



David Bailey, ETAS GmbH

Test And Validation: Coping With Complexity

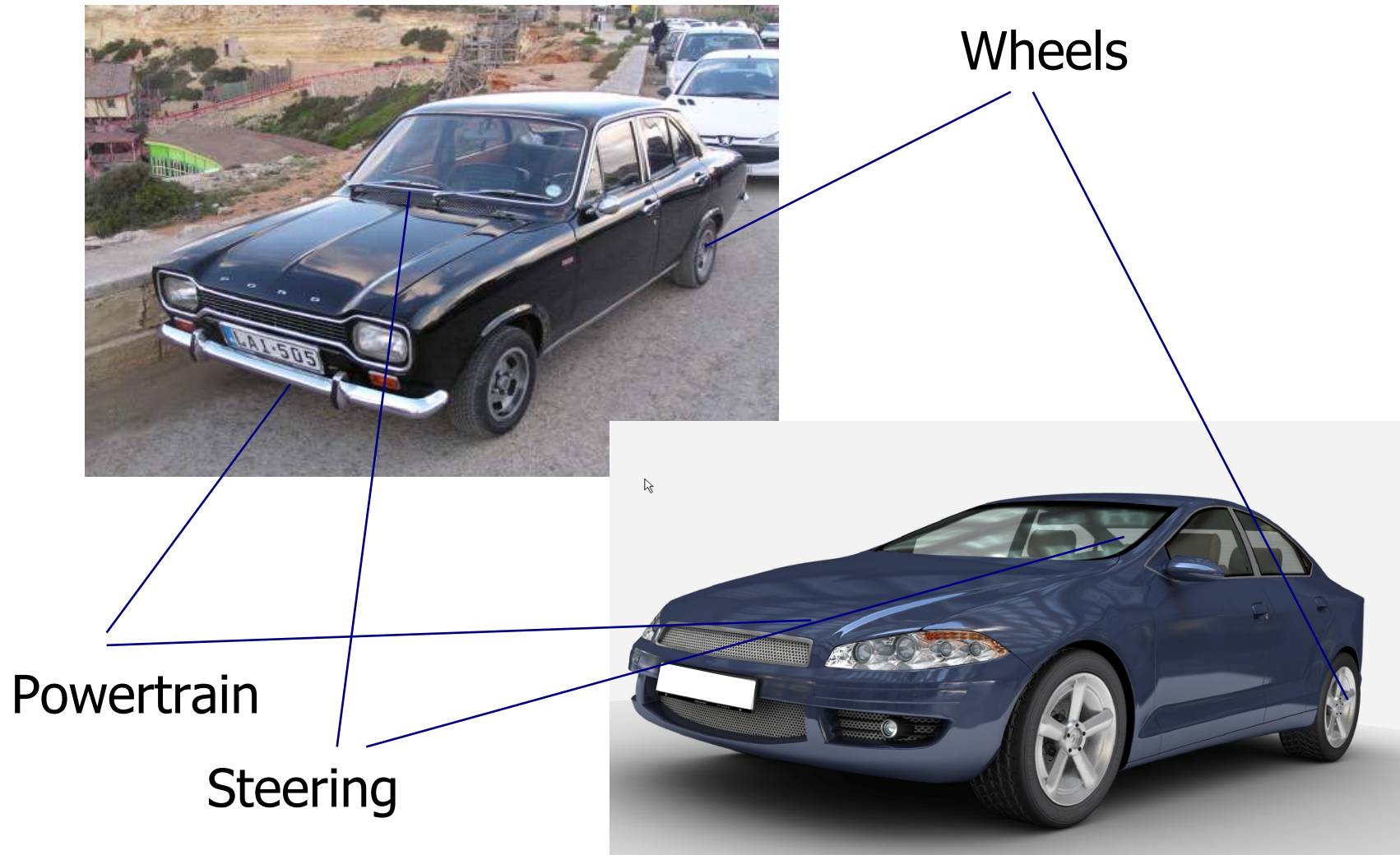
The state of play in vehicle software and system validation

Agenda

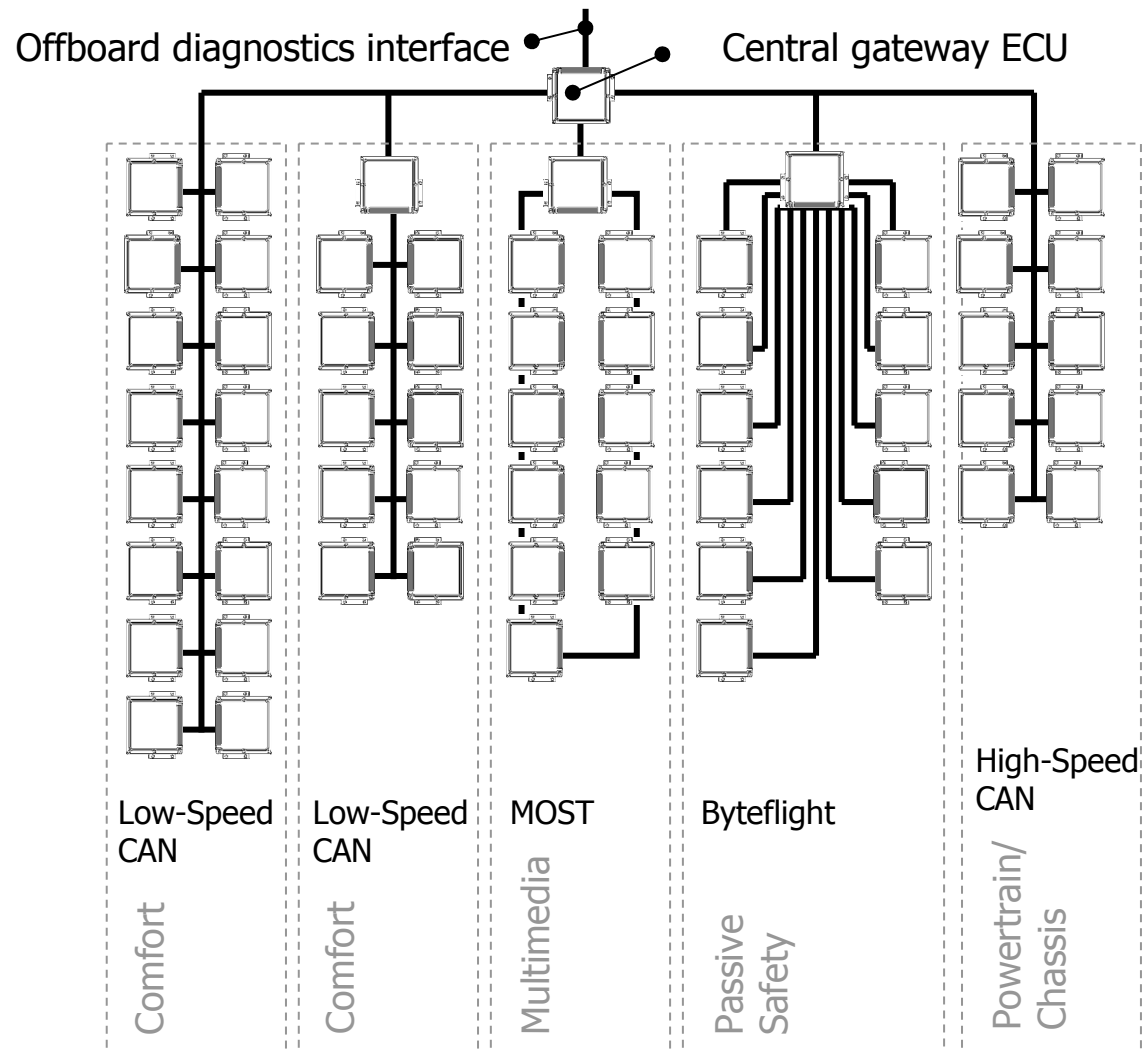
- Test & Validation – How far have we come?
- What is driving complexity ?
- How can demands for greater complexity & reliability be reconciled?

Cars: From Yesterday to Today

Form & Function versus Content

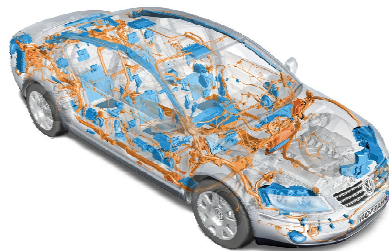


Today – Example: BMW series (E65)



- Over 65 networked ECUs
- 4 bus-systems
- ~ 116 MB code
- up to 900 functions

The drivers of Complexity



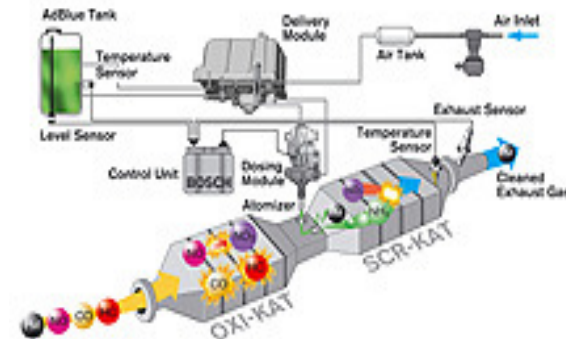
Warranty costs



Ever tighter emissions with safety regulations coming soon!

