



# CRUSADER

A full vehicle integration facility

**C**rossfunctional **u**nique **s**ystemtest **a**pproach **d**riven by **e**ntire **r**elationships

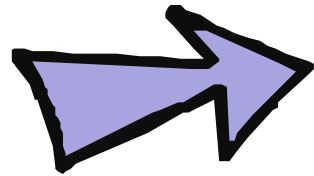
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# An innovative vehicle-in-the-loop test bench

## We're talking about....

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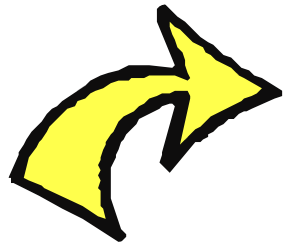
an Unique test bench

completely new test bench setup

Driven by Entire Relationships

from system point of view

simulate reality as close as possible  
(environment- and traffic simulation)



CRoss-functional testing

not only one local function:  
testing at whole system  
(vehicle level)

an innovative

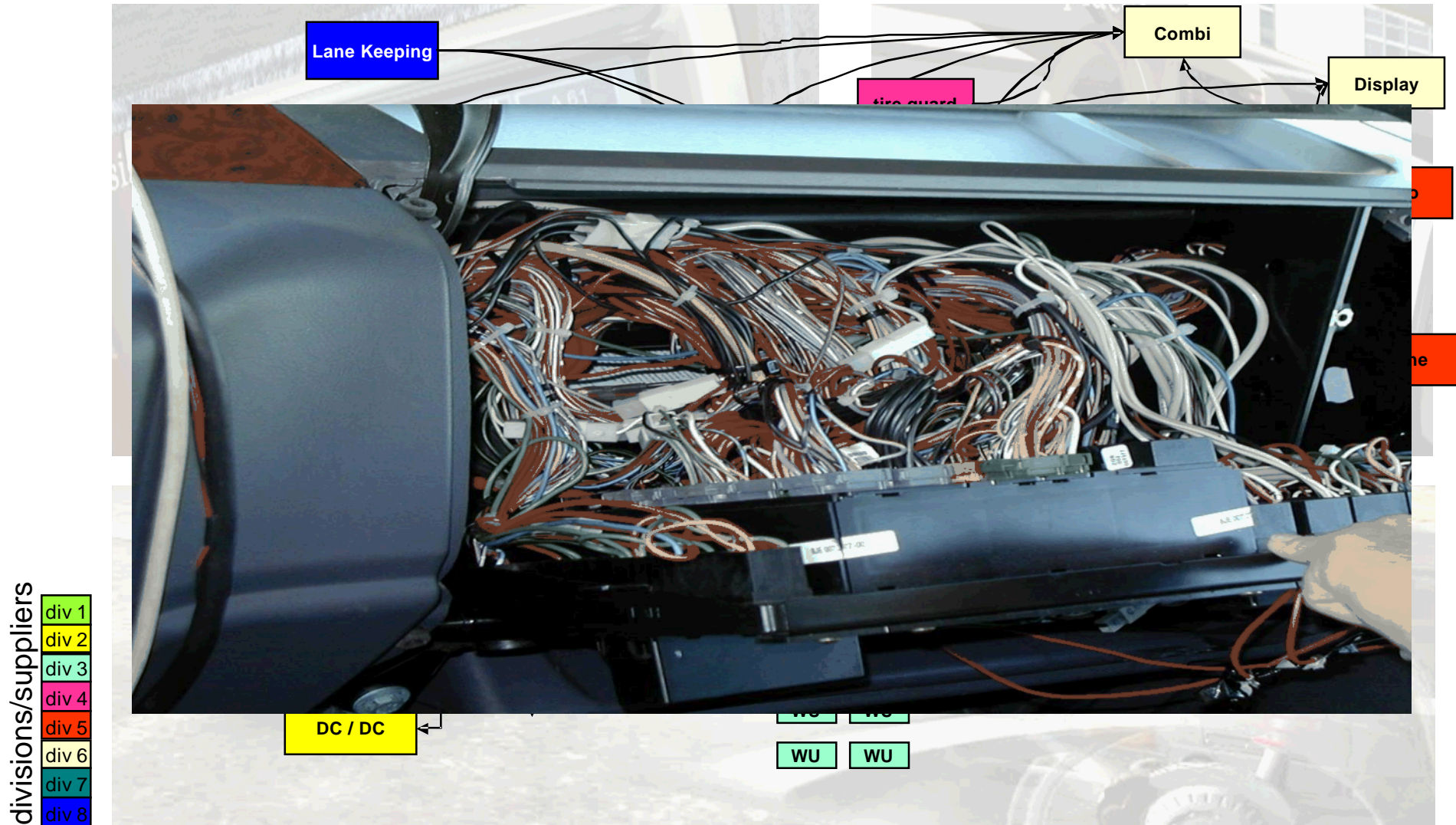
System test Approach

a new kind of system testing



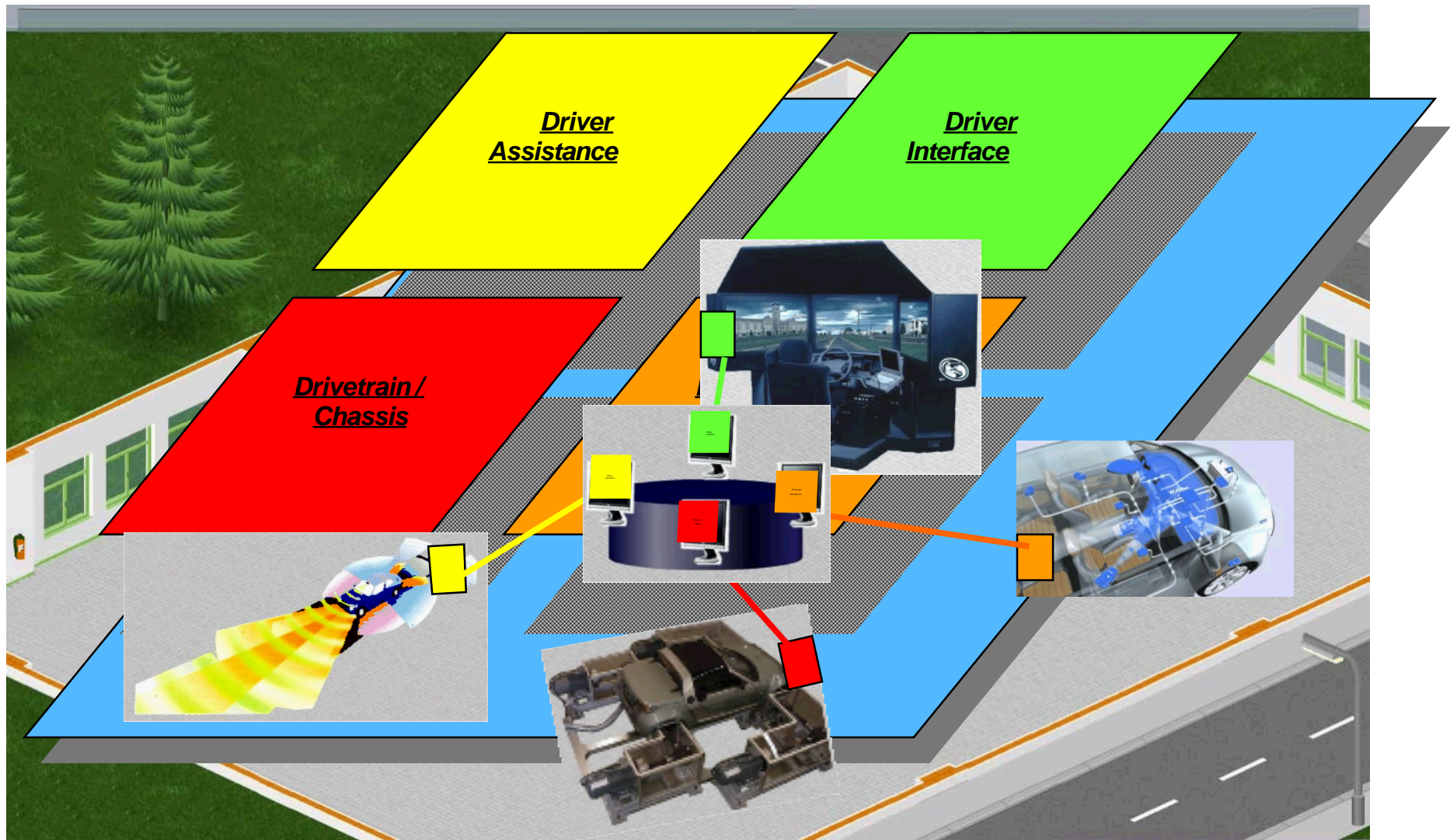
# Motivation

An ever increasing inter-dependability ... .. reaching the limits of integration



# Motivation

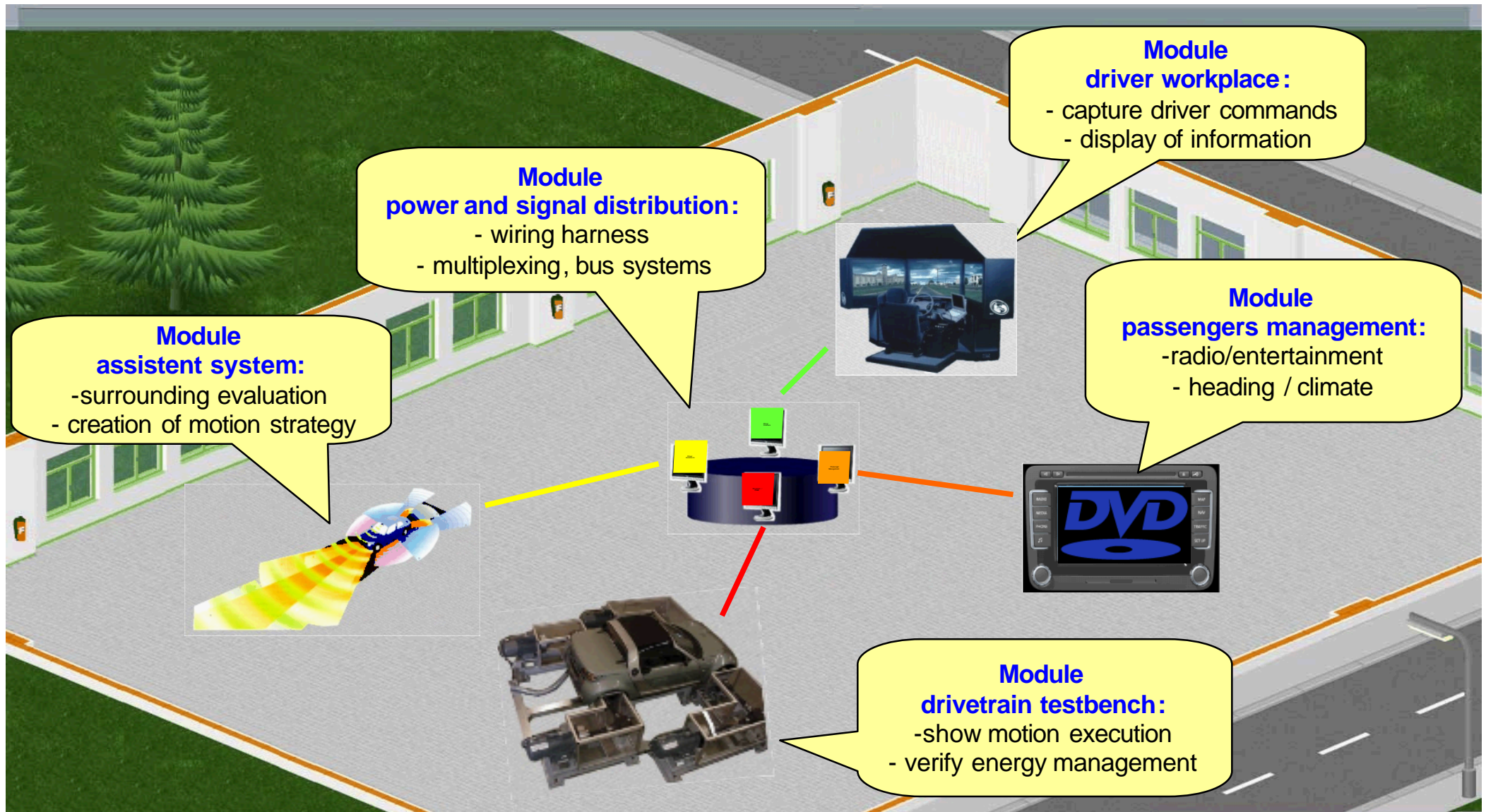
## New possibilities of integration on vehicle level





