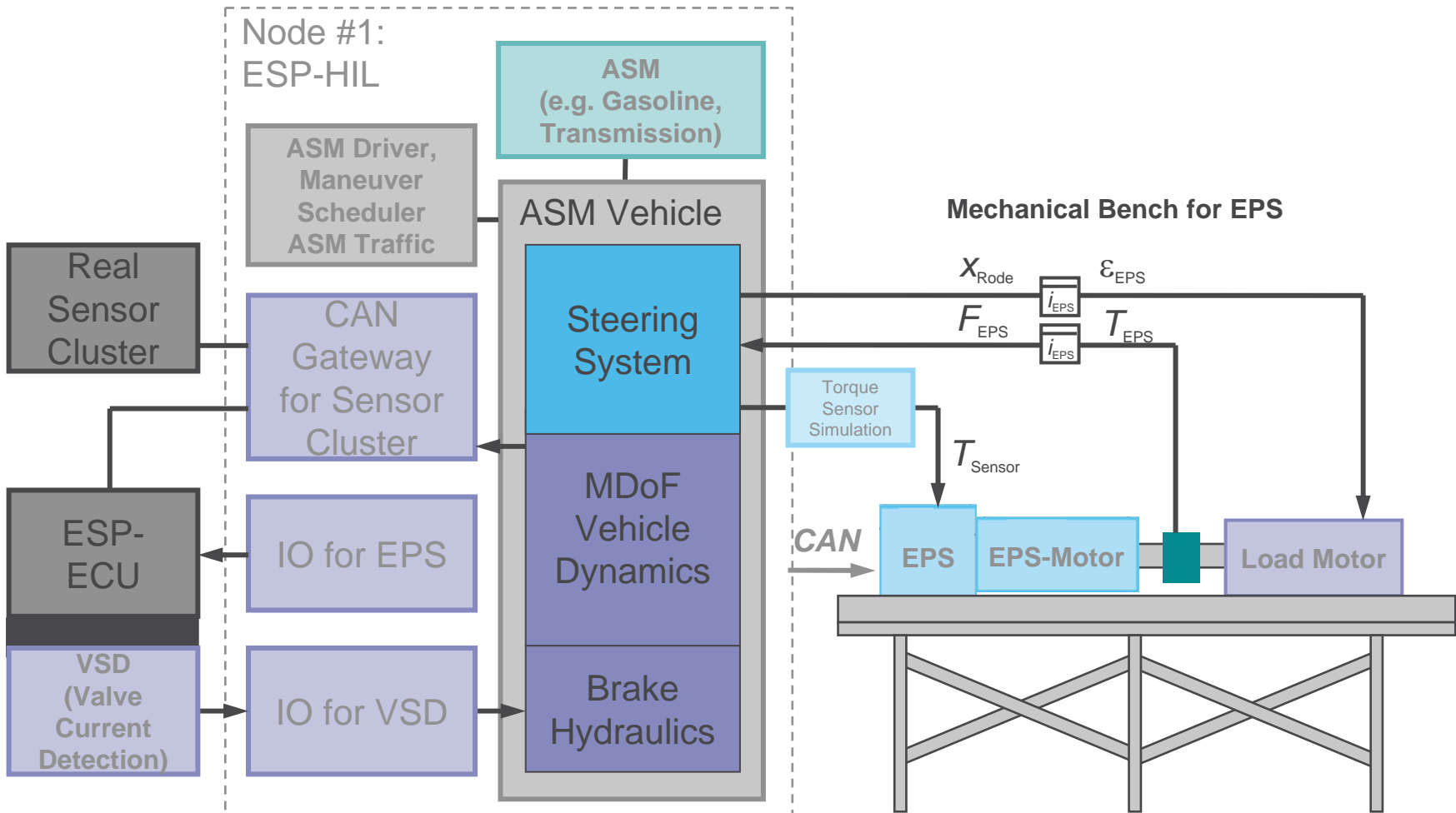
HIL Topology for Vehicle Dynamics HIL (example structure):



Overall integration of EPS electric motor simulation in the vehicle model:



Overall integration of EPS electric motor simulation in the vehicle model:



	Electric Power Level	Mechanical Level (simple bench)	Mechanical Level (heavy bench)
Pros	<p>Flexible (e.g. motor parameter)</p> <p>Full access to the model</p> <p>No safety restrictions</p>	<p>Little knowledge of ECU and electric motor required</p>	<p>Little knowledge of ECU and electric motor required</p> <p>Testing of mechanical parts is possible</p>
Contras	<p>Knowledge of motor characteristics and electric diagnostic functions</p>	<p>Inflexible</p> <p>Testing deviation of motor parameters is impossible</p>	<p>Inflexible</p> <p>Testing deviation of motor parameters is impossible</p> <p>Safety restrictions (mechanics)</p>
Use Case	<p>Component, Diagnosis testing</p> <p>Integration testing of dynamic systems e.g., vehicle dynamics incorporating steering system and ESP or virtual vehicles</p>	<p>Component, Diagnosis testing</p> <p>Integration testing of dynamic systems e.g., vehicle dynamics incorporating steering system and ESP or virtual vehicles</p>	<p>Testing of the mechanical system</p> <p>Testing of entire steering system</p>

Thank you for your attention!



Thomas Gockeln

dSPACE GmbH · Technologiepark 25 · 33100 Paderborn

Stuttgart 17.06.09

Important Notice



© Copyright 2009, dSPACE GmbH

All rights reserved. Written permission is required for reproduction of all or parts of this publication. The source must be stated in any such reproduction.

This publication and the contents hereof are subject to change without notice. Brand names or product names are trademarks or registered trademarks of their respective companies or organizations.