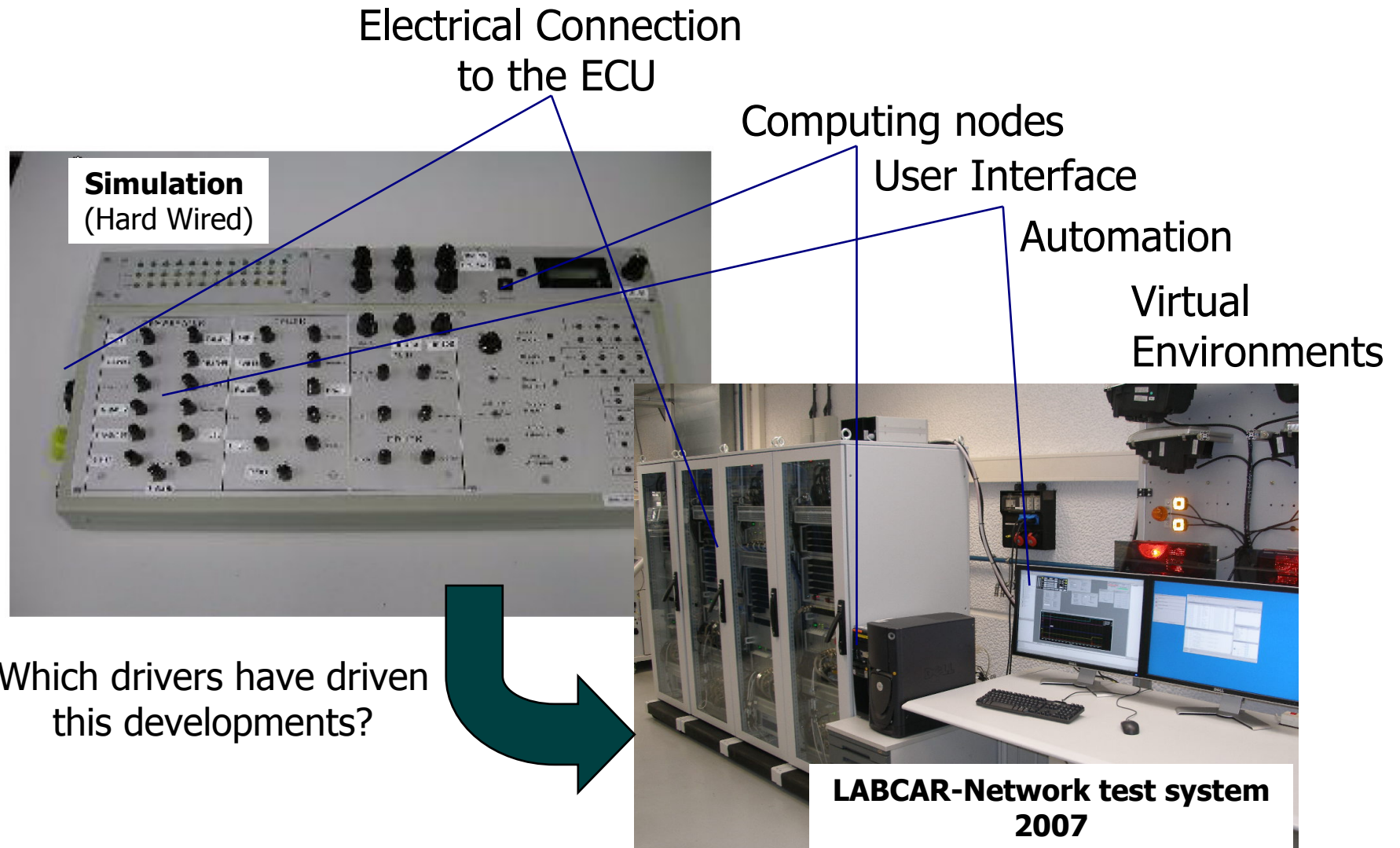


Increasing number of variants per platform

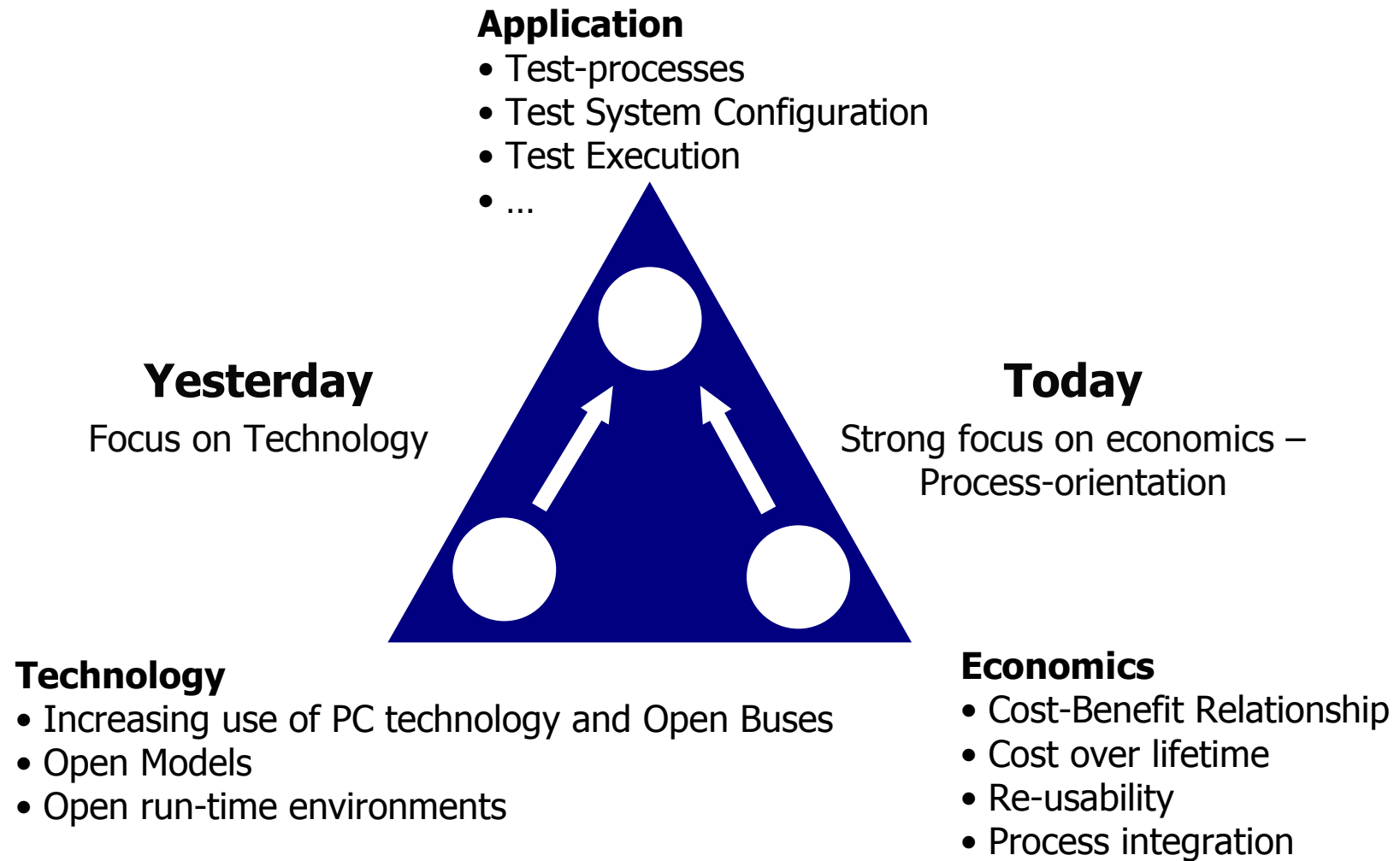


Increasingly complex sub-systems

Test Systems: From Yesterday to Today



Drivers in 3 Dimensions



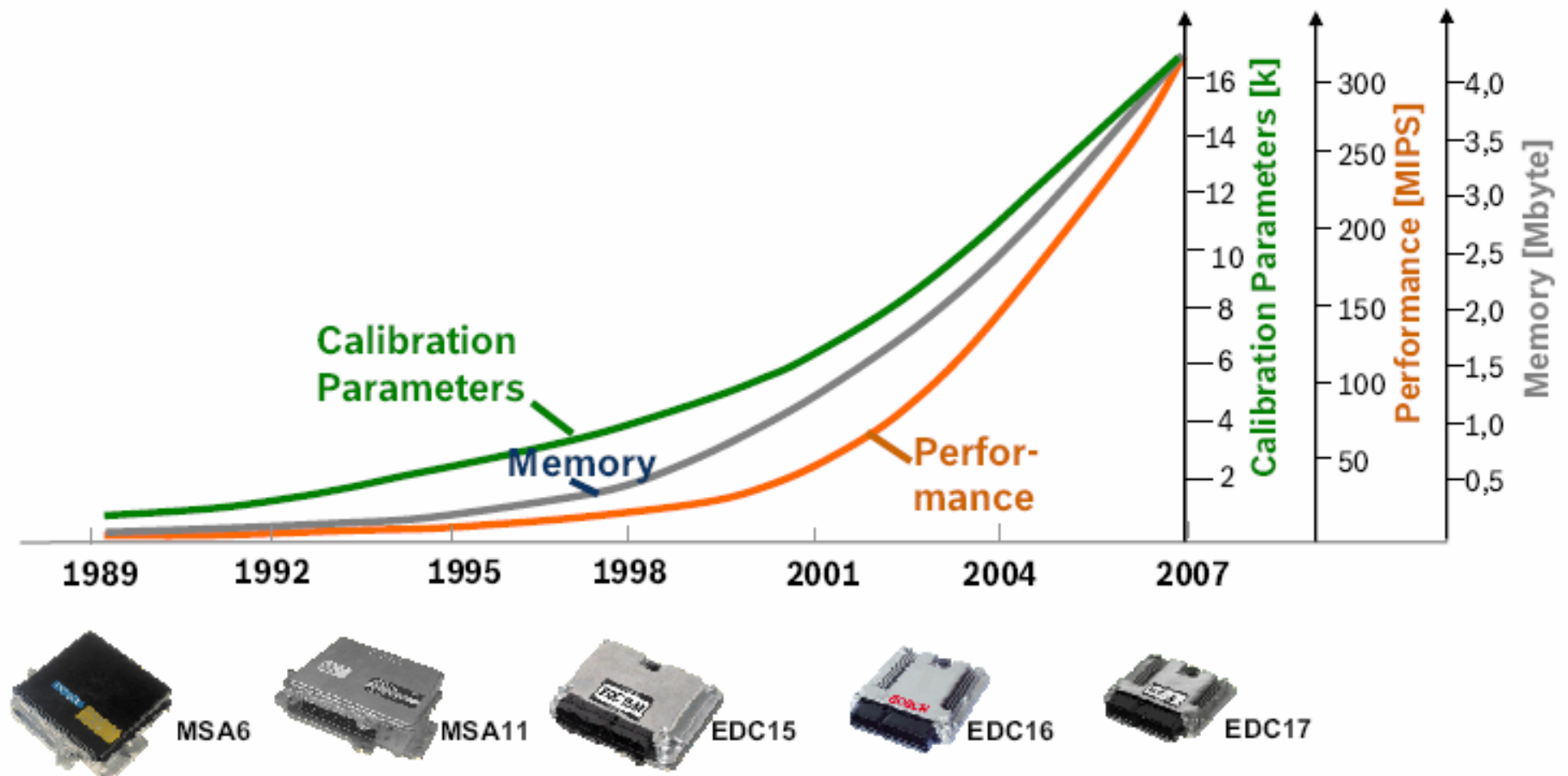
Test & Validation: from Yesterday to Today