# Complete Vehicle Integration Facility CRUSADER

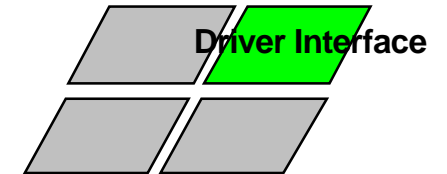
## The modular deployment



# Overview module: driver workplace

## A dynamic driving simulator

- ▶ six-degrees dynamic driving simulator platform
- ▶ VW Golf mockup mounted on top (original CAN and serial components)
- ▶ simulator and mockup controlled by traffic- and environment simulation
- ▶ visualisation of traffic in front of the windscreen (screen display)
- ▶ operation with a real driver (man-in-the-loop)



traffic  
simulation

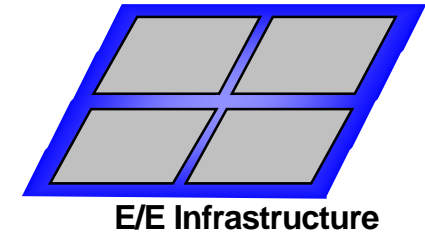
environment  
simulation



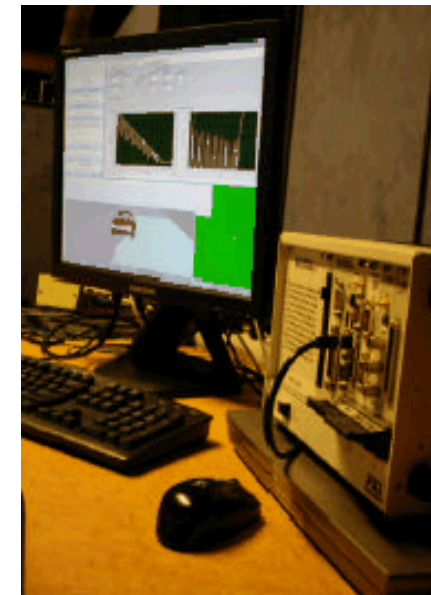
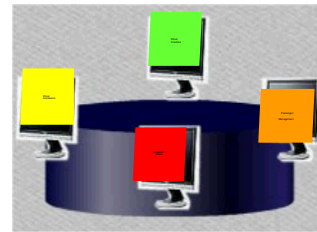
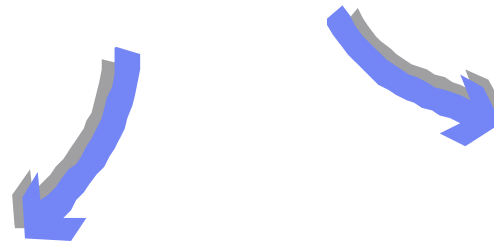
# Overview module: signal distribution, E/E infrastructure

## Visualization of the interfaces

- ▶ represents the E/E infrastructure of the whole test system
- ▶ has been realized by the inter-module connections itself (CAN, ethernet...)
- ▶ analyse data on the interfaces by means of using the suitable tooling
- ▶ optimize interfaces in terms of improving performance or reducing complexity



show dataflow of the interfaces:

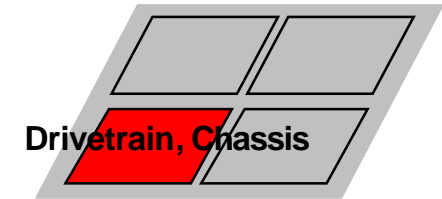




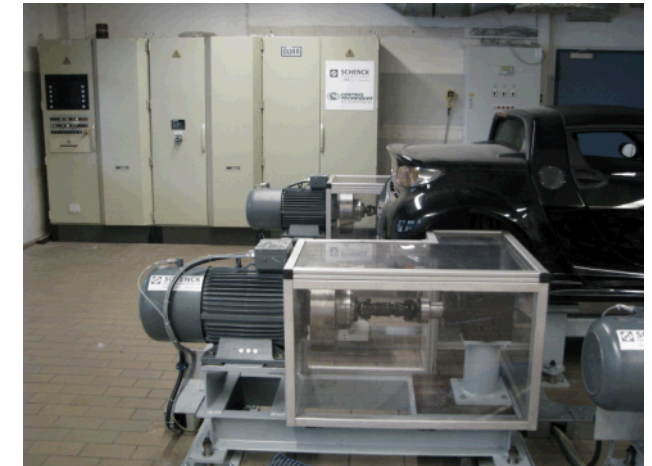
# Overview module: drivetrain/chassis

## Vehicle-in-the-loop testbench

- ▶ drivetrain testbench to verify the motion execution of the vehicle
- ▶ consists of 4 independently controllable electric motors (asynchronous)
- ▶ basically the torques on the wheels will be measured
- ▶ the corresponding counterforces will be provided



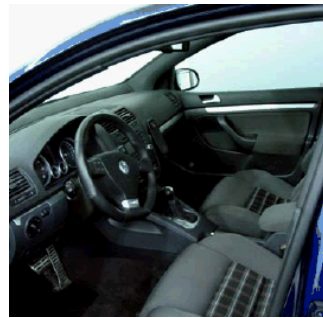
emulate all counter-forces  
which are originally active in reality  
(between wheel and road)





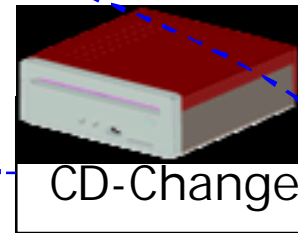
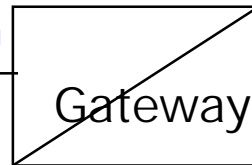
# Overview module: passengers management

## All tasks independent from driving



module 1: DWP

Infotainment CAN



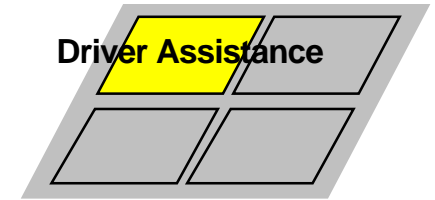
- ▶ multimedia system including navigation and map data
- ▶ surrounded by additional components

incorporate interior- and infotainment functionalities

# Overview module: assisting system

## Surrounding evaluation, simulation of sensor data

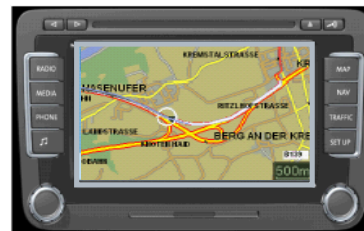
traffic scenario and environment simulation



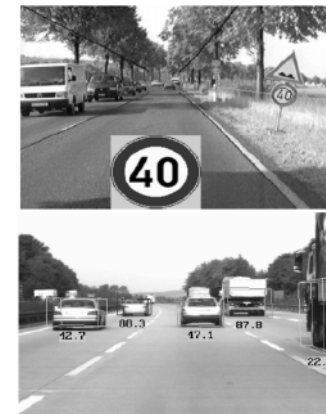
object data: distance, relative speed, dimensions of obstacles