Trends and consequences



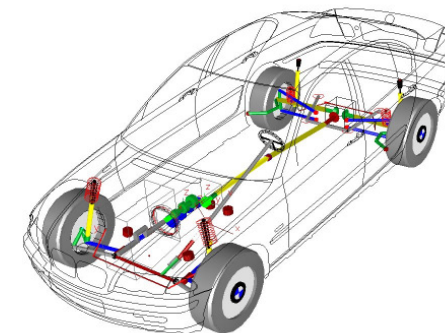
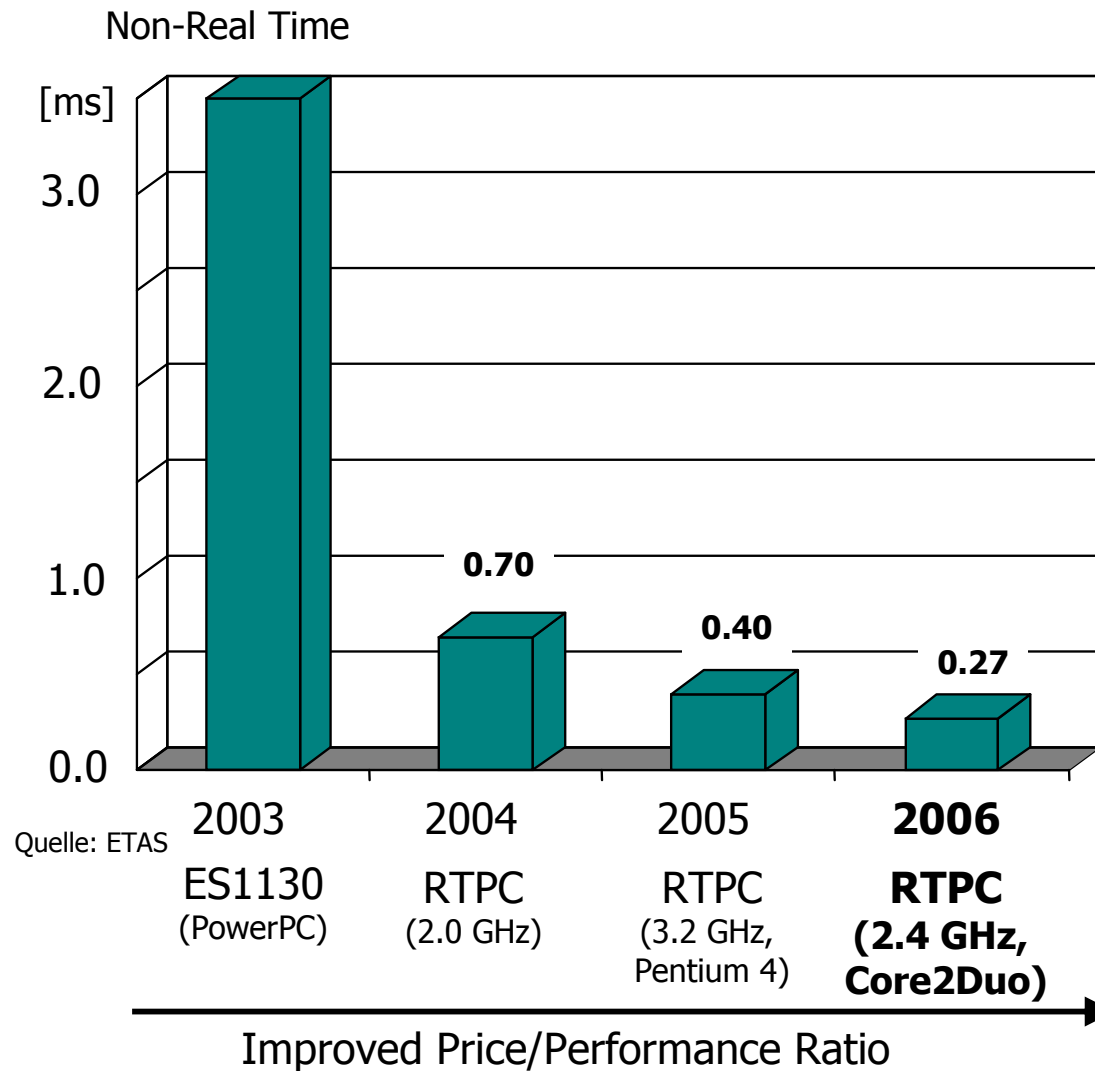
Trends		Yesterday	Today
↑ Increasing ECU functionality (Quantitive & Qualitative)		<ul style="list-style-type: none"> • Manual Testing • Simple Models • Slow real-time micros 	<ul style="list-style-type: none"> • Automated Testing • Complex Models • Fast real-time micros
↑ Increasing Networking (Quantitive & Qualitative)			
↓ Sinkendes Budget			

Complexity growth (Diesel Systems)



Source: Bosch Diesel Systems 2007; DS/PJ-EER; EEH0 07 024

Increasing ECU functionality: Fast real-time μ s replace slow ones



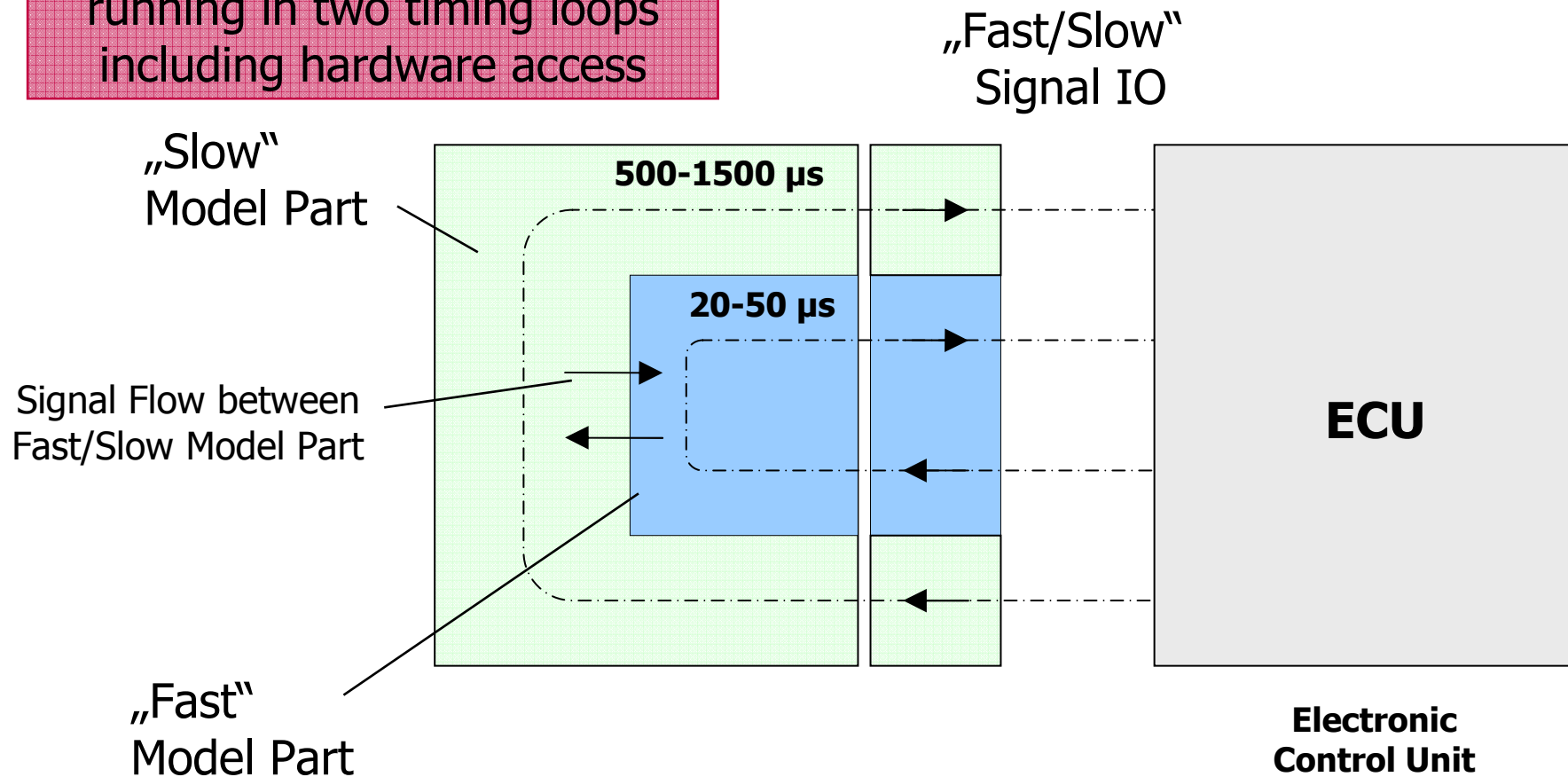
- **Calculation time [ms]**
- Euler-integrations
 - Vehicle Dynamic Model
LABCAR-VDYM V5.0
 - Excludes I/O turnaround

Multi-Core Processors – “Triggered Sub-Systems”

Benefits of multi-core processors in model execution



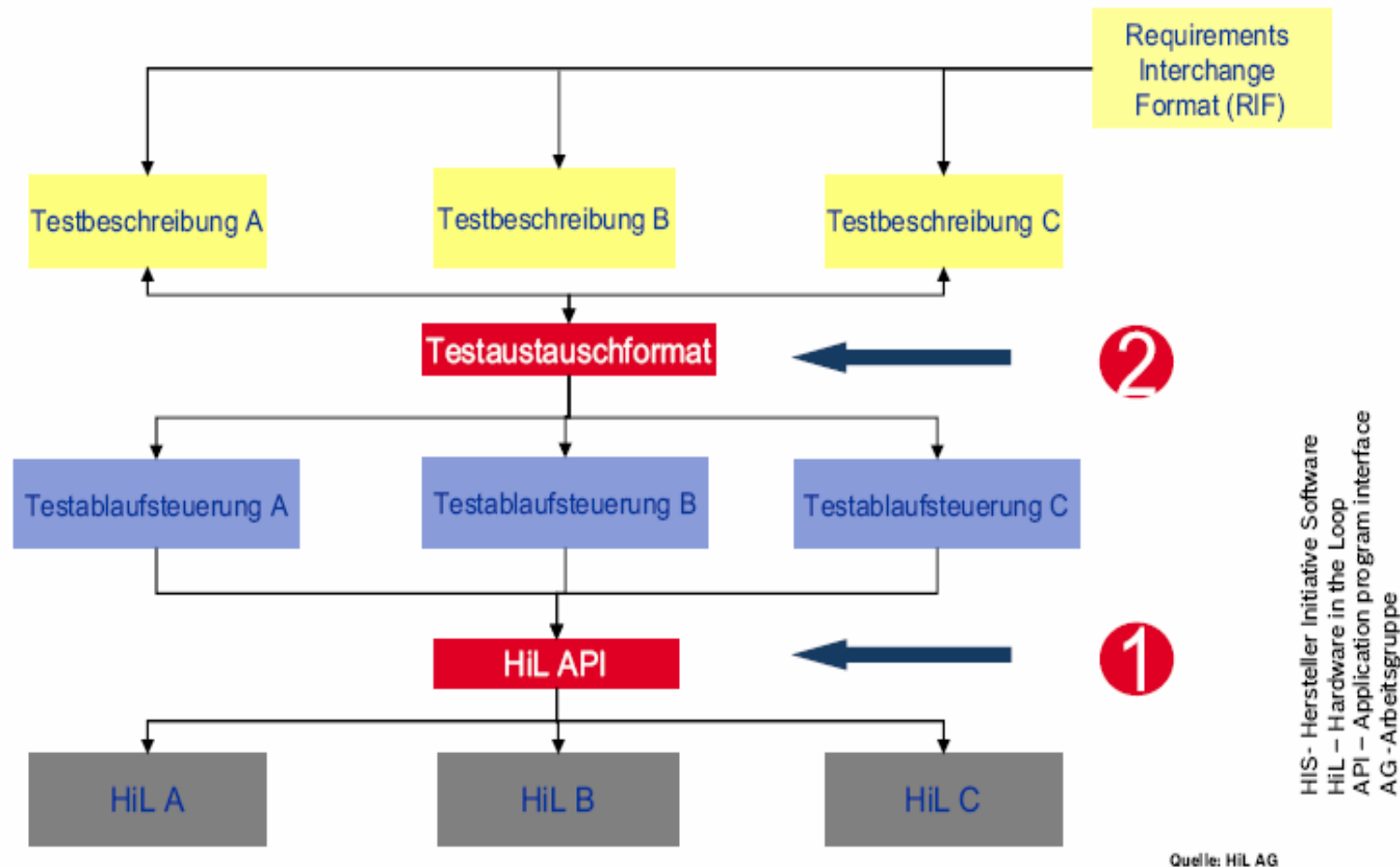
Real-time model
running in two timing loops
including hardware access



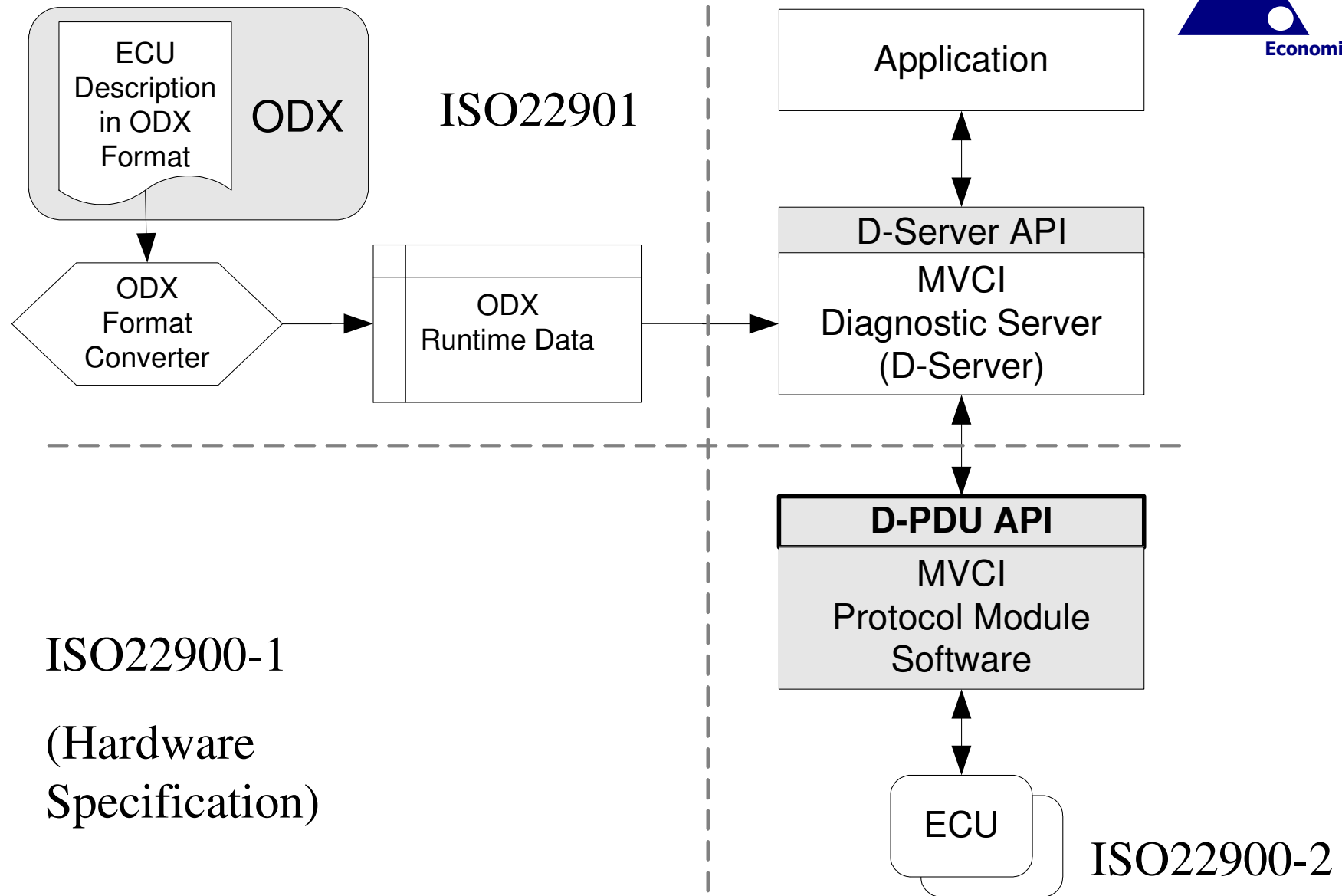
TASK: Increase test cost & coverage with lower budgets

Requirement	Advantages & Characteristics
Test Stand Independence	<ul style="list-style-type: none">➤ Guaranteed re-usability of test-cases between projects, systems, versions and variants➤ Protection of Intellectual Property➤ Reduction of implementation effort (once, for ever)
Independence from Development language	<ul style="list-style-type: none">➤ Reduction of learning effort➤ Re-usable development environment
Parametrised (logical) test cases	<ul style="list-style-type: none">➤ Simple but powerful adaptations possible for specific test applications➤ Limiting the development effort "one test-case per specification"➤ Lower the administration effort
Test Project Management	<ul style="list-style-type: none">➤ Management of different combinations of test cases with parameter-sets with minimal effort
Integration in Test-processes	<ul style="list-style-type: none">➤ Increase Transparency & Traceability➤ Open interfaces (eg to requirements management tools (Doors, SVN...))➤ Dedicated roles <p>(There is no universal test-environment!)</p>