- ▶ calculation of object data
- ▶ provision of route and map data
- ▶ injection of object data directly into CAN bus-system (bypass radar sensors)



eHorizon:  
navigation + map data

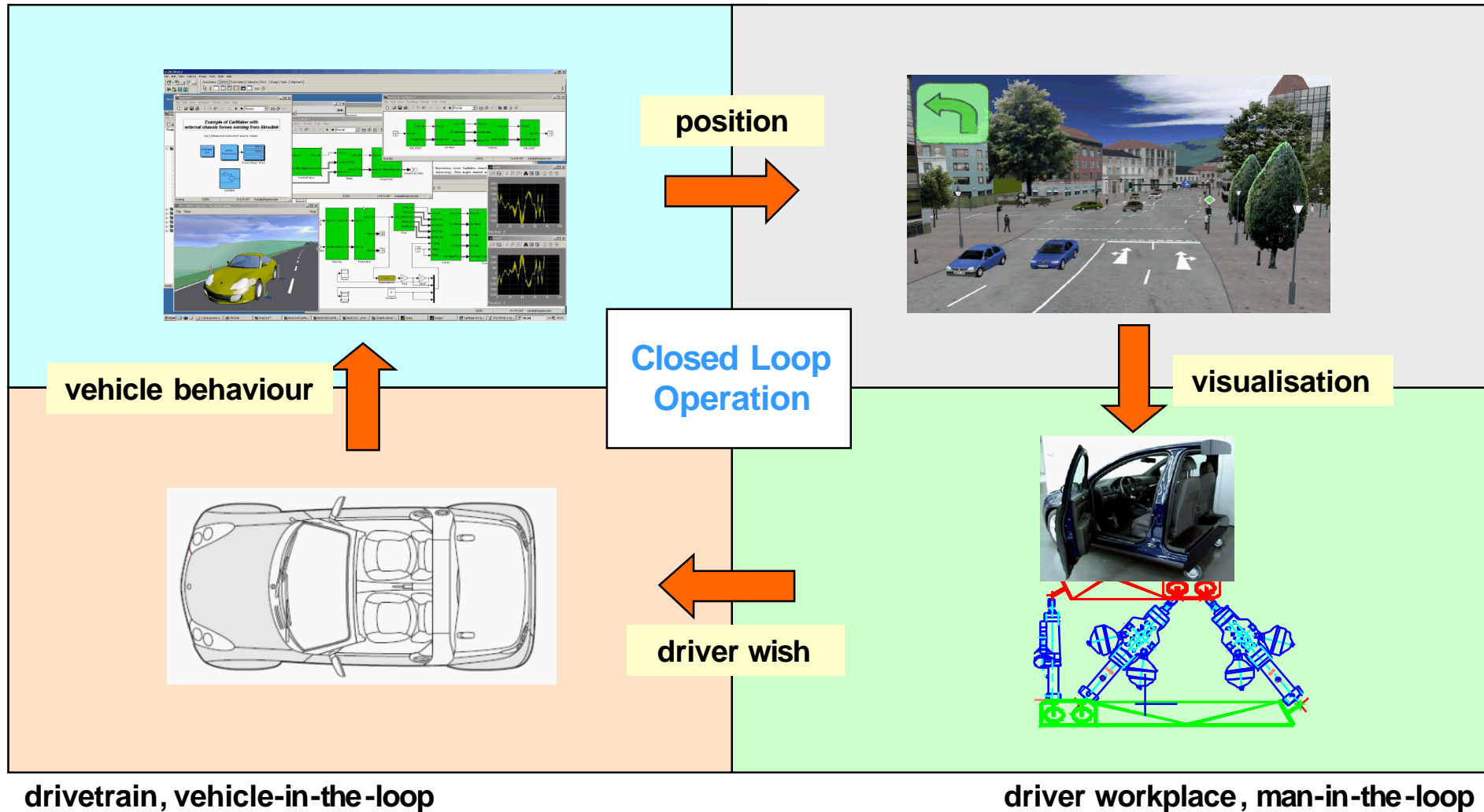


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## A closed loop testing, overview

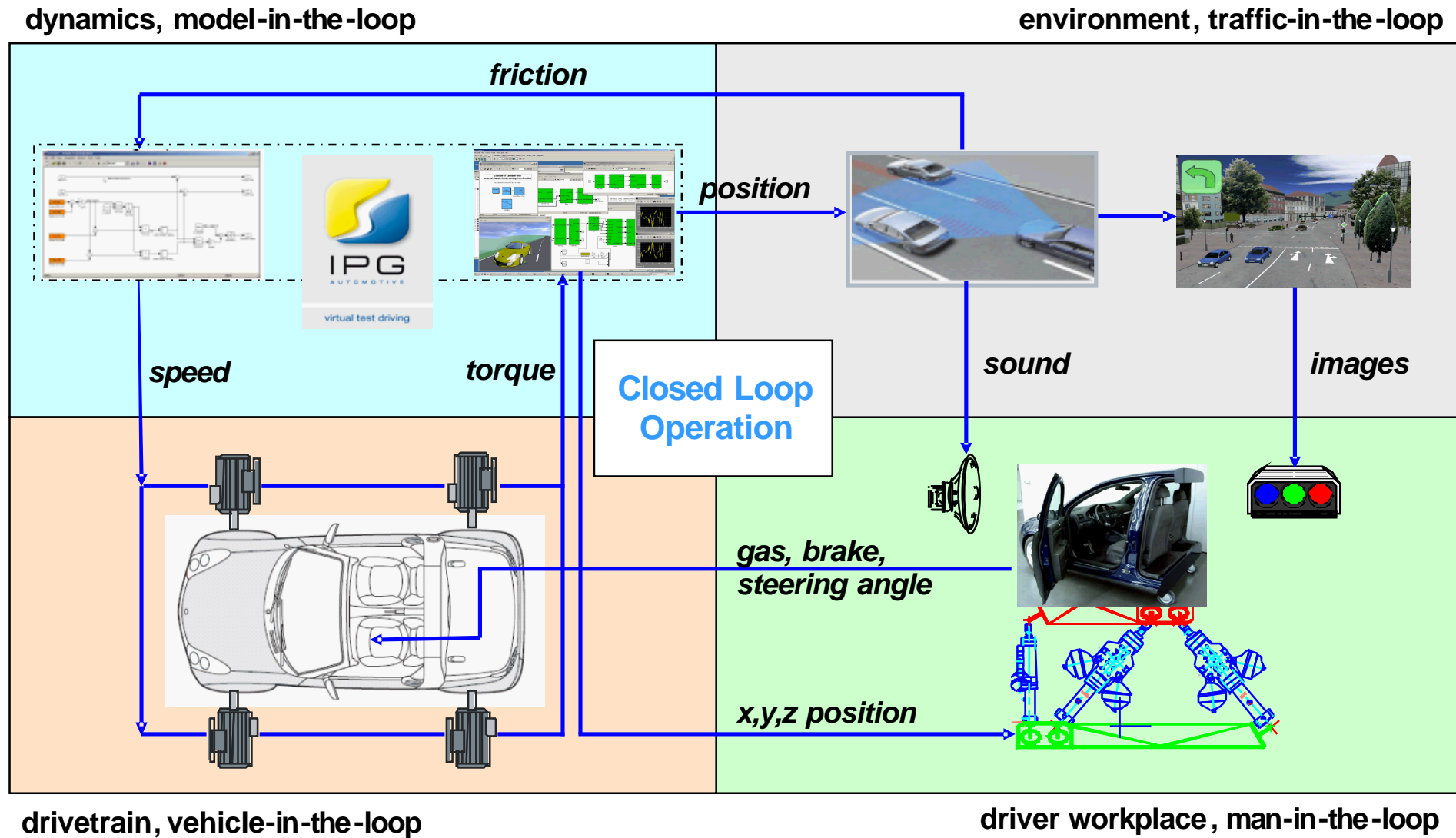
dynamics, model-in-the-loop

environment, traffic-in-the-loop



# CRUSADER

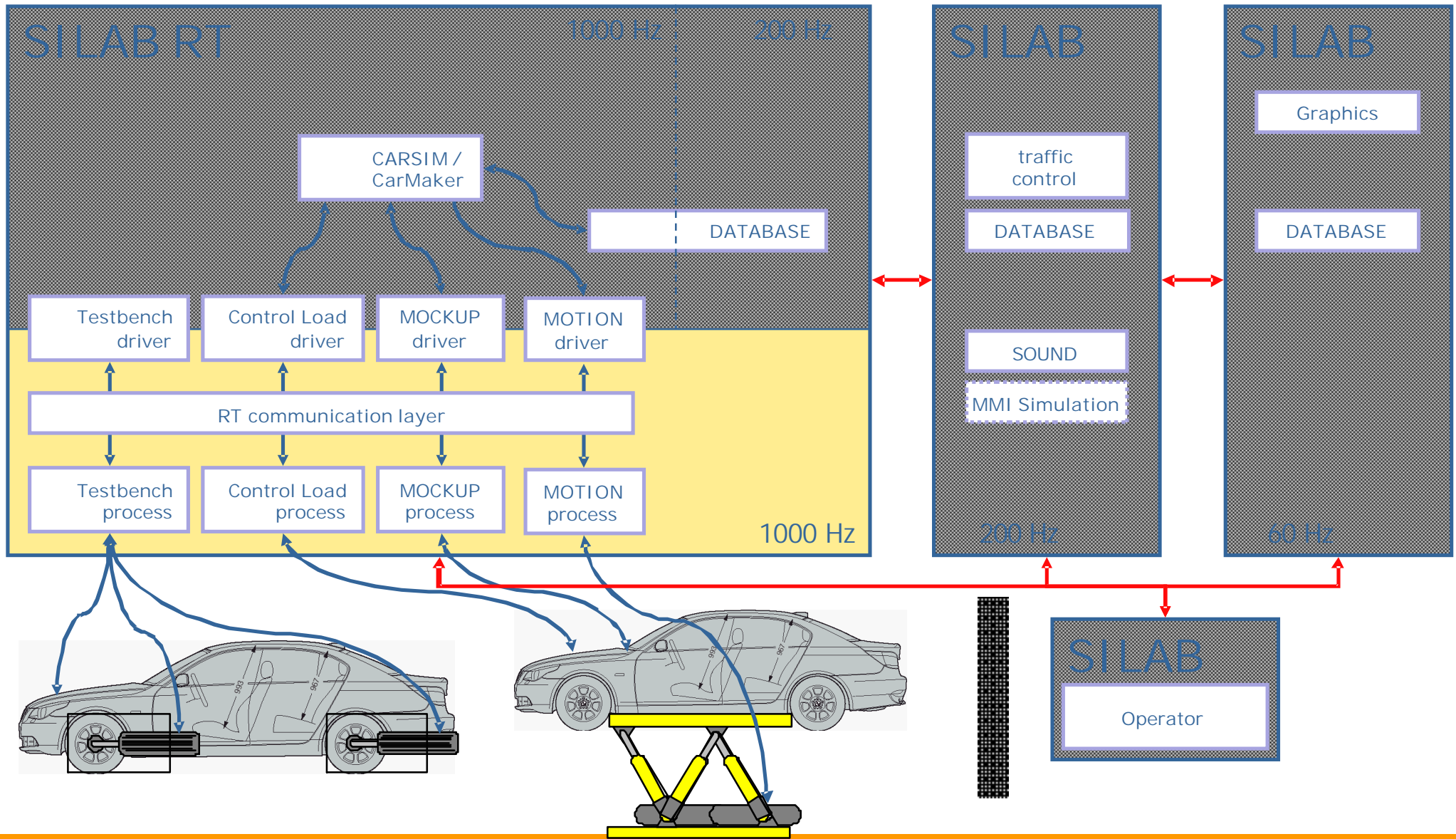
A closed loop testing, the basic principle...