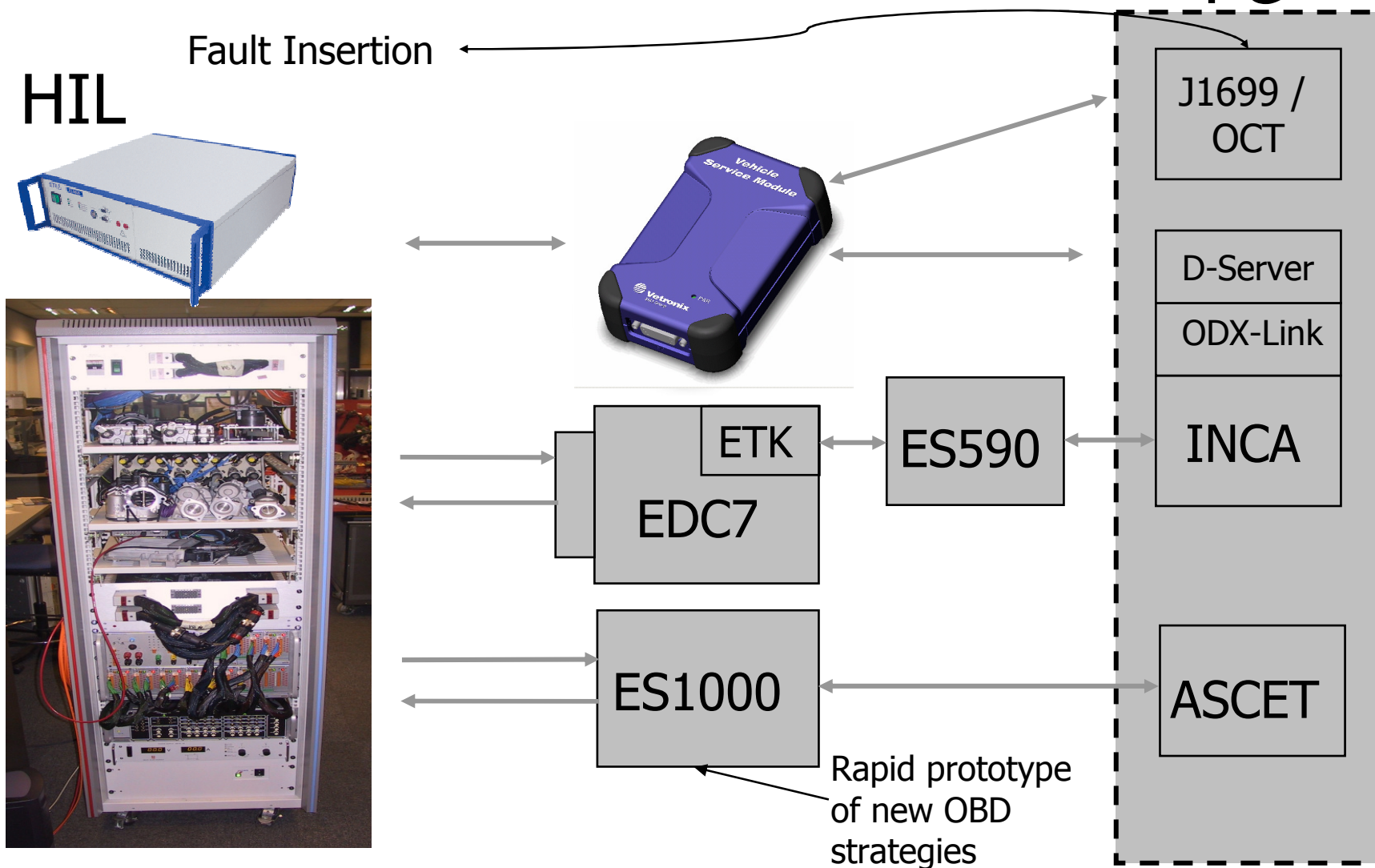
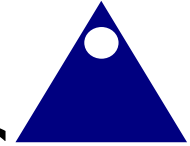
HiL AG: Harmonisierung von Schnittstellen



Industry Standardization



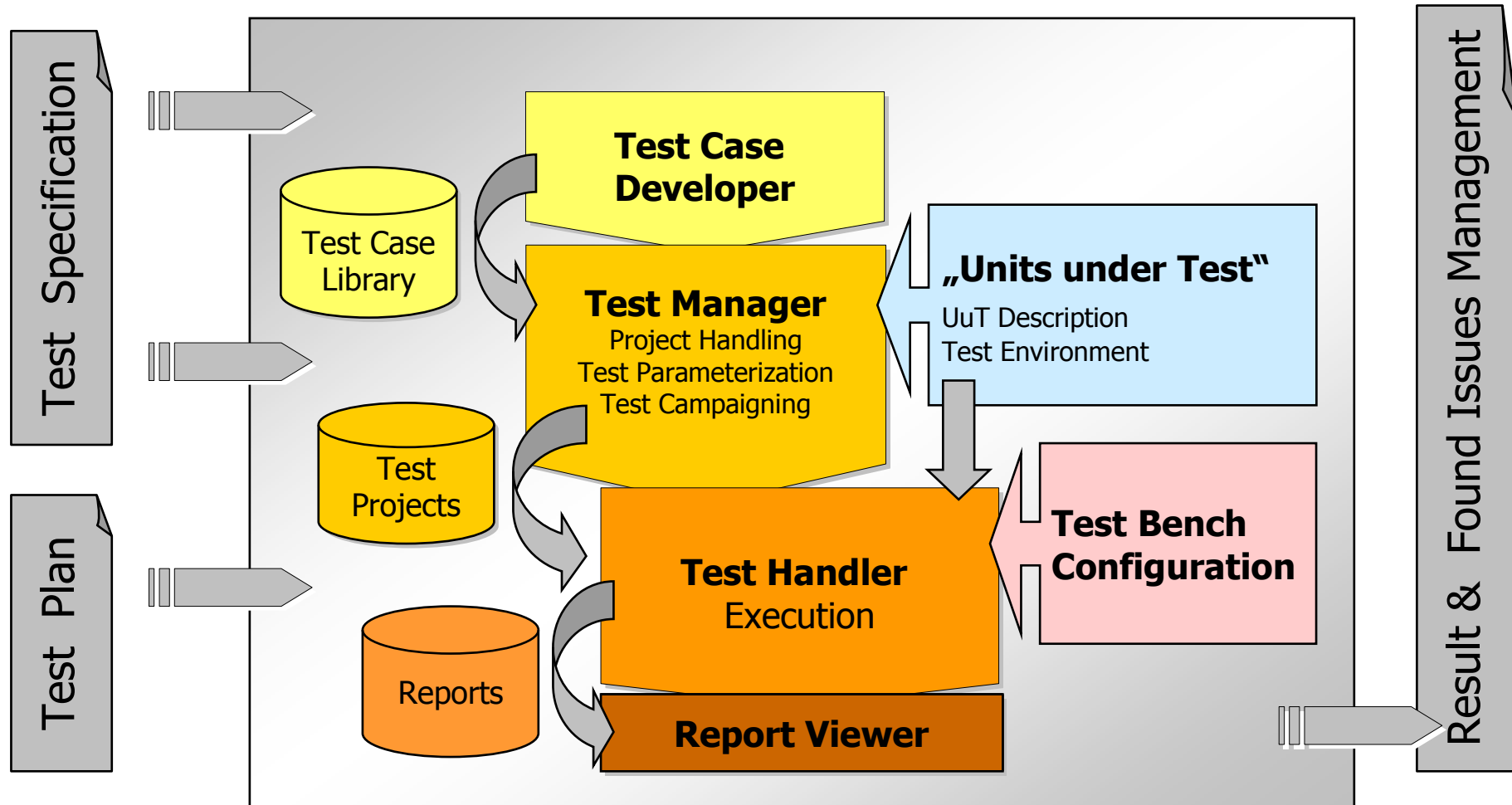
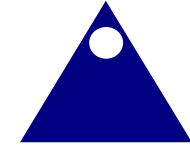
Example Test Environment for OBD Development & Validation

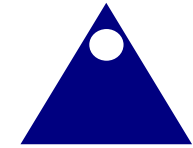


Description and allocation of roles

Test automation completes or replaces manual testing

Application





Requirements of the Test Developer

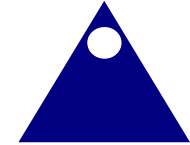
There is no universal test language!

Language Type	Example	Comment
Test – oriented	TTCN-3	<ul style="list-style-type: none"> ➤ Rather complex ➤ Has specific Test constructs (e.g. “Verdicts”) ➤ Small and specialized user circle
Script	Python, Perl, m	<ul style="list-style-type: none"> ➤ Little learning effort ➤ Limited Process security (no compiled test-cases) ➤ Normally not “strong typed” (a big problem for operational consistency)
Graphical	Simulink, UML tools, NI TestStand	<ul style="list-style-type: none"> ➤ User friendly with guided operations ➤ Guaranteed syntactical correctness ➤ Sub-optimal for sequential test architectures ➤ Possible loss of oversight with big projects ➤ Lack of transparency
Software Development	C#, VB, C++	<ul style="list-style-type: none"> ➤ Very powerful development environment (also low cost) ➤ Large user group ➤ Higher learning effort ➤ No specific Test Constructs (e.g. verdicts)