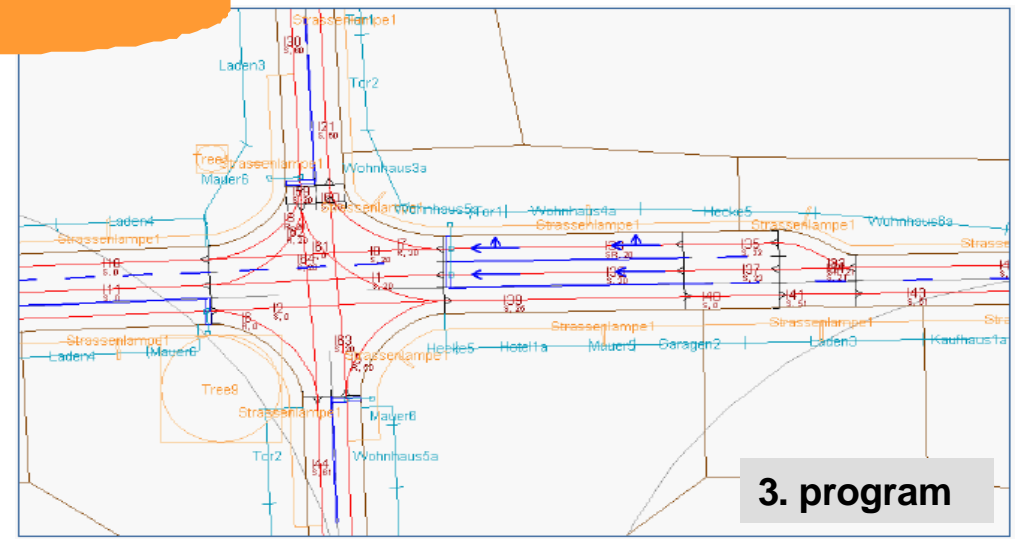
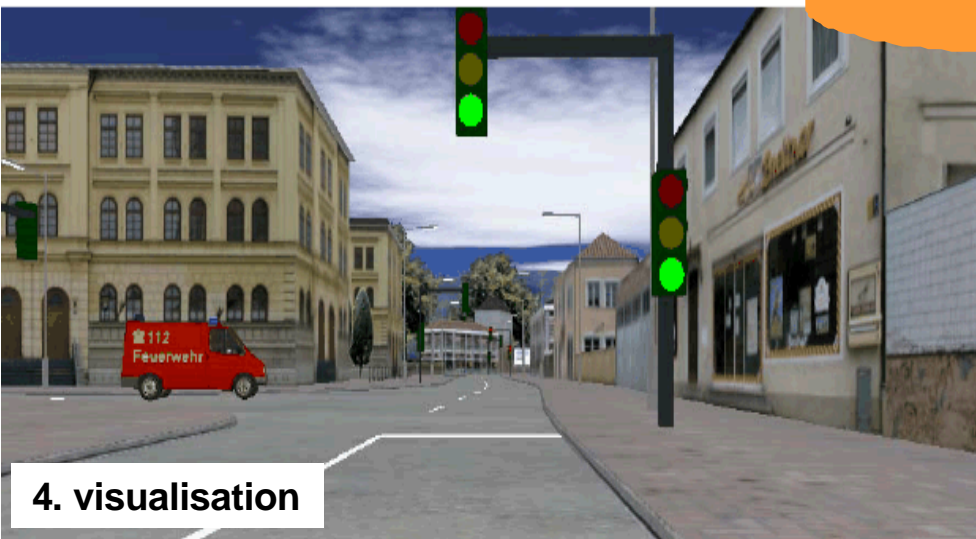
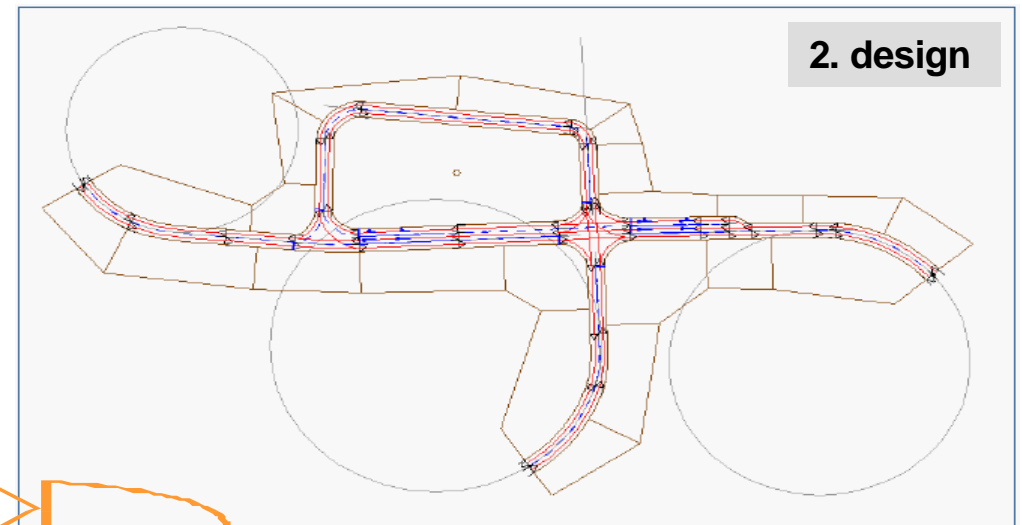
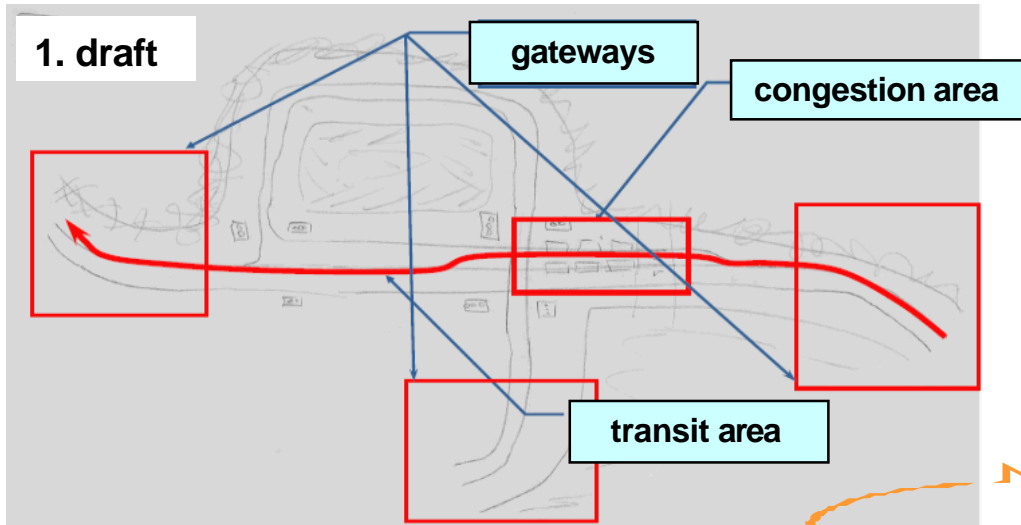
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## SILAB Real Time Approach, System architecture



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## SILAB traffic simulation, tool based development process





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## Pics CRUSADER components, Powertrain testcenter Regensburg, Germany

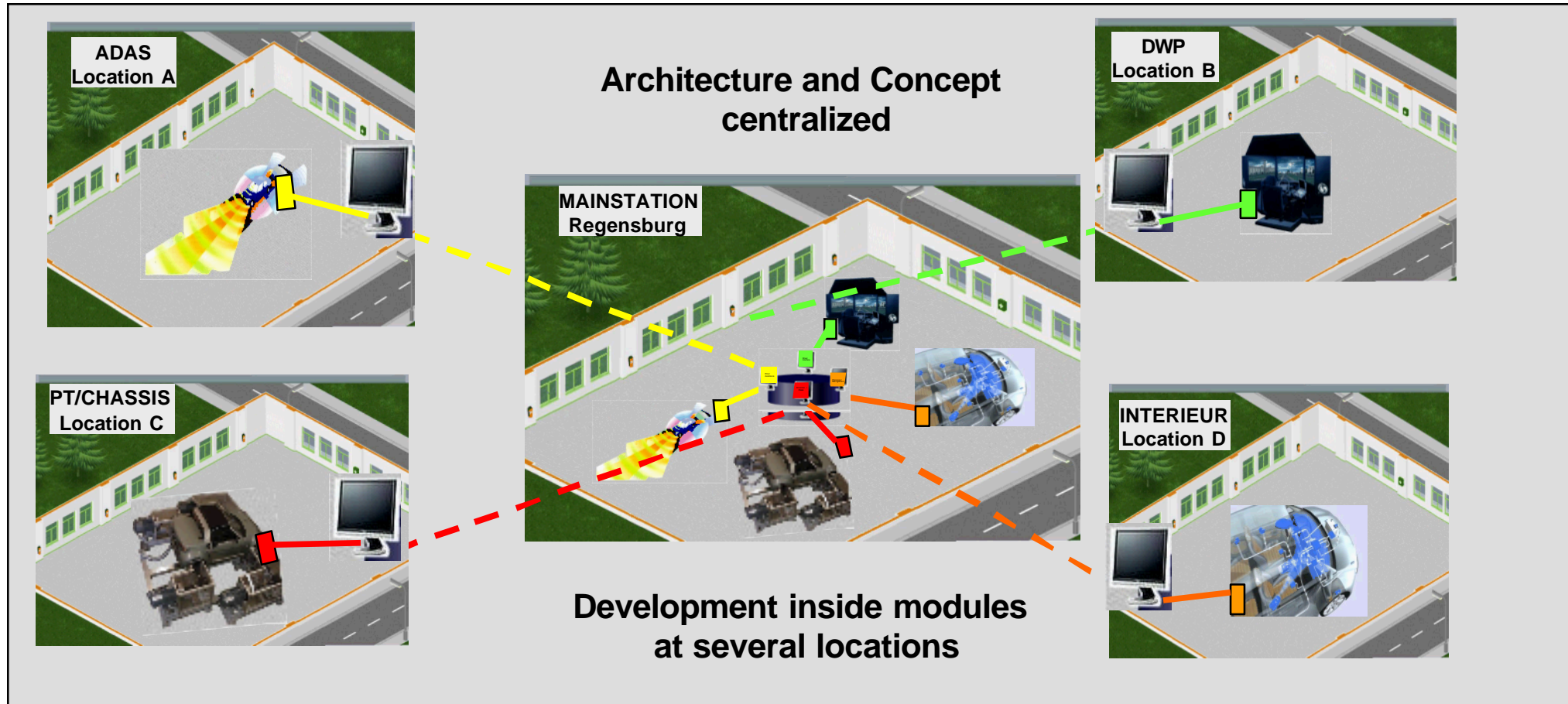


located at Regensburg,  
Siemensstrasse 12  
powertrain testcenter



# Complete Vehicle Integration Facility CRUSADER

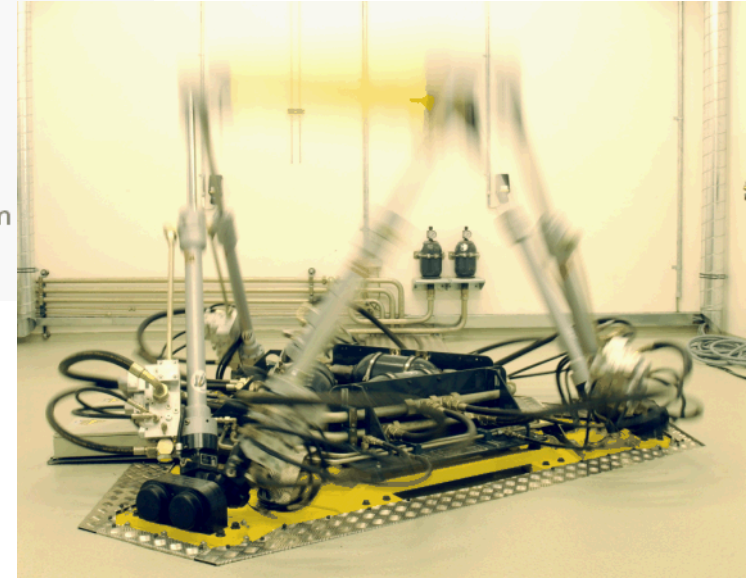
## The modular deployment in future





# Partners (1)

## Simtec Systems, Braunschweig, Germany



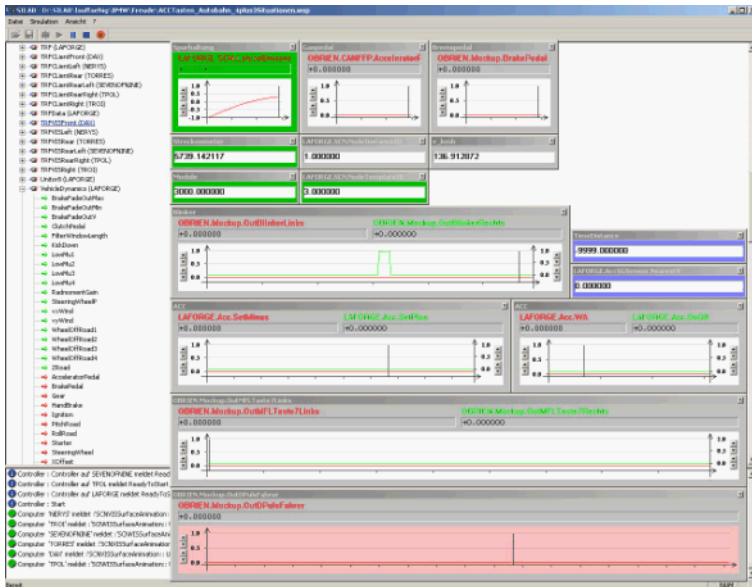
Realization of VW Golf mockup integration on dynamic driving simulator

Hall 1, Booth 1652, Mr. B.Kaufmann



# Partners (2)

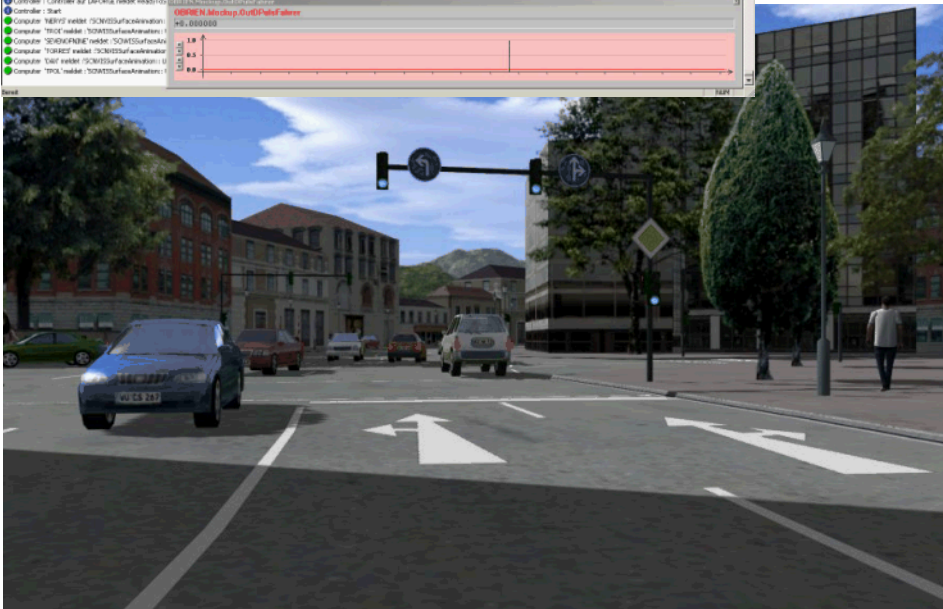
IZVW, Center for Traffic Sciences, Würzburg, Germany



Center for Traffic Sciences, Würzburg  
Methodology and Traffic Sciences, Prof. Dr. Krüger