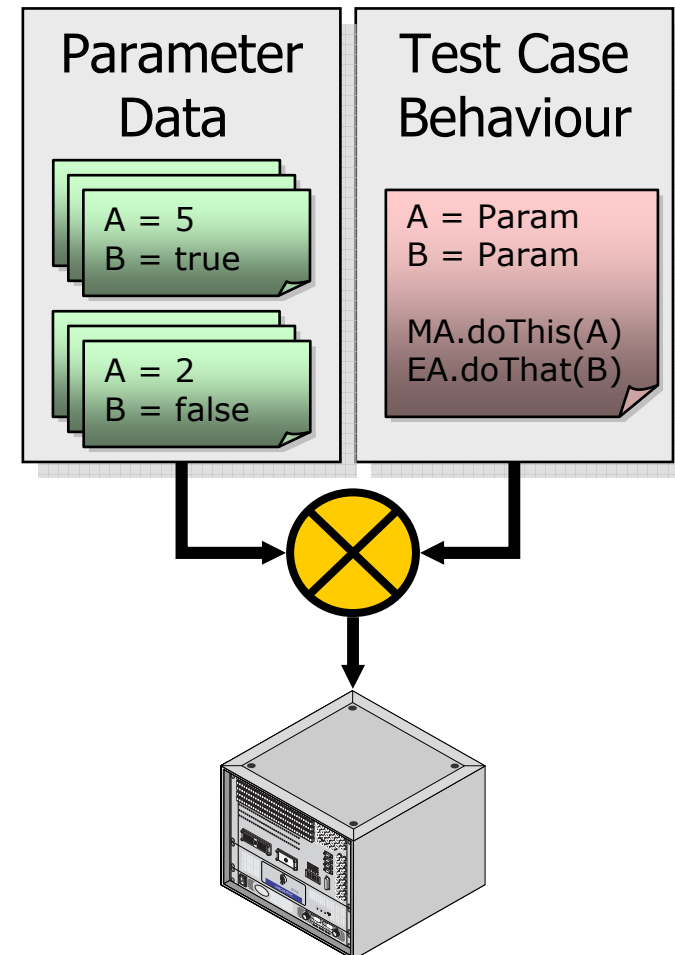
Example: Test Parameterization

Fundamental for re-usability

Application

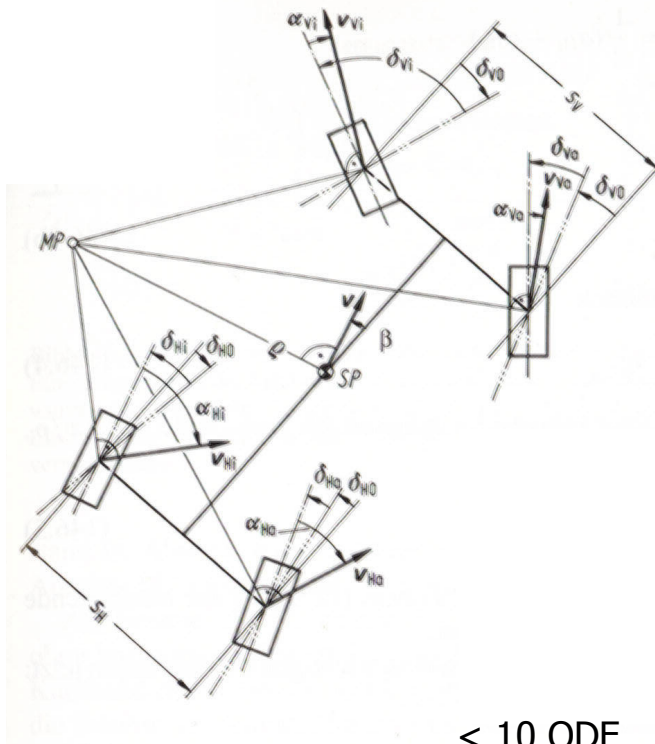


Use of the parameter	Description
Adaptation of Test Systems	Data for specific Test-system configurations, time-outs & tool options.
Setting and definition of the working point of the tests	Environmental Data, Fine-tuning of the plant-models to the test conditions (i.e. dependent on the Unit under Test)
Setting the Test-points and Test -vectors	Describing the Test scenario. (e.g, arc diameter, entrance speed, exist speed, braking force... for ESP test)
Settings for Evaluation Method	e.g. Selection of method and definition of pass/fail thresholds



Increasing ECU functionality

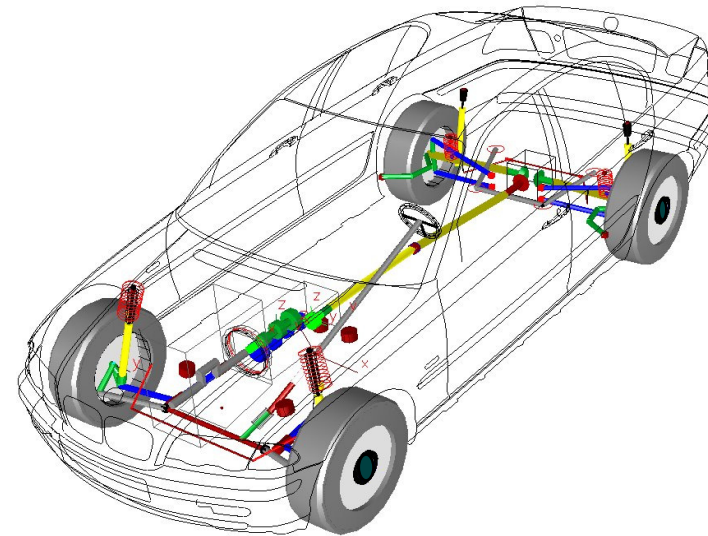
Complex Real-Time models replace simple RT models



< 10 ODE

Yesterday: Simple two-track model
for Vehicle Dynamics

(Source: Dynamik der Kraftfahrzeuge, Mitschke)



< 150 ODE

Today: Complex MBS-vehicle dynamics
model with Axel-geometry

(Source: INTEC, LABCAR-VDYM V5.0)

ODE = Ordinary Differential Equations, **MBS** = Multi-body simulation

Model Optimization using both physical & statistical, data driven methods (*e.g. TLRNNs, SOM/TFA/LLM*)

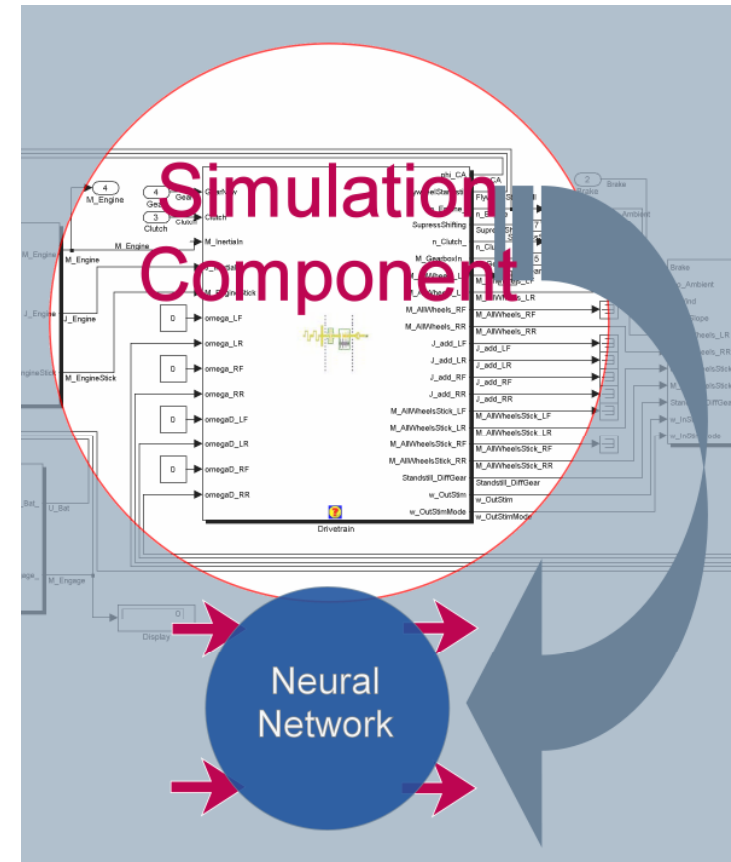


The Problem

- There is a break in the tool-chain between CAE tools used for basic powertrain design and plant models used for controls development
- How to assess design impact on emissions?
- How can complex models still run in real time?

Solutions

- Complex „logical“ optimization of the physical model (*eg: WAVE RT von Ricardo*)
- Statistical Modelling Tools (*Gamma Technologies, The Mathworks*)
- Engineering solutions.