## SILAB tooling:

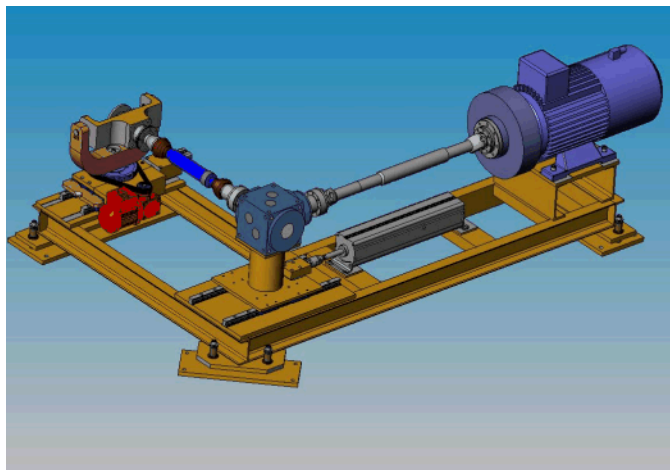
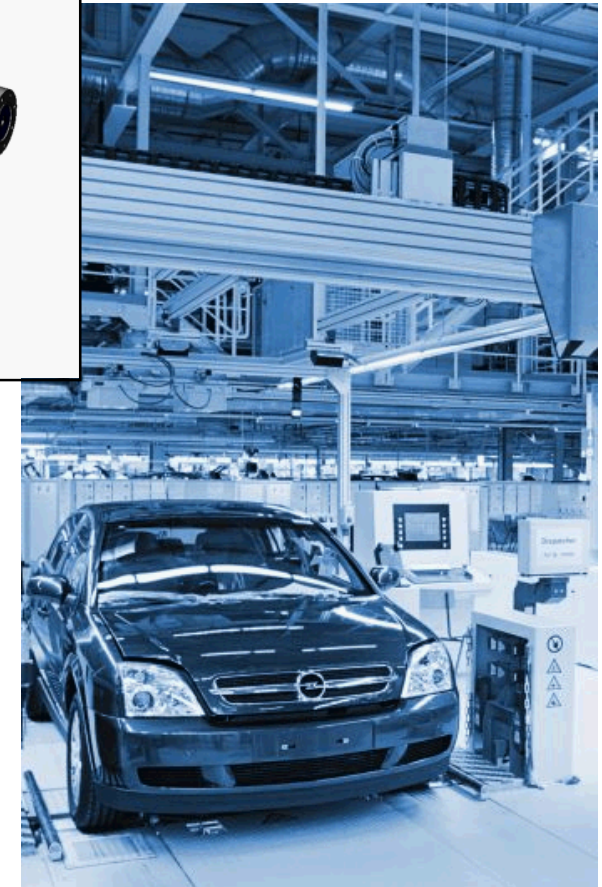
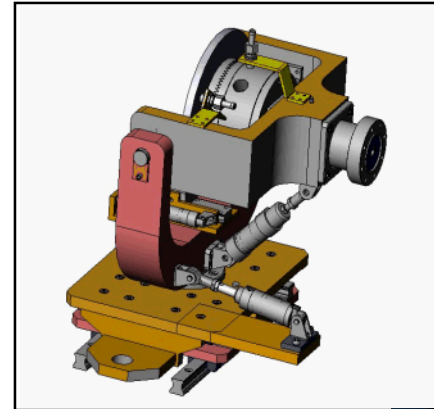
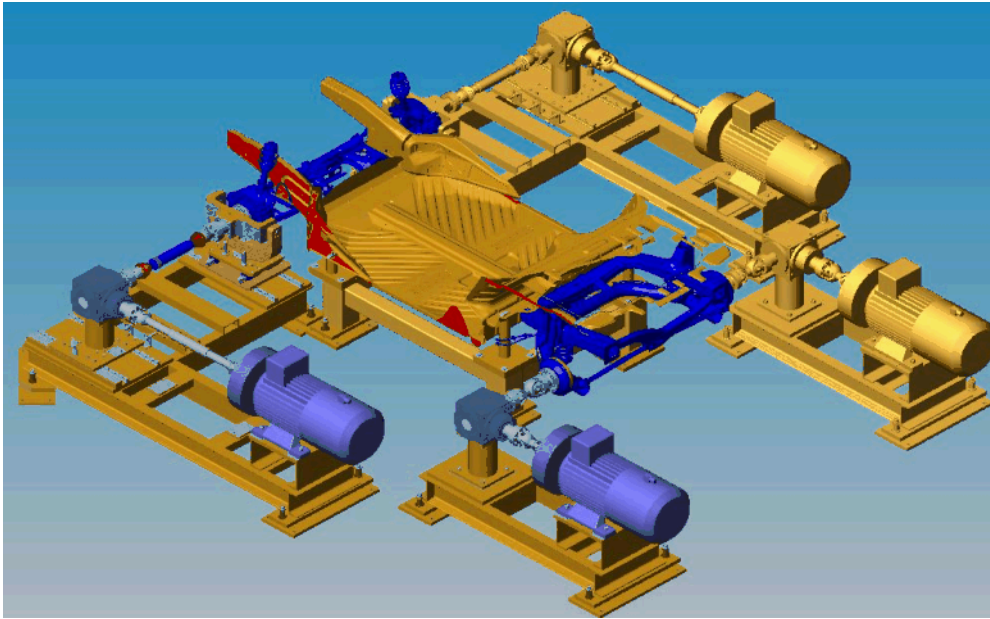
Provision of traffic scenarios and  
environment simulation





# Partners (3)

Dürr, Assembly Products GmbH, Püttlingen, Germany



**x-dynodrive testbench**

drivetrain testbench adaption  
provision of realtime behaviour

**Hall 1, Booth 1850**



# CRUSADER

## Summary Main Use Cases, only a snapshot.....

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### ▶ vehicle dynamics

- ▶ optimization of transmission- and engine control for different driving scenarios
- ▶ test different types of vehicles by changing the models or the simulation parameters

### ▶ hybrid drivetrains

- ▶ verify energy- and loadmanagement
- ▶ repetition of reference traffic scenarios to validate different hybrid approaches/drivetrains

### ▶ assisting systems

- ▶ simulate object data and verify the vehicle behaviour of new assisting functionalities
- ▶ usability studies of assisting functionalities, e.g. HMI design

### ▶ commonly

- ▶ closed loop control makes it possible to run fully automated test cases (without driver)
- ▶ fault insertion for power- and signal lines



# CRUSADER

## Summary Business Case

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- ▶ Realization of a complete vehicle system test bench which will be completed with an environment- and traffic simulation
- ▶ based on new modular deployment which represents a grouping of functionalities
- ▶ one single test bench for every module (driver workplace, drivetrain bench,...), to be connected together as a complete test system or can be operated as single-user testbench too



**Reduction of integration effort by testing with CRUSADER**



**Satisfying our customers !**

# CRUSADER

A Complete Vehicle Integration Facility

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## CRUSADER

a broad range of system testing !

Thank you for your attention.