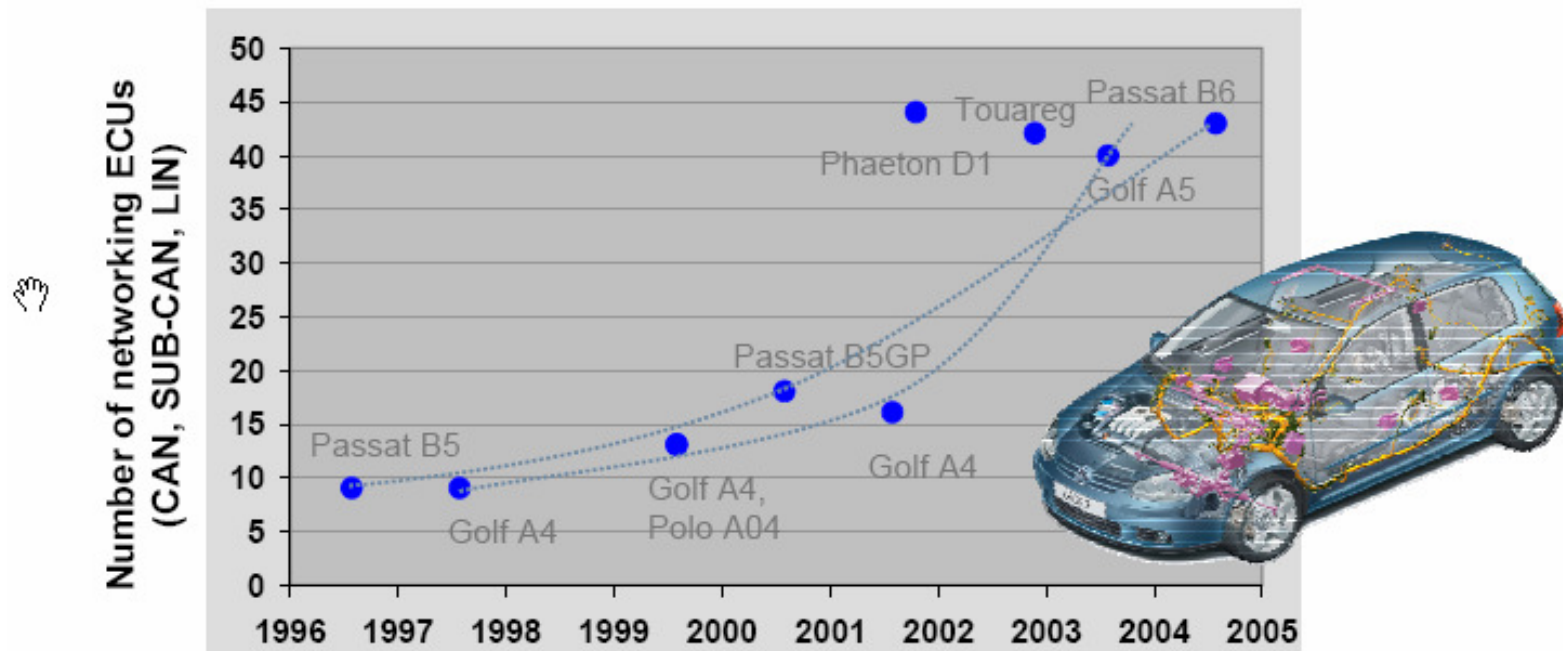
HiL-Simulation: from Yesterday to Today

Trends and consequences



Trends		Yesterday	Today
↑ Increasing ECU functionality (Quantitive & Qualitative)			
↑ Increasing Networking (Quantitive & Qualitative)		<ul style="list-style-type: none"> • Single HiL Systems • Slow Bus-systems • Sequential Development process 	<ul style="list-style-type: none"> • Networked HiL Systems • Fast Bus-Systems • Iterative Development Process
↓ Sinking Budget Budget			

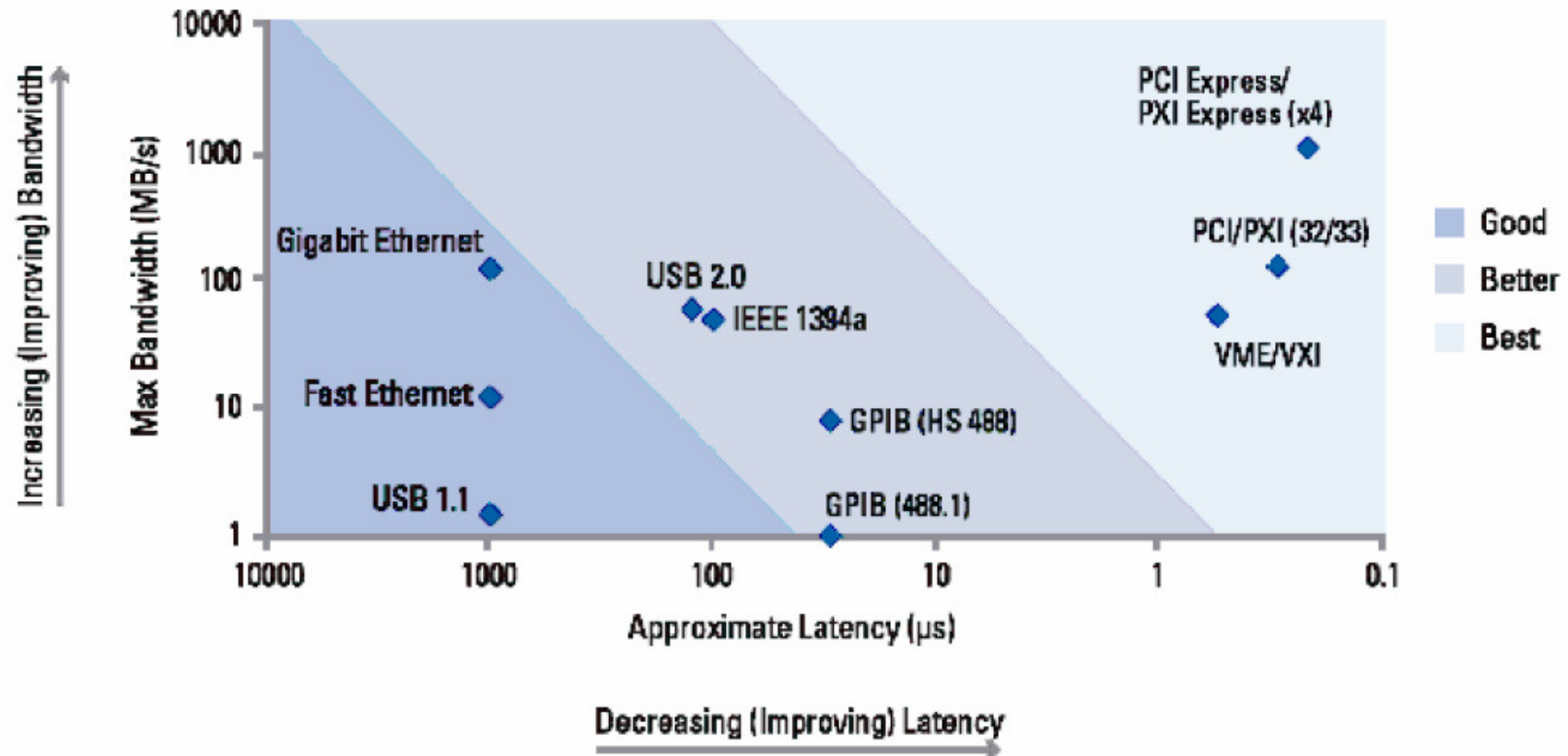
Increasing Networking Indicators



Quelle: Volkswagen AG (Grafik)

Increased Networking – HiL- & PC worlds

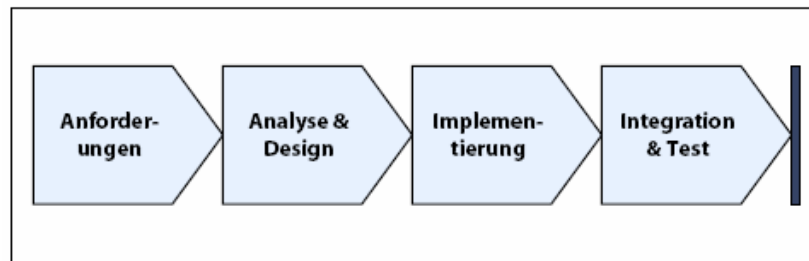
Fast bus systems replace slow ones



Quelle: www.ni.com, National Instruments
White Paper - Bus Performance.pdf

Increasing Networking

Iterative Processes replace Sequential ones

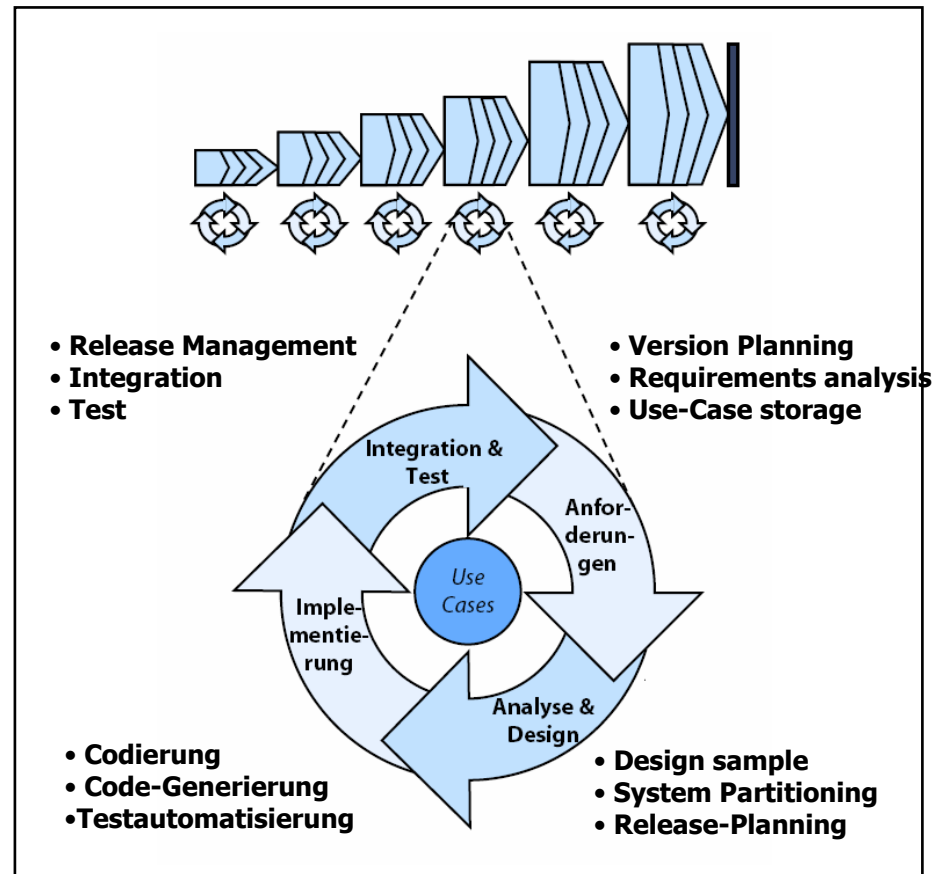


Quelle: www.basycon.com
POSTER_SW-Qual_EntwProz.pdf

**Vehicle Development is
,largely` software
development**

**→ The Development process
should adapt accordingly**

Yesterday: Sequential Development Proces



Today: Iterative Development process.
Increasing coherence MiL-SiL-HiL

HiL-Simulation: From Yesterday to Today

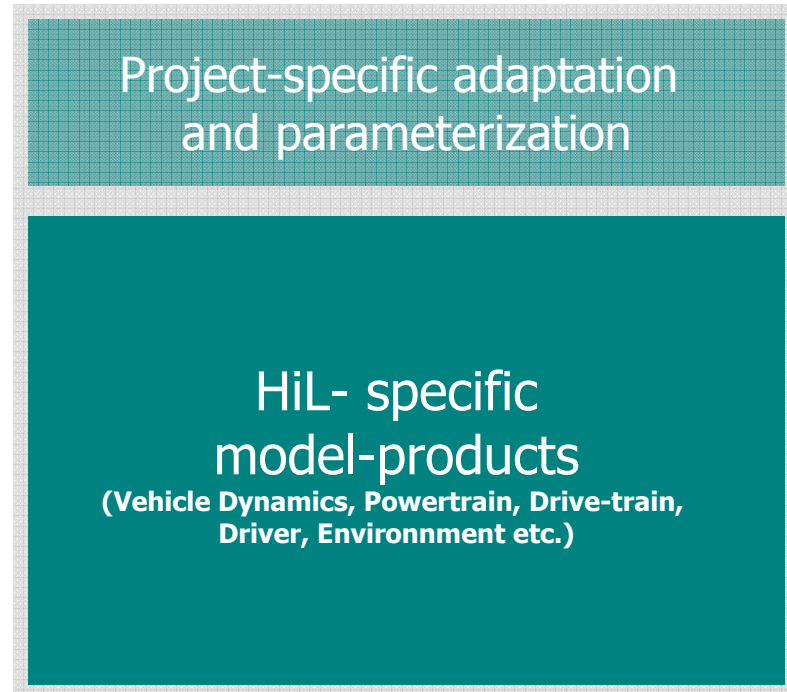
Trends & Consequences



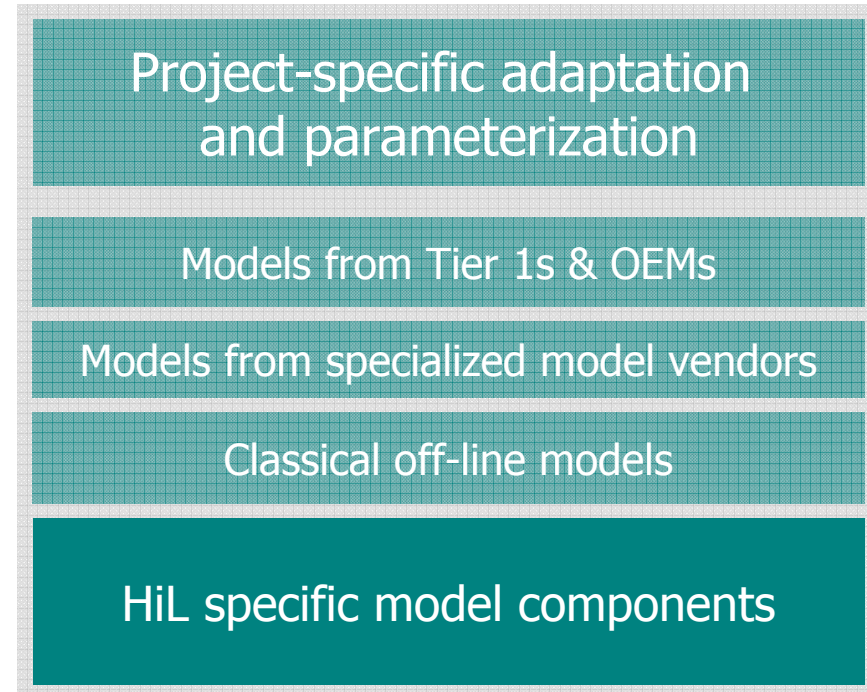
Trends		Yesterday	Today
↑ Increasing ECU functionality (Quantitive & Qualitative)			
↑ Increasing Networking (Quantitive & Qualitative)			
↓ Sinking Budget Budget		<ul style="list-style-type: none"> • System-based service • Proprietary models • Technology-driven product solution 	<ul style="list-style-type: none"> • Solution-based service • Open models • Application driven Pproducts • Re-usable test-cases • Outsourcing of test activity

Sinking Budget, rising requirements

Open model solutions integrate with complex models



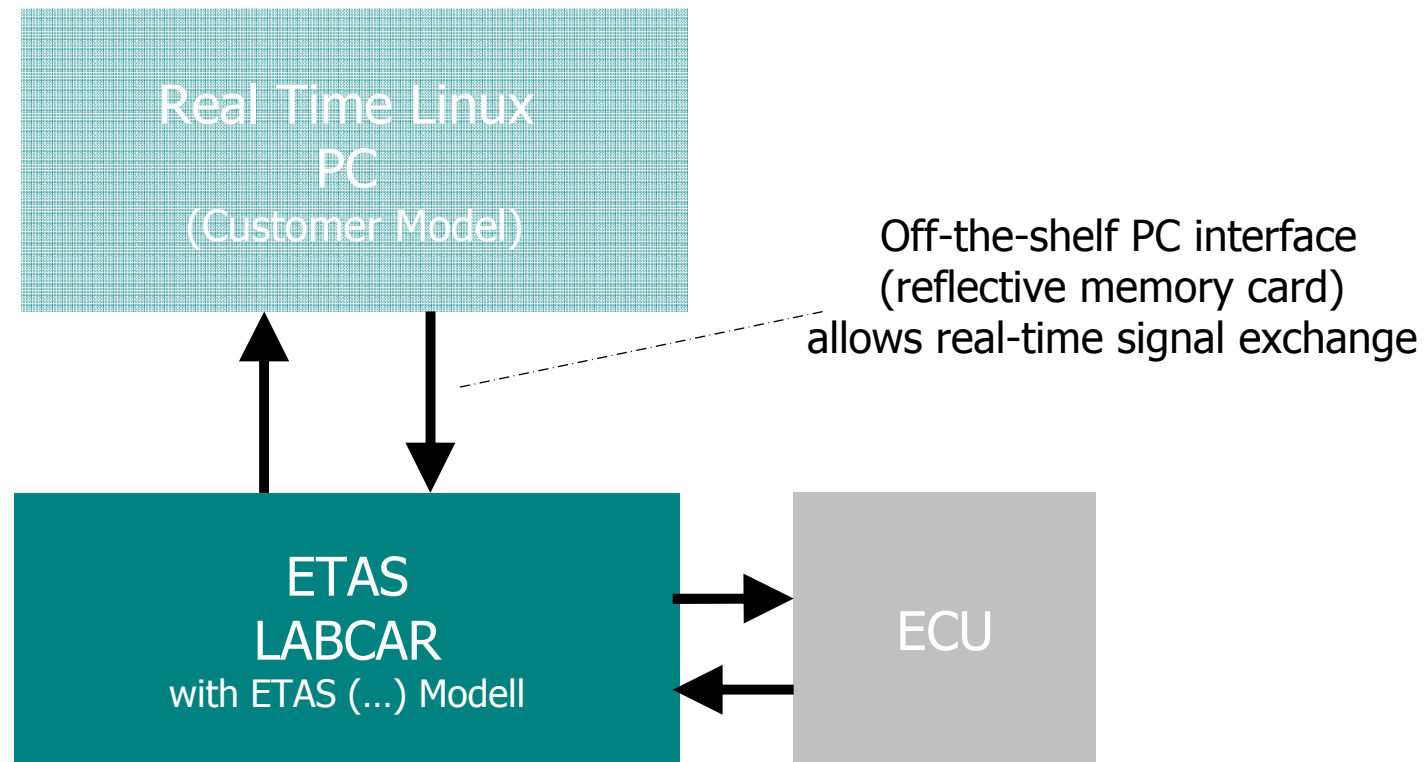
Yesterday: HiL-specific real-time models



Today: HiL specific models extended with a variety of specialized models from different sources

Sinking Budget – Rising Requirements




Open integration example



Sinking Budget

Application-driven solutions replace technology-driven ones






		Power-Train	Chassis	Body	Others...
	<ul style="list-style-type: none"> High-End HiL-System 				
	<ul style="list-style-type: none"> Standard HiL-System 	Yesterday: Technology Driven (z.B. ETAS VME-LABCAR)			
	<ul style="list-style-type: none"> Basic HiL-System 				

Sinking Budget

Application-driven solutions replace technology-driven ones



		Power-Train	Chassis	Body	Others...
	<ul style="list-style-type: none"> High-End HiL-System 	Today Application Driven e.g. ETAS PT-LABCAR			
	<ul style="list-style-type: none"> Standard HiL-System 				
	<ul style="list-style-type: none"> Basic HiL-System 				

What will the future bring?



- **Application**

- New Applications

Increasingly „virtual“ testing
Reusability & Interoperability
Common Test Environments
deployed at new stages of
development

- Standardization

Test languages, Tool APIs

- Automation

Increasing Test Automation, also
other development processes
automation (e.g. calibration)

What will the future bring?



- **Technology**

- Increasing Processing Power

DualCore, QuadCore, ...

- Faster PC Buses

PCI-Express, US

- Virtualization

Increasingly high fidelity, real-time capable models

Increasing model Types (e.g. Processor, ECU models, network models)

What will the future bring?

- **Economics**

- Further Efficiency Drives
- Further Cost Pressure
- Outsourcing
- Standardization

24/7 „Test Houses“

Road → to Lab → to Math

Reducing costs but driving requirement for MUCH improved process security

Further industry wide standardization moves
Increased utilization of de facto standard technology (PC, .NET...)



Thanks for your attention!



David Bailey
Business Development Manager – ETAS GmbH
+49 711 89661 371
David.bailey@etas.com
www.etas.com

David is responsible for business development at ETAS for Test & Validation solutions. He has been working at ETAS for 4 years. Previously David has worked for Dearborn Group Inc where aside from business management in Europe he participated in a number of standardisation committees related to vehicle bus protocols & ECU reprogramming.